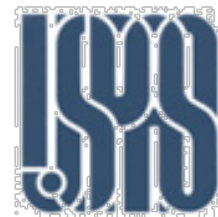


Vacuum Science and Technology for Accelerator Vacuum Systems

Yulin Li and Xianghong Liu
Cornell University, Ithaca, NY



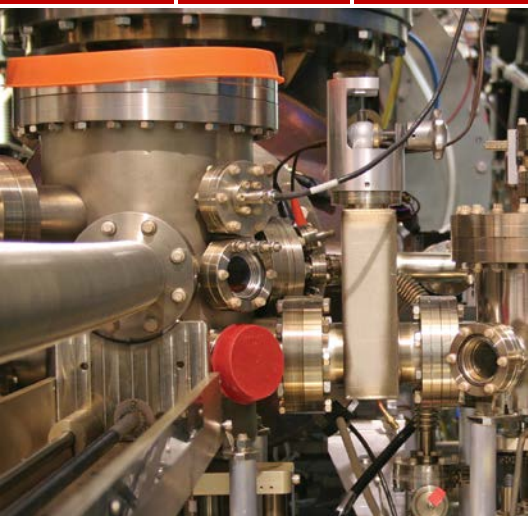


Table of Contents

- Vacuum Fundamentals
- Vacuum Instrumentation
- Sources of Gases
- Vacuum Pumps
- **Vacuum Components/Hardware**
- Vacuum Systems Engineering
- Accelerator Vacuum Considerations, etc.

Bellows – Functions



- ❑ *Make up for transverse offsets in beamline hardware, and minor misalignments*
- ❑ *Provide installation personnel with sufficient flexibility to install hardware.*
- ❑ *Reduce stresses on adjacent vacuum joints.*
- ❑ *Provide adequate expansion and/or contraction ability during thermal cycles.*
- ❑ *Provide required movements for functioning instruments, such as beam profile viewers.*

Bellows – Key Parameters



- *Bellows free length*
- *Bellows maximum extended length*
- *Bellows minimum compressed length*
- *Bellows maximum transverse offset*
- *Maximum number of cycles*
- *Bellows end configurations*

Types of Flexible Bellows



Edge-Welded

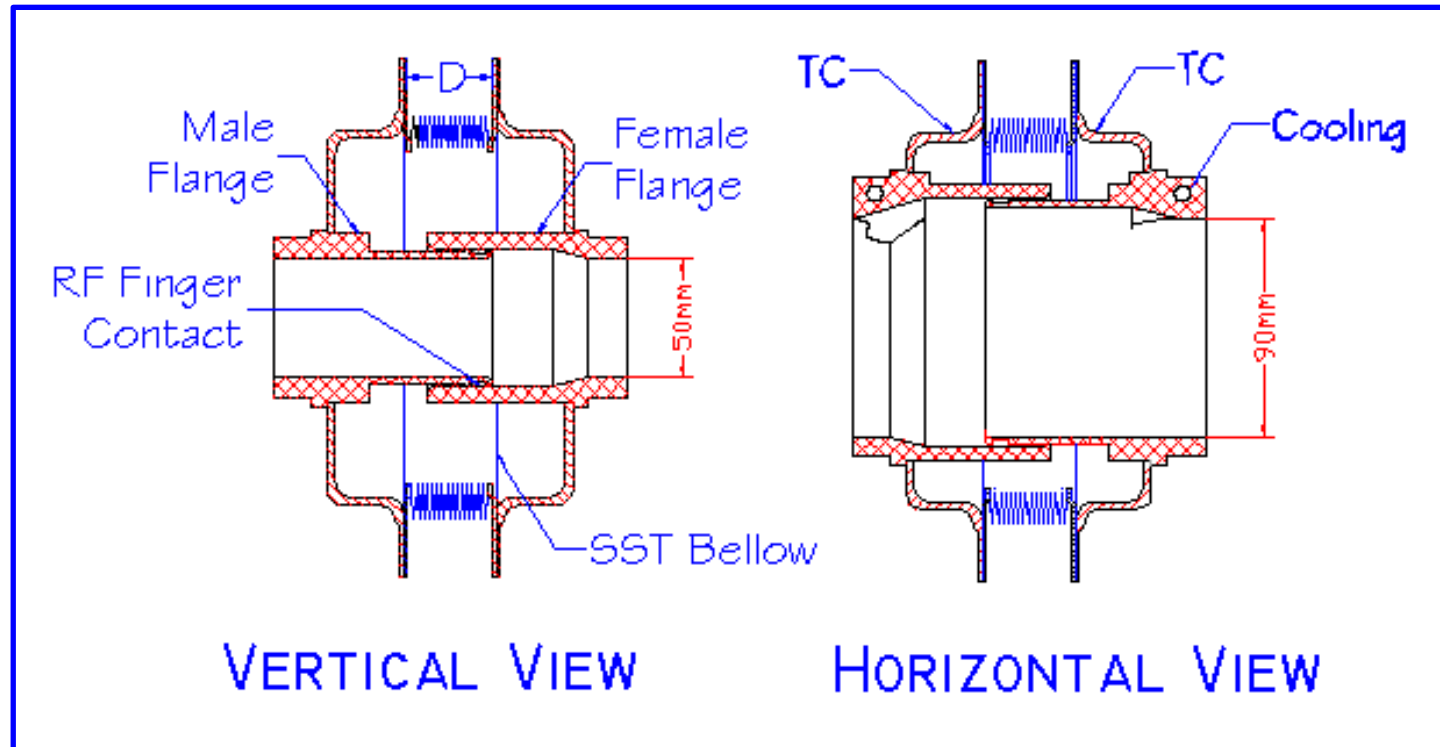
- *Very flexible, both axial and transverse*
- *Very long stroke available*
- *Non-circular cross section available*
- *User-configurable, from most vendors*
- *Higher cost*
- *Need mechanical and corrosion protections*



Hydro-formed

- *More robust, comparing to welded*
- *Lower cost*
- *Usually good transverse flexibility*
- *Not good for long stroke application*

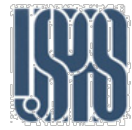
RF-Shielded Sliding Joint in CESR



*In storage rings (or accelerators with intense short bunched beams), bellows **MUST** be shielded from the beam. Otherwise, wake-field will be excited in the cavities to:*

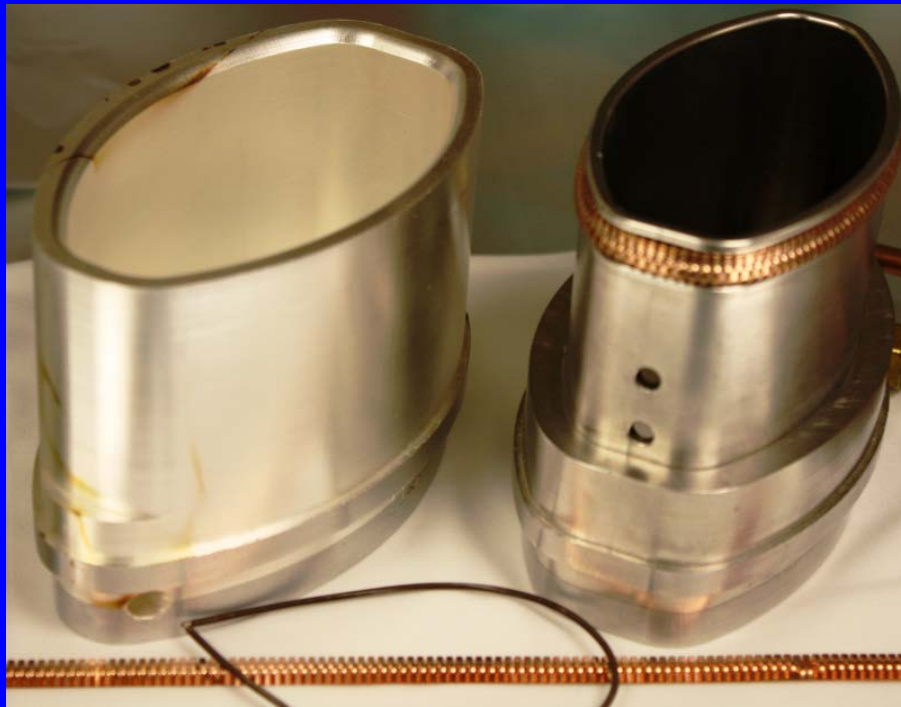
- Cause damage to the bellows*
- Induce negative effects to the beam.*

Sliding Joint in CESR – Parts



~120 used in CESR, each provide 1.75" Stroke

Two sliding oval-shaped tubes, made of 6061-T6 aluminum, and Be-Cu RF fingers. One with hard coating, one with silver coating.

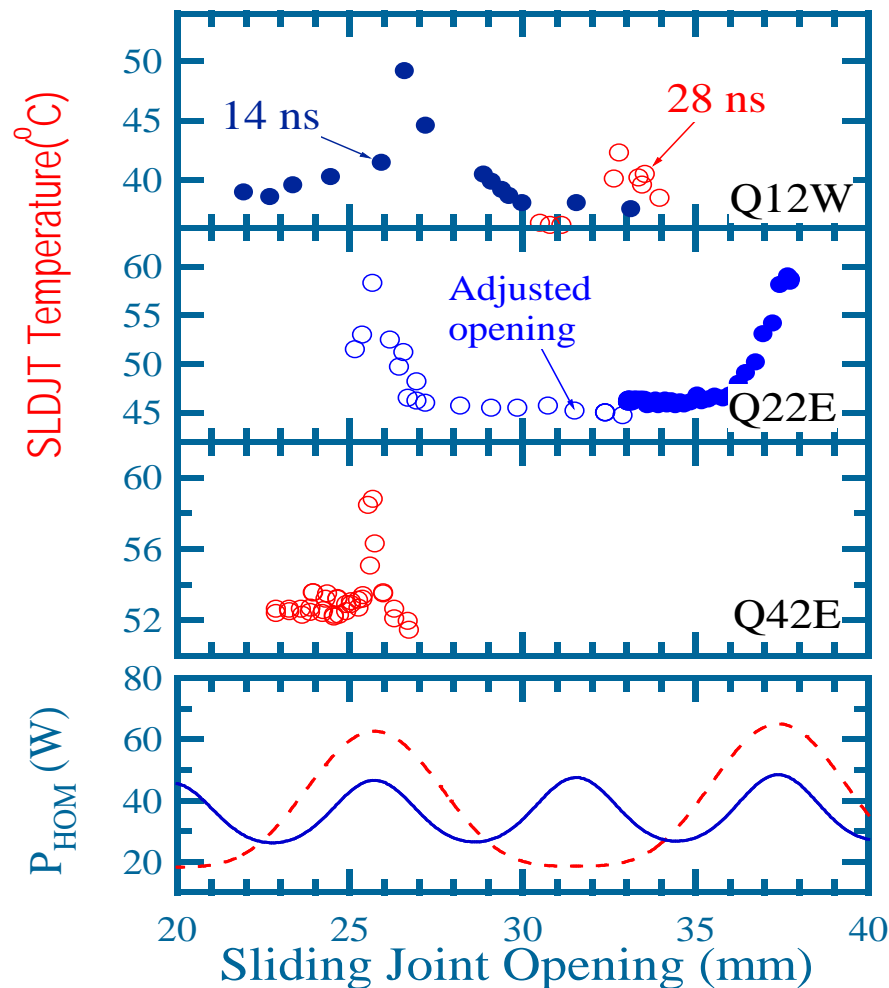


Friction bonded pans enable transitions between aluminum to stainless steel bellows

