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Vacuum Science and Technology for Accelerator Vacuum Systems

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# Table of Contents

- Vacuum Fundamentals
- Vacuum Instrumentation
- Vacuum Pumps
- Vacuum Components/Hardware
- Vacuum Systems Engineering
- Accelerator Vacuum Considerations, etc.



- Make up for transverse offsets in beamline hardware, and minor misalignments
- Provide installation personnel with sufficient flexibility to install hardware.
- □ *Reduce stresses on adjacent vacuum joints.*
- Provide adequate expansion and/or contraction ability during thermal cycles.
- Provide required movements for functioning instruments, such as beam profile viewers.

3



# Bellows – Key Parameters



- Bellows free length
- Bellows maximum extended length
- Bellows minimum compressed length
- Bellows maximum transverse offset
- Maximum number of cycles
- Bellows end configurations





# Types of Flexible Bellows



#### Edge-Welded

- Very flexible, both axial and transverse
- Very long stroke available
- Non-circular cross section available
- User-configurable, from most vendors
- Higher cost
- Need mechanical and corrosion protections





#### Hydro-formed

- More robust, comparing to welded
- Lower cost
- Usually good transverse flexibility
- Not good for long stroke application





# RF-Shielded Sliding Joint in CESR





In storage rings (or accelerators with intense short bunched beams), bellows MUST be shielded from the beam. Otherwise, wake-field will be excited in the cavities to:

- $\rightarrow$  Cause damage to the bellows
- $\rightarrow$  Induce negative effects to the beam.



### Sliding Joint in CESR – Parts



#### ~120 used in CESR, each provide 1.75" Stroke

Two sliding oval-shaped tubes, made of 6061-T6 aluminum, and Be-Cu RF fingers. One with hard coating, one with silver coating.





Friction bonded pans enable transitions between aluminum to stainless steel bellows







# Sliding Joint in CESR – RF Heating

- CESR sliding joint was designed more than 30 years ago.
- Though with the RF-contact shielding the bellows, the steps in the CESR sliding joints forms a RF cavities.
- We have observed resonant RF excitation in the cavities, and cause significant heating some particular opening.
- Most modern designs of RFshielded bellows have much smoother transitions, to reduce RF-impedance.







## RF-Shielded Sliding Joint of PEP II







RF-Shielded Sliding Joint of KEK Style













#### **RF-Shielded Beam Viewer for Cornell ERL**





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11







- All-metal Gate Valves
- · All-metal Angle Valves
- · RF All-metal Gate Valves
- Fast Closing Valves









- 3 leaf springs
- 4 ball pairs
- 5 detents
- 6 gate seal
- 7 spring stop

 All-metal UHV values only available from VAT Values
ID from 35-mm to 320-mm



- Gate values with metal bonnet seals and elastomer flap seals are more available.
- For general UHV system, this is an low-cost alternative.
- > ID from 35-mm to 320-mm





## RF Shielded All-metal Gate Valves



- > Used as sectoring vacuum sections in large accelerator vacuum system.
- > Pneumatic actuated, allowing vacuum system interlocking.
- > 316L stainless steel body with elastically deformed metal seals
- > RF trailer deploys at open position.
- > Max. operating temperature 200°C
- Bellows sealed, allowing 100,000 cycles









## Fast Close and Beam Stop Valves





- Closing time: < 10-ms after trigger</p>
- Usually used on X-ray beamlines
- Need reliable and fast vacuum gauges at engineered distance from the valve, to provide sensible valve closing trigger.
- > Most firings are false trigging !!

#### Beam Stop for X-ray beamlines



 P<sub>max</sub>: 5 kW
Max. Power density: 25 W/mm<sup>2</sup>



1. Body; 2. Copper Plate 3. bellows; 4. Water cooling











# All-metal Angle Valves





 All-metal Easy-Close angle valves, no torque wrench needed.
Best in dust-free environment





- All-metal angle valves with copper gasket seals. More robust.
- More sealing cycles with increasing torque



Used for roughing, purging and venting vacuum systems





# Variable Leak Valves

- A variable leak value is used for vacuum equipment that need to control the amount of gas introduction.
- It enables the gas introduction of remarkably small amount; minimum controllable leakage is less than 1×10<sup>-9</sup> torr·L/sec.
- Additionally, it is all-metal and can be baked up to 450°C, making it ideal for ultra-high vacuum equipment.
- The seal surface is fragile, so one must NOT close the valve too fast.