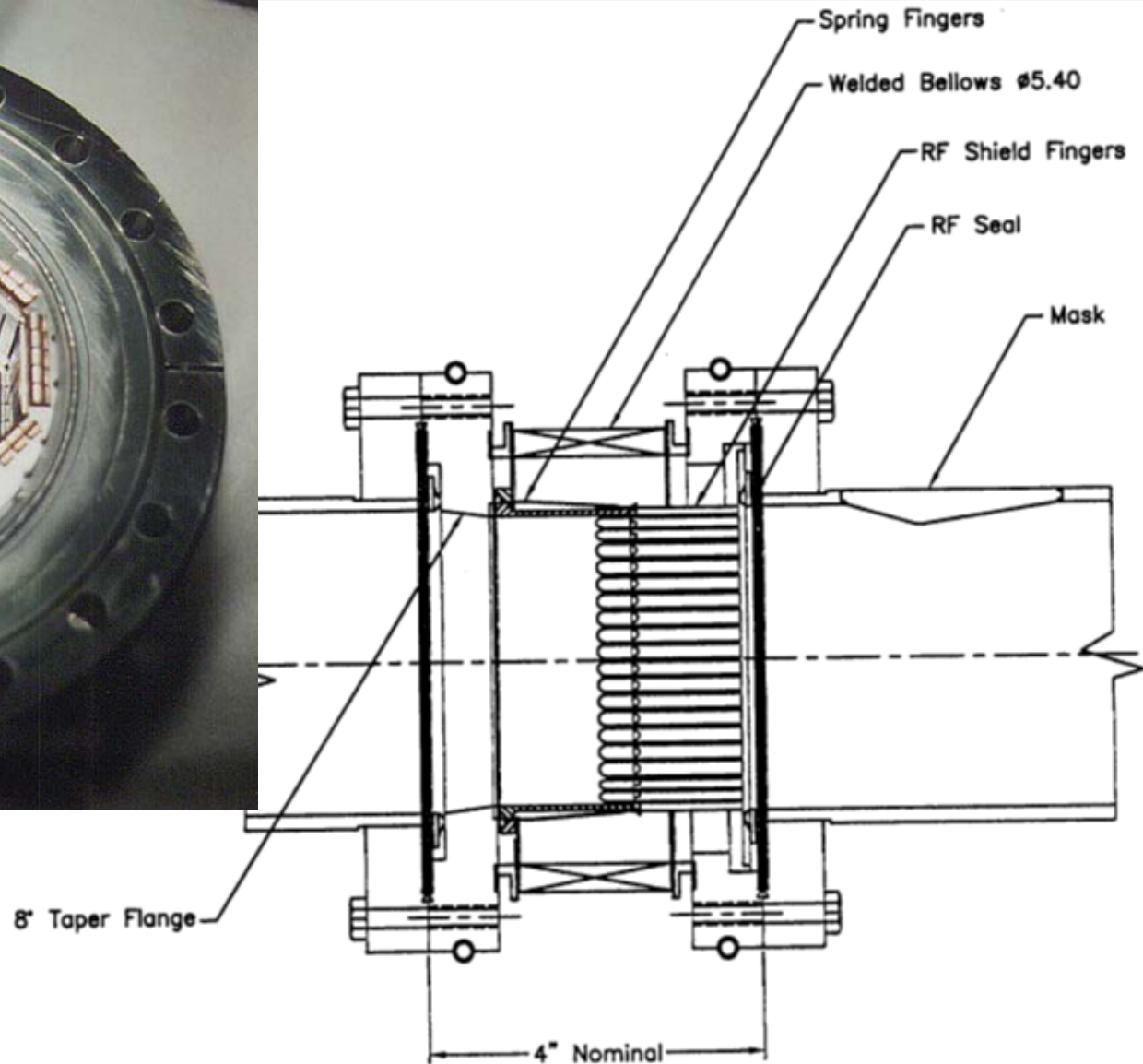
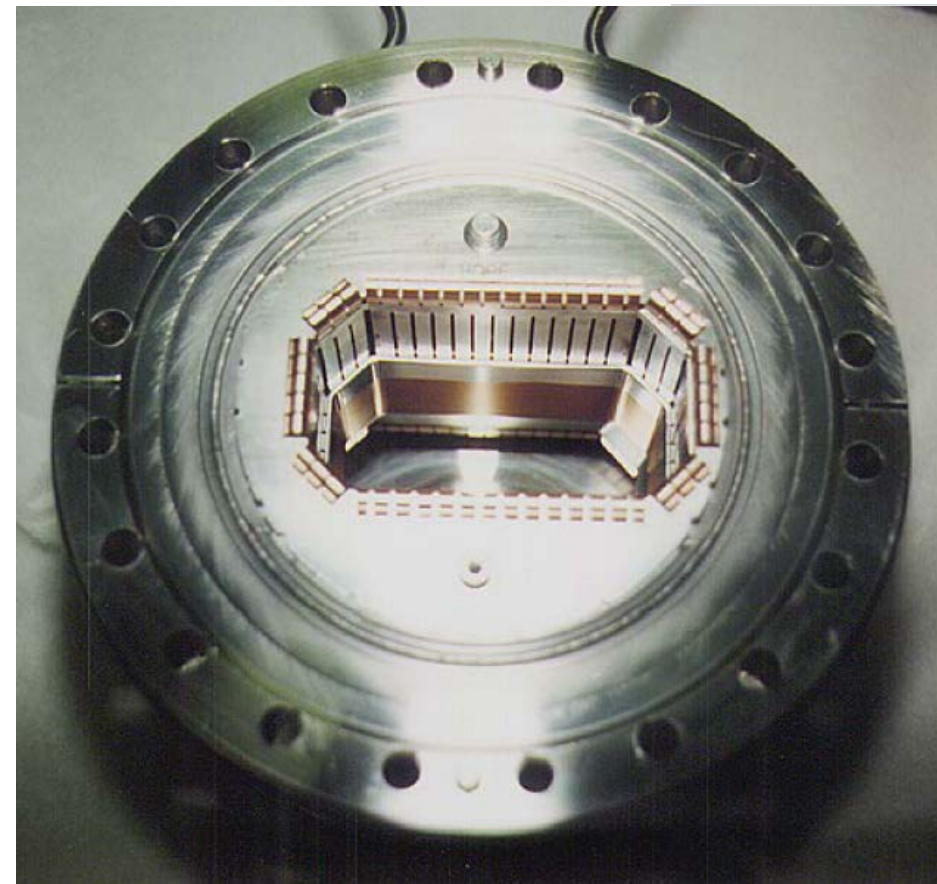
Sliding Joint in CESR – RF Heating



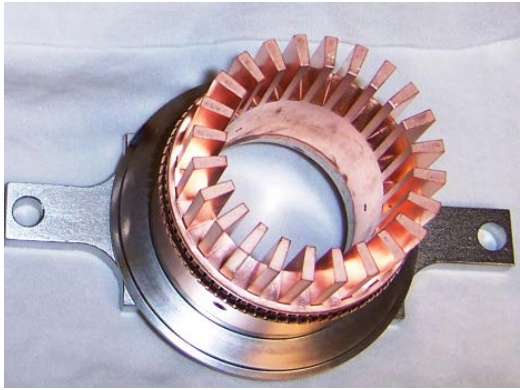
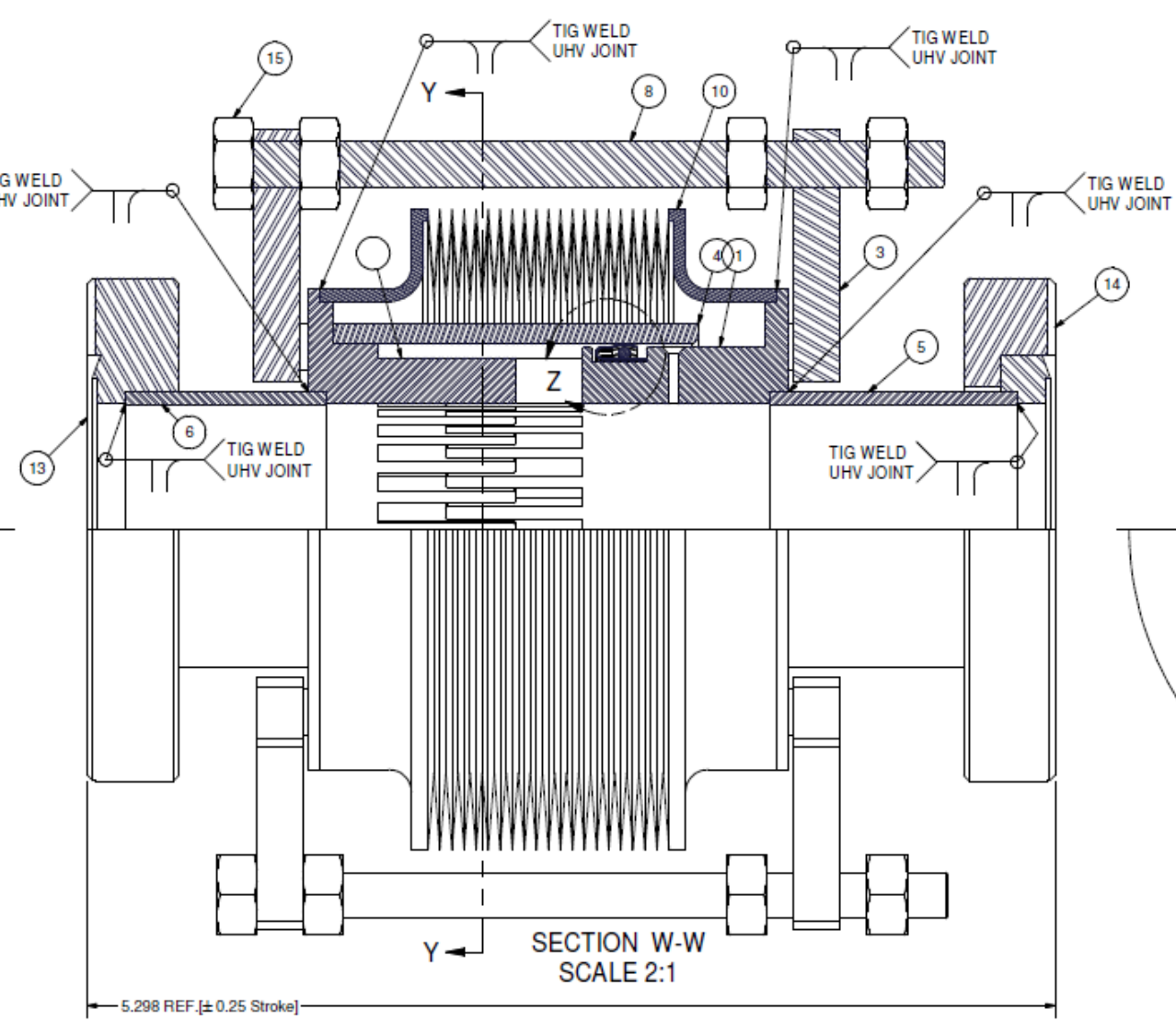
- CESR sliding joint was designed more than 30 years ago.
- Though with the RF-contact shielding the bellows, the steps in the CESR sliding joints forms a RF cavities.
- We have observed resonant RF excitation in the cavities, and cause significant heating some particular opening.
- Most modern designs of RF-shielded bellows have much smoother transitions, to reduce RF-impedance.



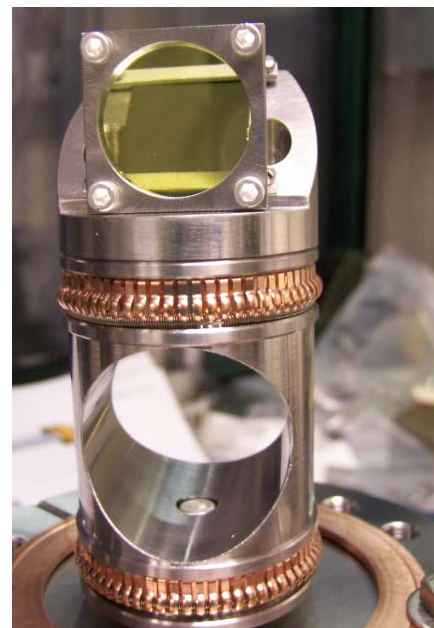
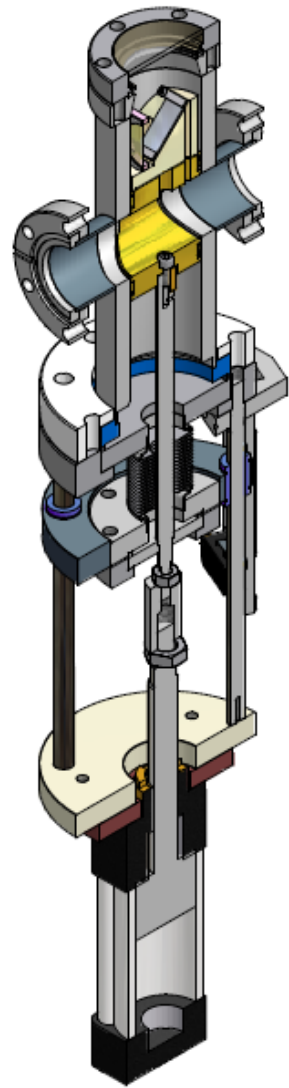
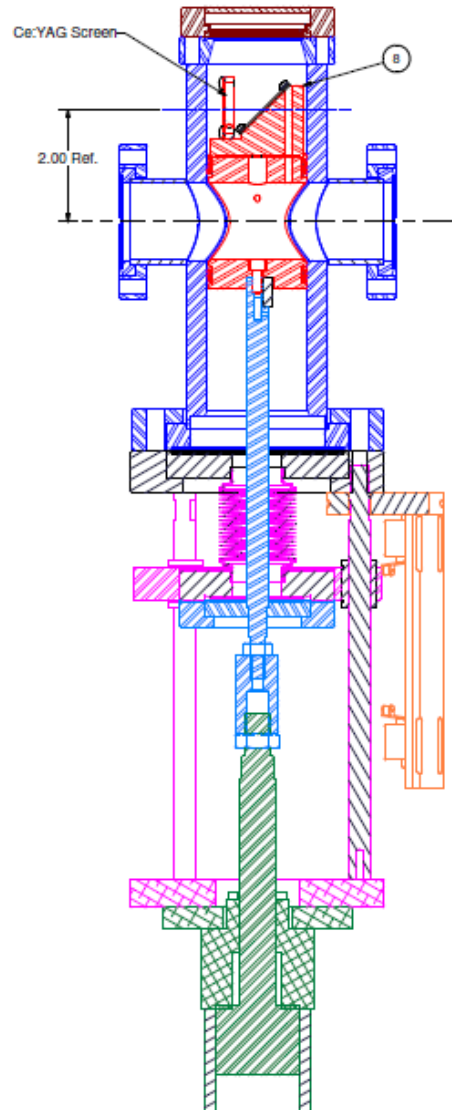
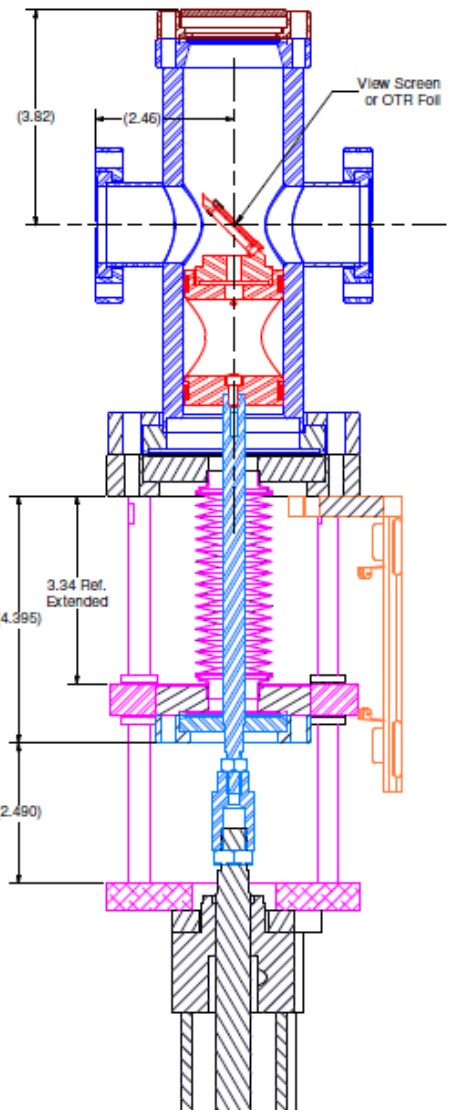
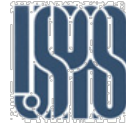
RF-Shielded Sliding Joint of PEP II



RF-Shielded Sliding Joint of KEK Style



RF-Shielded Beam Viewer for Cornell ERL

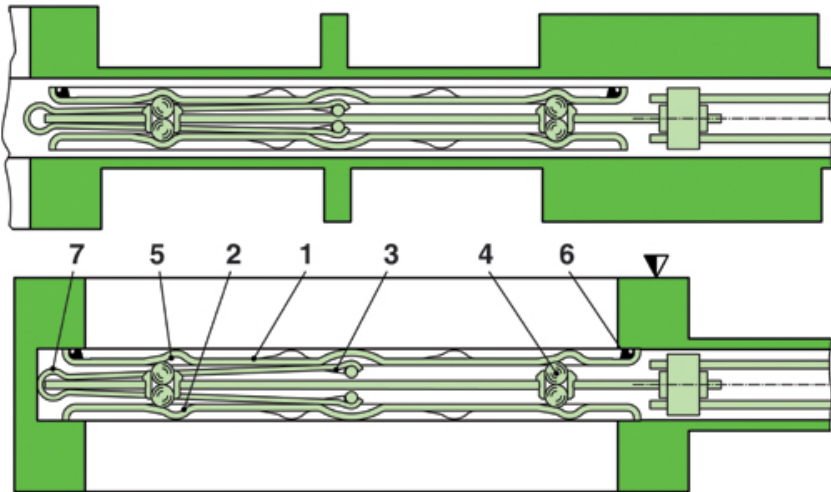


Vacuum Valves for Accelerators



- *All-metal Gate Valves*
- *All-metal Angle Valves*
- *RF All-metal Gate Valves*
- *Fast Closing Valves*

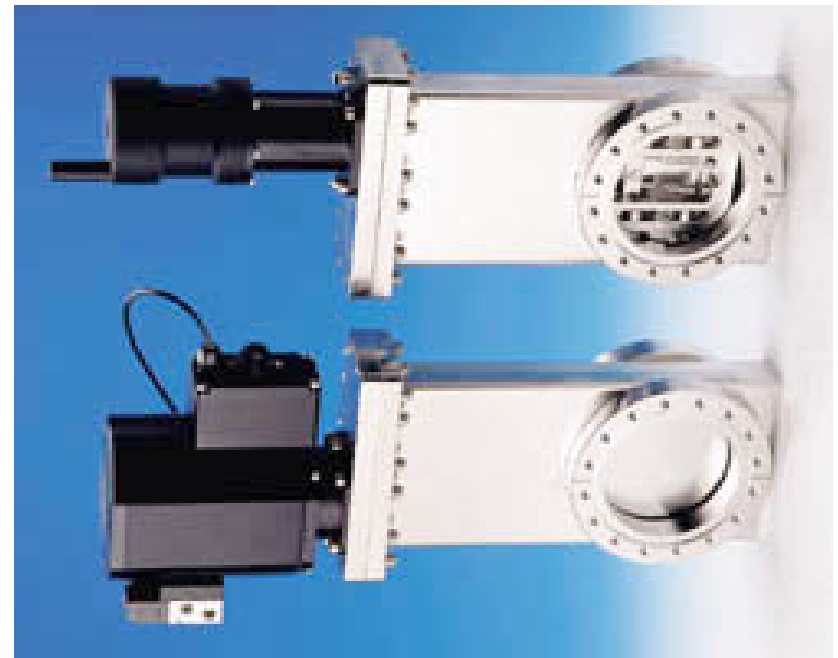
UHV Gate Valves



- ▼ - valve seat side
- 1 - valve gate
- 2 - counter plate
- 3 - leaf springs
- 4 - ball pairs
- 5 - detents
- 6 - gate seal
- 7 - spring stop