# Electrical Feedthroughs





- Coaxial •
- Power •
- High Current •
- High Voltage •
- Breaks •
- · RF Power







# Instrumentation Feedthroughs



#### Multi-pin feedthroughs





Sub-D feedthroughs



Thermocouple feedthroughs







## Linear Motion & Multi-motion Feedthroughs



- The class of feedthroughs span from simple "pushpull" to precision units.
- Manual, motorized, and pneumatic action.
- UHV compatible

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- Linear travel ranges from  $\frac{1}{2}$ " to 6"
- Magnetic coupled translator for over 48" travel
- Multi-axis stages







Rotary Motion Feedthroughs



- Manual or motorized actuation.
- · UHV compatible
  - Torque to 50 oz-in
  - Speeds to 50 rpm







Magnetic Coupled

Bellows Coupled ("Cat's Tail")





## Pumping Ports for Beampipes



These components must maximize conductance to the pump, while minimizing detrimental effects on the beam.

- To connect the beam space to the vacuum pumps, opening have to be made between the beampipe wall and the pump port.
- The most common openings are in the form of slots along the beam direction, as illustrated here.
- Beam bunches passing by the slots radiates RF power, contributing RF impedances.
- The losses from the pumping slots should be checked to within the allowed impedance 'budget'.







For a single slot on a round beam pipe, the loss factor (in unit of V/pC) is:

$$k = 1.24 \times 10^{-3} \frac{n_b}{\sigma_b^5} \cdot \frac{l_{slot}^2 \cdot w_{slot}^4}{r_{pipe}^2}$$

- *n<sub>b</sub>* is the number of bunches
- $\sigma_b$  is the beam bunch length in mm
- I<sub>slot</sub> and w<sub>slot</sub> are the length and width in mm of the slot, respectively,
- *r*<sub>pipe</sub> is the inner radius of the beam pipe
- RF loss at a lost is severer for very short bunches
- Long, narrow slots are the better 'compromise' between RF loss and gas conductance



Spreadsheet

## PEP-II Pump Tee







# RF 'Cavities' in Flange Joints



- Making beamline flange joints using regular Cu gaskets may form RF cavities, particularly when the beam aperture differs significantly from the flange cross shape.
- Measures must be taken to bridge the gap to form a smooth bore beamline.
- □ Some of the methods are:
  - ✓ *RF insert with spring fingers*
  - ✓ Gap rings
  - ✓ Zero-gap gaskets, similar to VATSEALs





### RF Insert at Flange Joints









## 'Gap Ring' at Flange Joints







# Flange design with minimized 'cavity'









## Zero-Impedance Flange Joints





Face-Seal Copper Gaskets used in KEK SuperB Taper-Seal Aluminum gaskets Used at SC-cavities at Cornell



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30



# Ceramic Beampipes



- Almost all storage rings have ceramic beampipes, as parts of fast magnets for beam injection and feedback control systems.
- The ceramic body usually made of alumina, and jointed to metal flanges via vacuum braze. A strong-back structure is normally used to support the ceramics.
- Thin metallic coating is deposited on the inner surface of the ceramics, to provide conductive pass for image current. The coating is usually slightly thicker than the corresponding skin-depth, but thin enough to allow external field penetrate through.



A CESR ceramic pipe mounted on strong-back frame, with flexible ends





31

## A Typical X-Ray Beamline Front-End











- 1. Crotch Provide safe separation of X-ray beam from the accelerator vacuum system. For high beam current storage rings, part of the crotch experience high density of SR power.
- 2. Beam stoppers (or shutters) Provide safe isolation between the X-ray beamline from the accelerator vacuum system. Multiple stoppers for redundancy.
- 3. X-ray windows (Be windows) and low-E filters
- 4. Fast-closing gate valves with vacuum triggering system
- 5. For windowless X-ray beamlines, adequate vacuum delay lines with differential pumping.