- *All-metal UHV valves only available from VAT Valves*
- *ID from 35-mm to 320-mm*

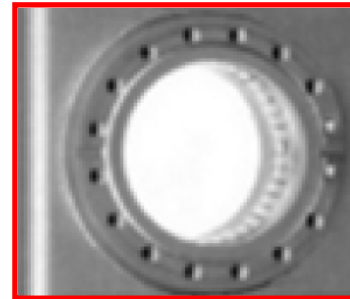


- *Gate valves with metal bonnet seals and elastomer flap seals are more available.*
- *For general UHV system, this is an low-cost alternative.*
- *ID from 35-mm to 320-mm*

RF Shielded All-metal Gate Valves

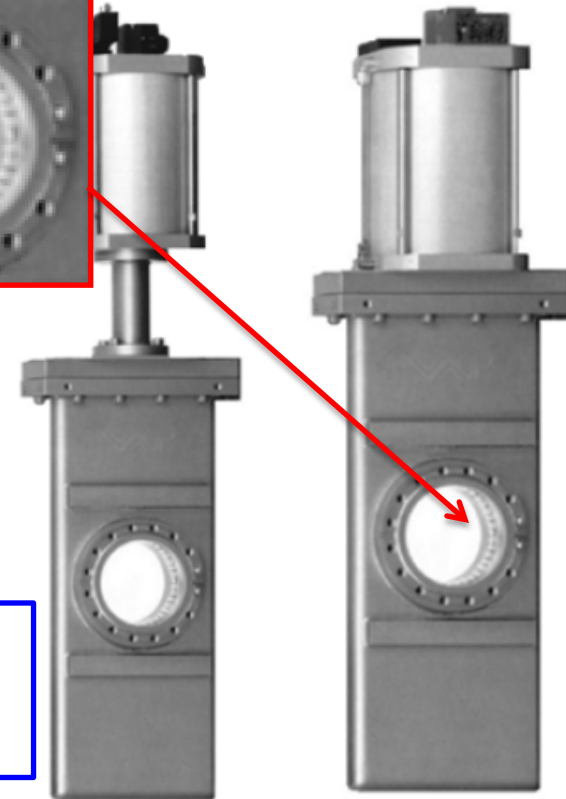


- *Used as sectoring vacuum sections in large accelerator vacuum system.*
- *Pneumatic actuated, allowing vacuum system interlocking.*
- *316L stainless steel body with elastically deformed metal seals*
- *RF trailer deploys at open position.*
- *Max. operating temperature 200°C*
- *Bellows sealed, allowing 100,000 cycles*

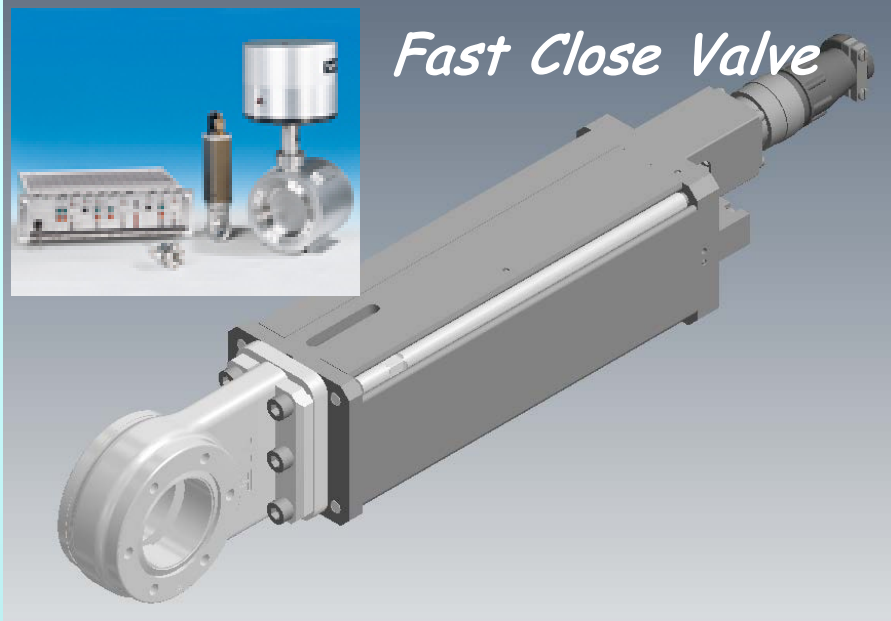


RF Seal on CESR Gate Valve

**Comb-Style RF Seal on
KEK/TPS GVs (Starting @1'30")**



Fast Close and Beam Stop Valves



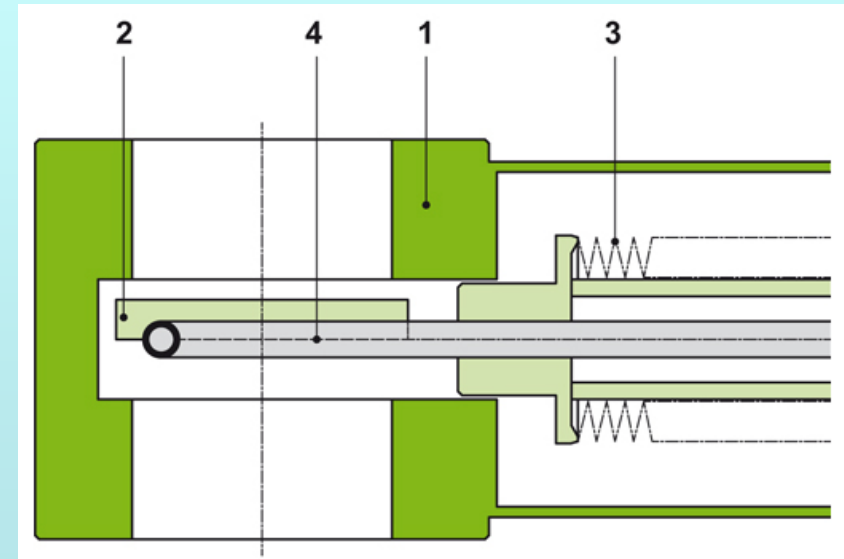
Fast Close Valve

- *Closing time: < 10-ms after trigger*
- *Usually used on X-ray beamlines*
- *Need reliable and fast vacuum gauges at engineered distance from the valve, to provide sensible valve closing trigger.*
- *Most firings are false triggering !!*

Beam Stop for X-ray beamlines

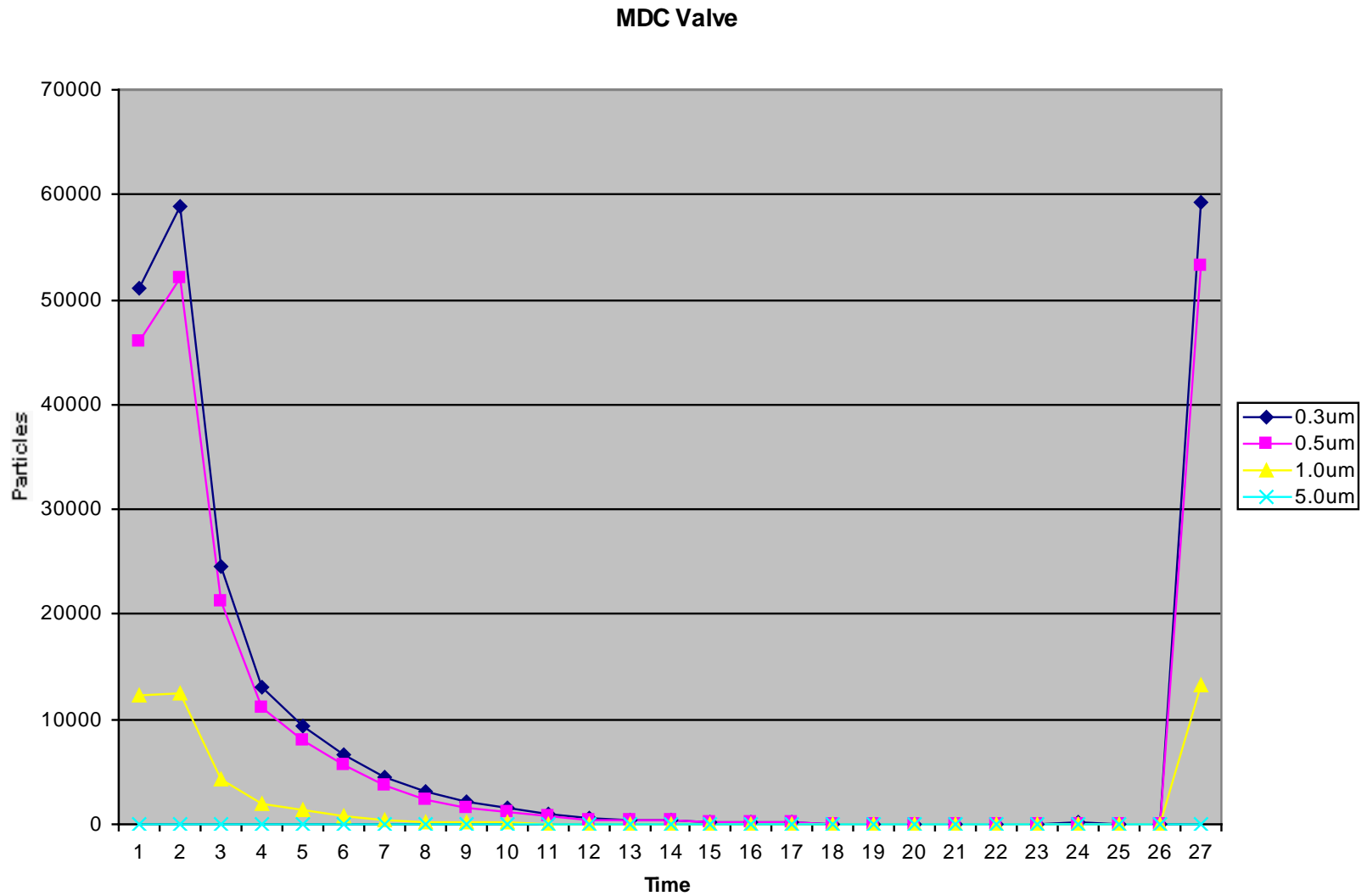


- ❖ P_{max} : 5 kW
- ❖ Max. Power density: 25 W/mm²

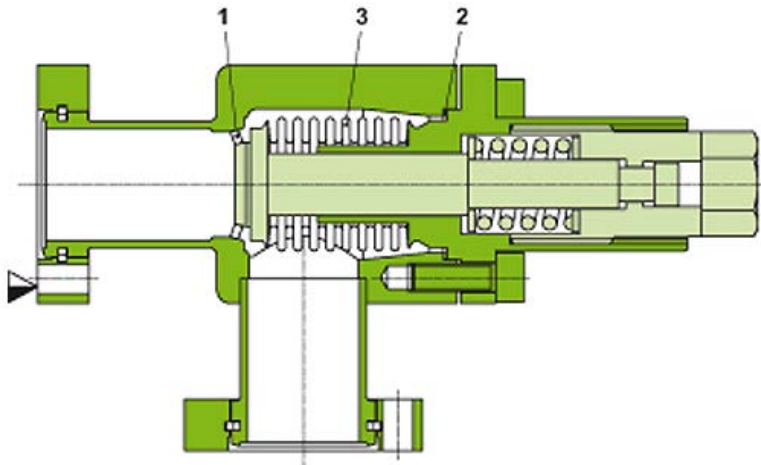
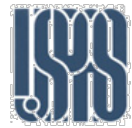


- 1. Body; 2. Copper Plate
- 3. bellows; 4. Water cooling

Particle Generation While Actuating Gate Valves



All-metal Angle Valves



- ▼ - valve seat side
- 1 - VATRING
- 2 - bonnet seal
- 3 - bellows

- All-metal Easy-Close angle valves, no torque wrench needed.
- Best in dust-free environment

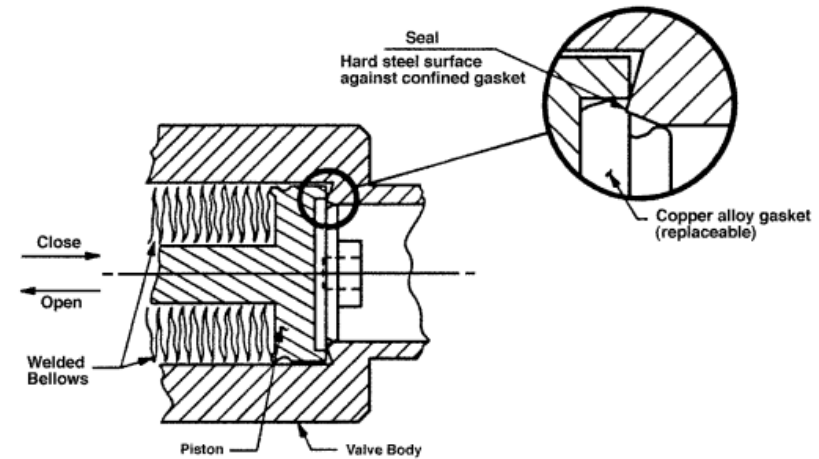


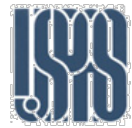
Figure 1-1 Sealing Principle

- All-metal angle valves with copper gasket seals. More robust.
- More sealing cycles with increasing torque

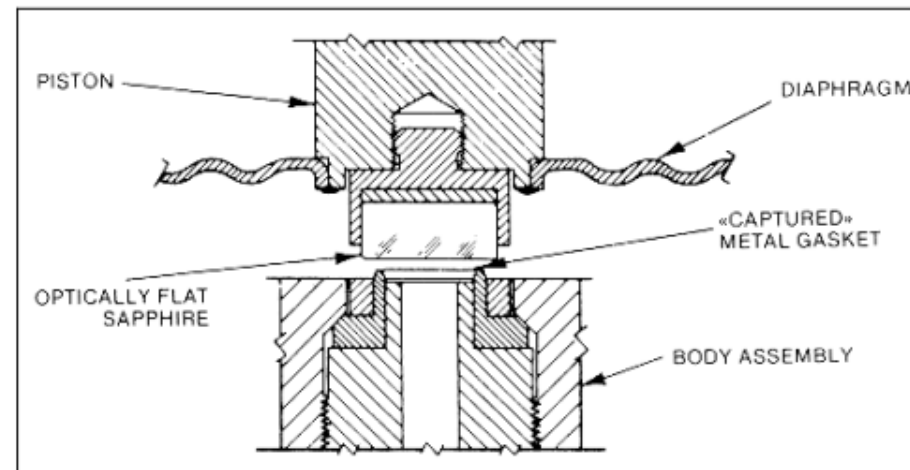


Used for roughing, purging and venting vacuum systems

Variable Leak Valves



- ❖ *A variable leak valve is used for vacuum equipment that need to control the amount of gas introduction.*
- ❖ *It enables the gas introduction of remarkably small amount; minimum controllable leakage is less than 1×10^{-9} torr·L/sec.*
- ❖ *Additionally, it is all-metal and can be baked up to 450°C , making it ideal for ultra-high vacuum equipment.*
- ❖ *The seal surface is fragile, so one must NOT close the valve too fast.*



Electrical Feedthroughs



- Coaxial
- Power
- High Current
- High Voltage
- Breaks
- RF Power



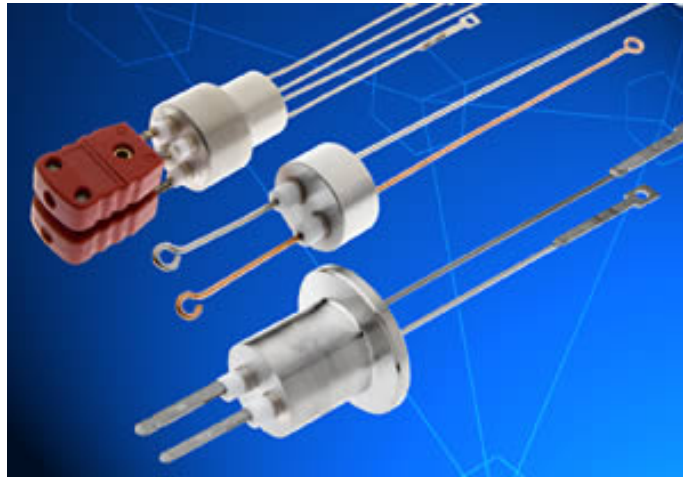
Instrumentation Feedthroughs



Multi-pin feedthroughs



Sub-D feedthroughs



Thermocouple feedthroughs

Linear Motion & Multi-motion Feedthroughs



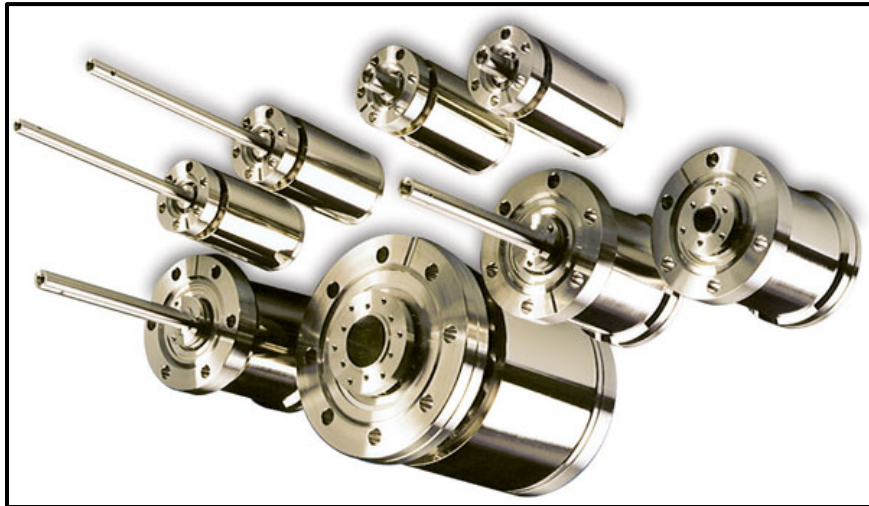
- The class of feedthroughs span from simple “push-pull” to precision units.
- Manual, motorized, and pneumatic action.
- UHV compatible
- Linear travel ranges from $\frac{1}{2}$ ” to 6”.
- Magnetic coupled translator for over 48” travel. For very long translators, ‘dead-end’ pumping may be required for some UHV applications.
- Multi-axis stages



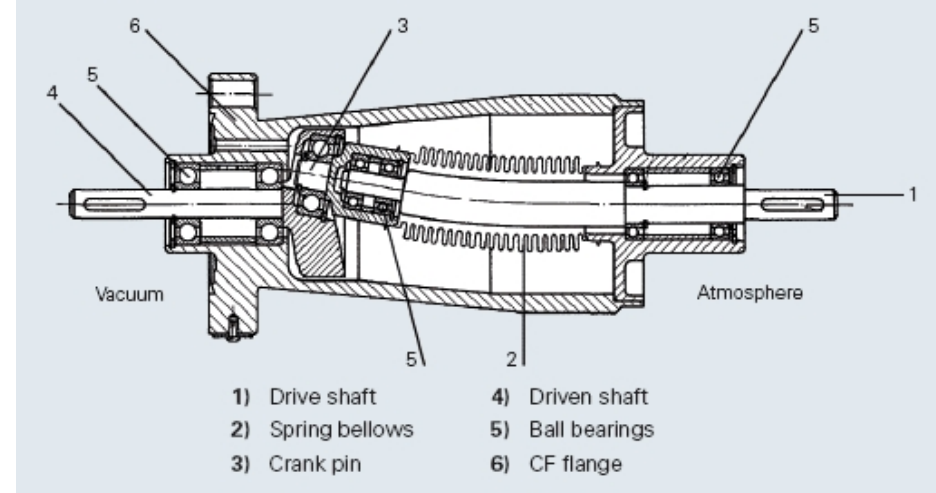
Rotary Motion Feedthroughs



- *Manual or motorized actuation.*
- *UHV compatible*
- *Torque to 50 oz-in*
- *Speeds to 50 rpm*

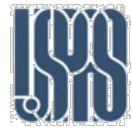


Magnetic Coupled



Bellows Coupled ("Cat's Tail")

Pumping Ports for Beampipes

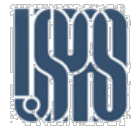


These components must maximize conductance to the pump, while minimizing detrimental effects on the beam.

- *To connect the beam space to the vacuum pumps, opening have to be made between the beampipe wall and the pump port.*
- *The most common openings are in the form of slots along the beam direction, as illustrated here.*
- *Beam bunches passing by the slots radiates RF power, contributing RF impedances.*
- *The losses from the pumping slots should be checked to within the allowed impedance 'budget'.*



RF Loss Factor of Pumping Slot



For a single slot on a round beam pipe, the loss factor (in unit of V/pC) is:

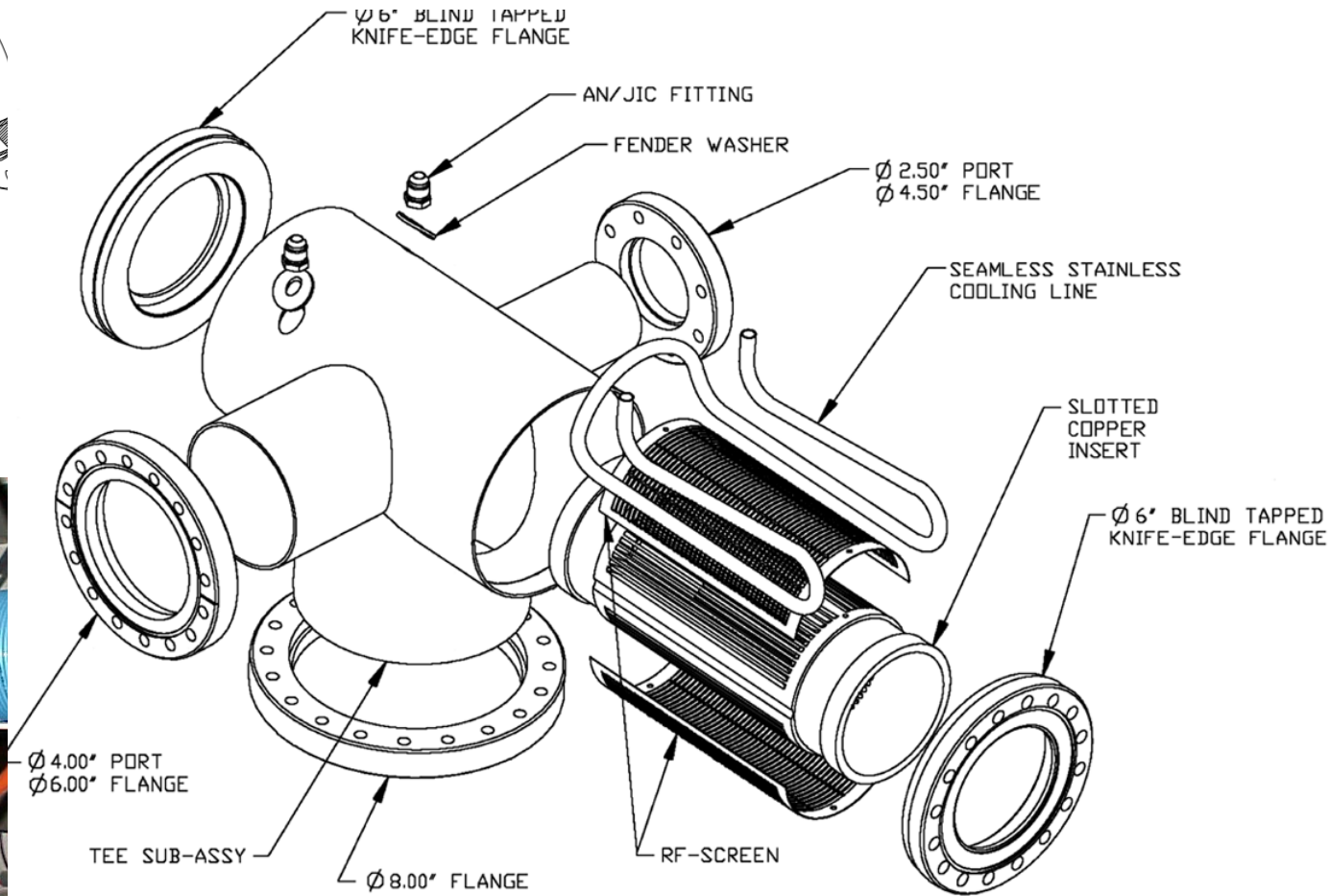
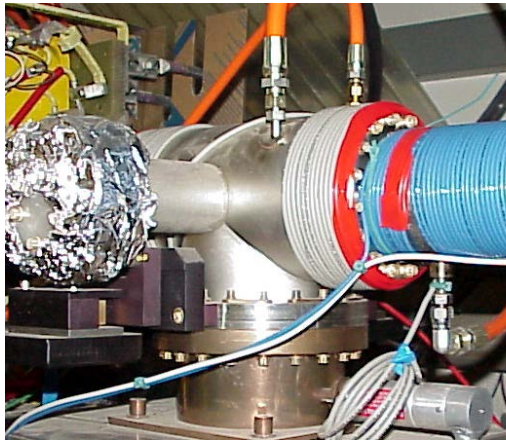
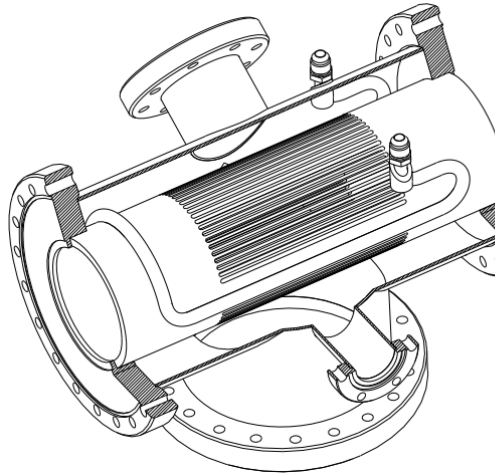
$$k = 1.24 \times 10^{-3} \frac{n_b}{\sigma_b^5} \cdot \frac{l_{slot}^2 \cdot w_{slot}^4}{r_{pipe}^2}$$

- n_b is the number of bunches
- σ_b is the beam bunch length in mm
- l_{slot} and w_{slot} are the length and width in mm of the slot, respectively,
- r_{pipe} is the inner radius of the beam pipe

Spreadsheet

- *RF loss at a lost is severer for very short bunches*
- *Long, narrow slots are the better 'compromise' between RF loss and gas conductance*

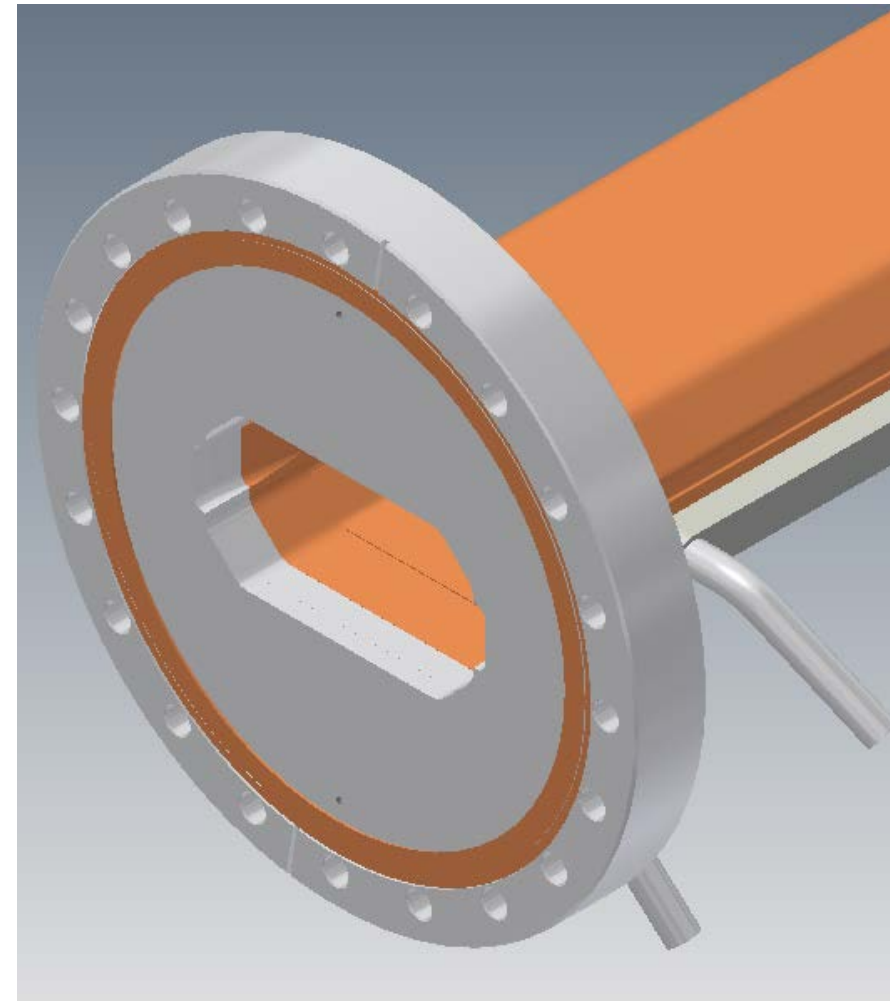
PEP-II Pump Tee



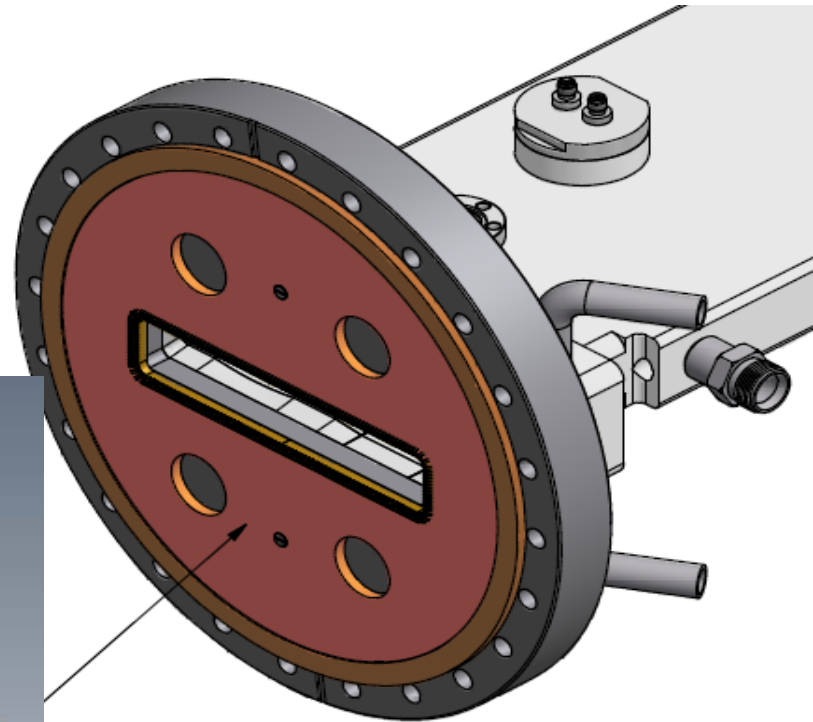
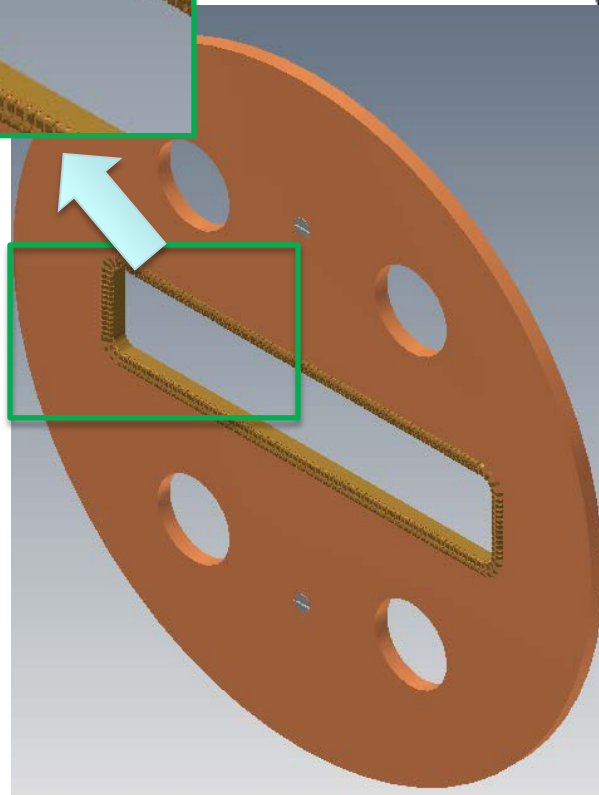
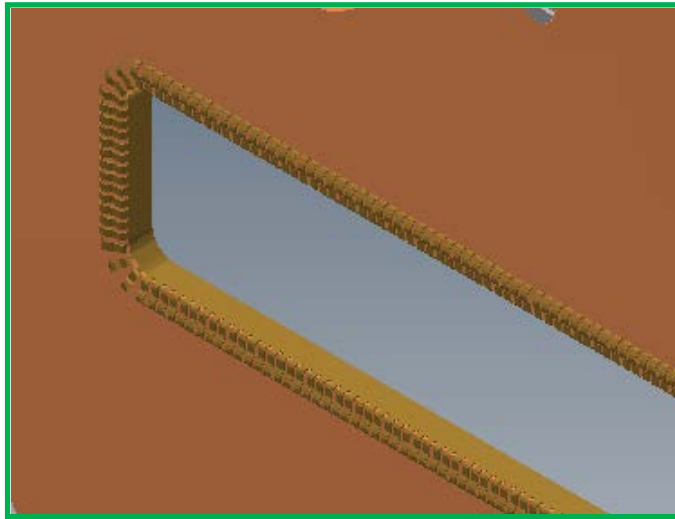
RF 'Cavities' in Flange Joints



- ❑ Making beamline flange joints using regular Cu gaskets may form RF cavities, particularly when the beam aperture differs significantly from the flange cross shape.
- ❑ Measures must be taken to bridge the gap to form a smooth bore beamline.
- ❑ Some of the methods are:
 - ✓ *RF insert with spring fingers*
 - ✓ *Gap rings*
 - ✓ *Zero-gap gaskets, similar to VATSEALs*

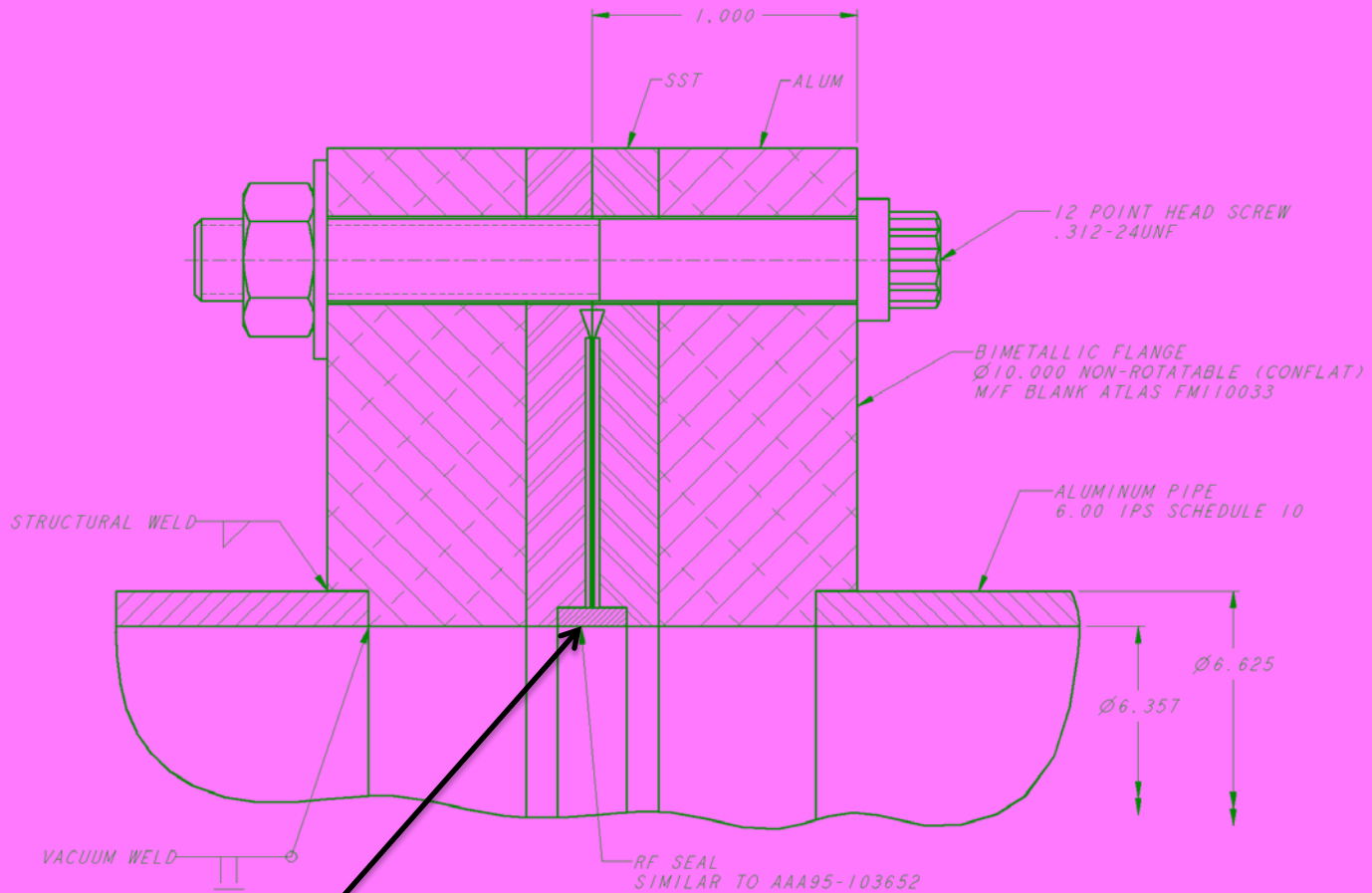


RF Insert at Flange Joints



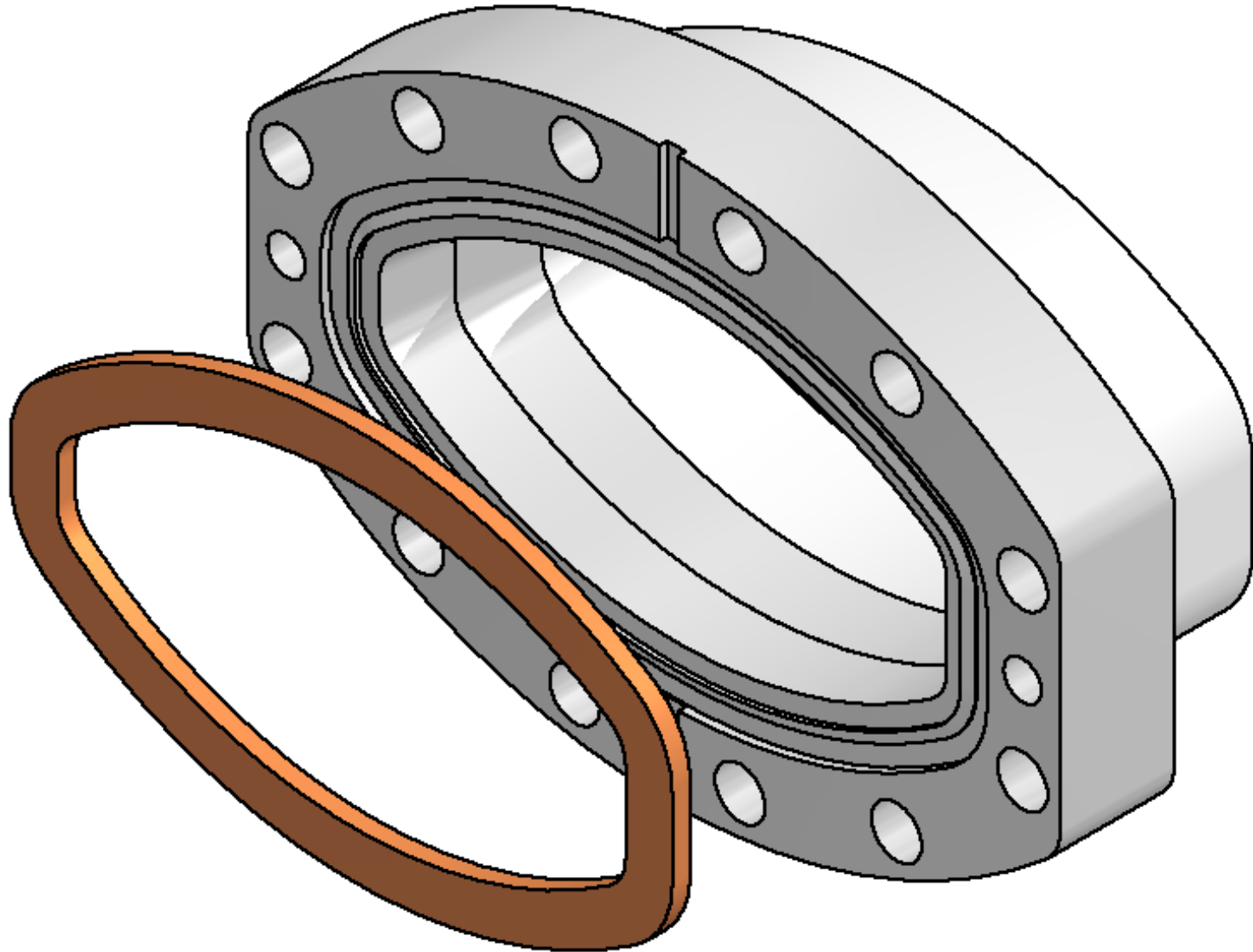
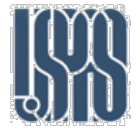
*Be-Cu RF Finger strip
brazed onto Cu RF insert,
to bridge the flange gap, on
the vacuum side of the
vacuum gasket.*

'Gap Ring' at Flange Joints



RF Seal Gap Ring

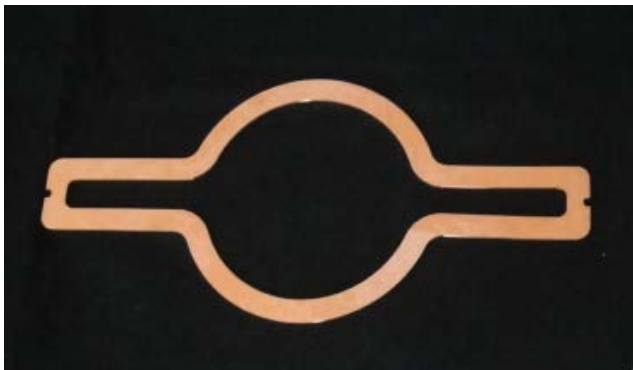
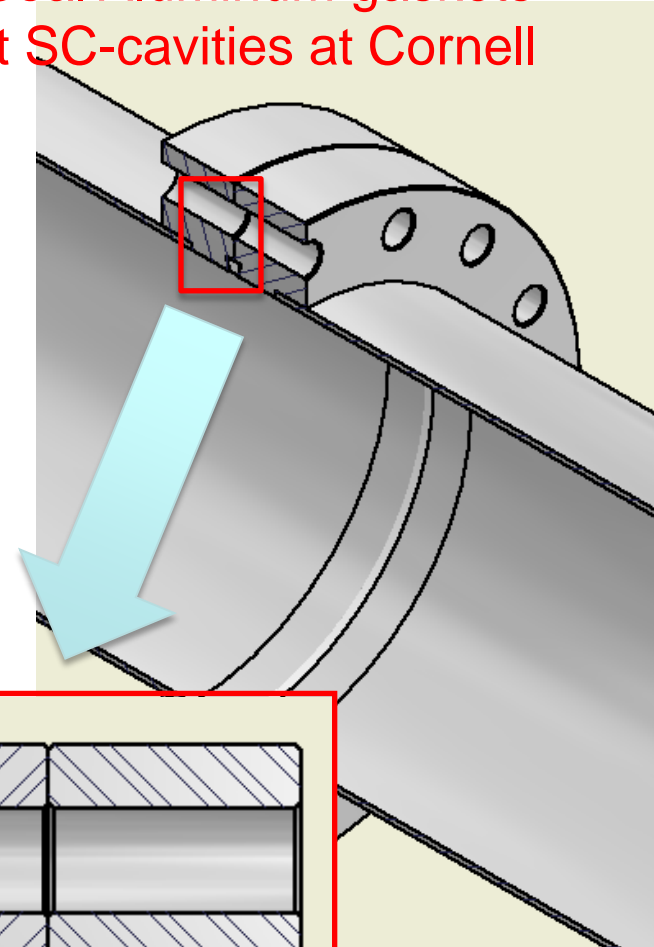
Flange design with minimized 'cavity'



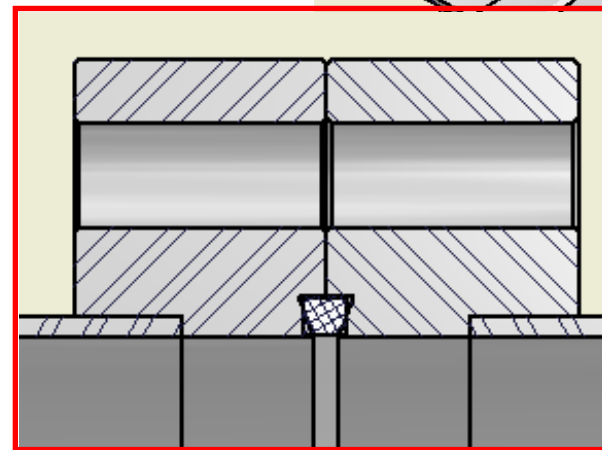
Zero-Impedance Flange Joints



Taper-Seal Aluminum gaskets
Used at SC-cavities at Cornell



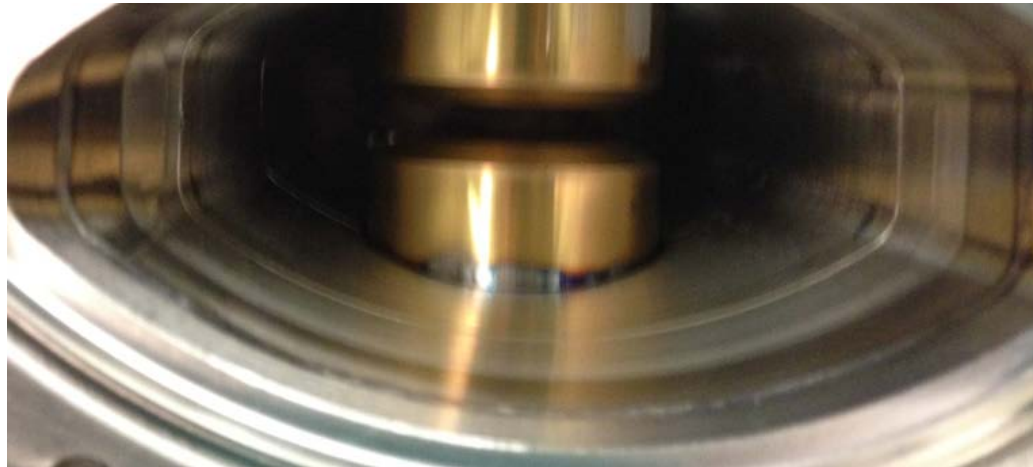
Face-Seal Copper Gaskets
used in KEK SuperB



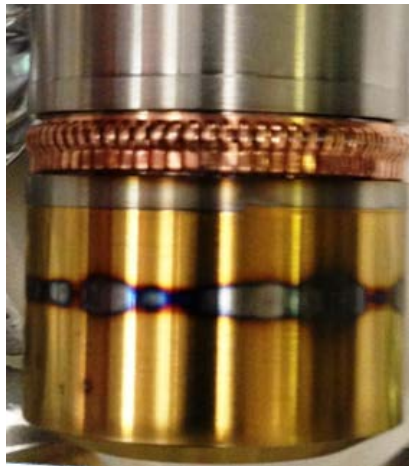
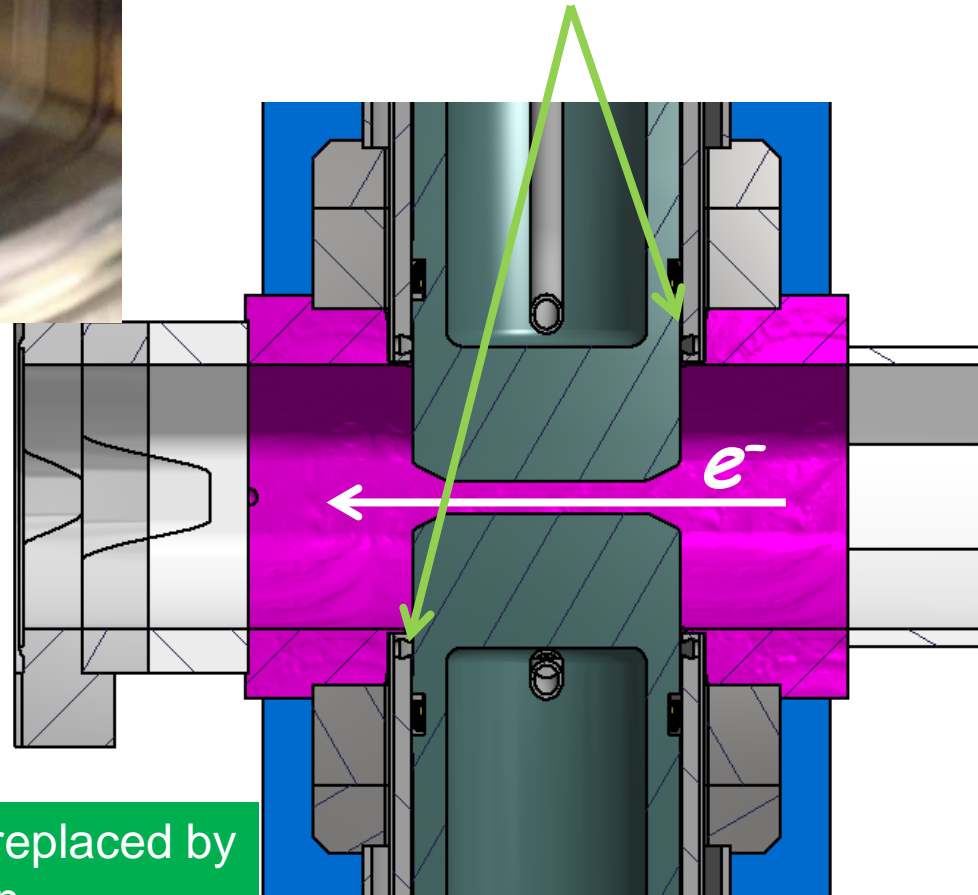
Bad Thing Happens with Bad RF Contacts



A Vertical Scraper at CESR



Contact Coil Spring
Locations of Heating/Arcing

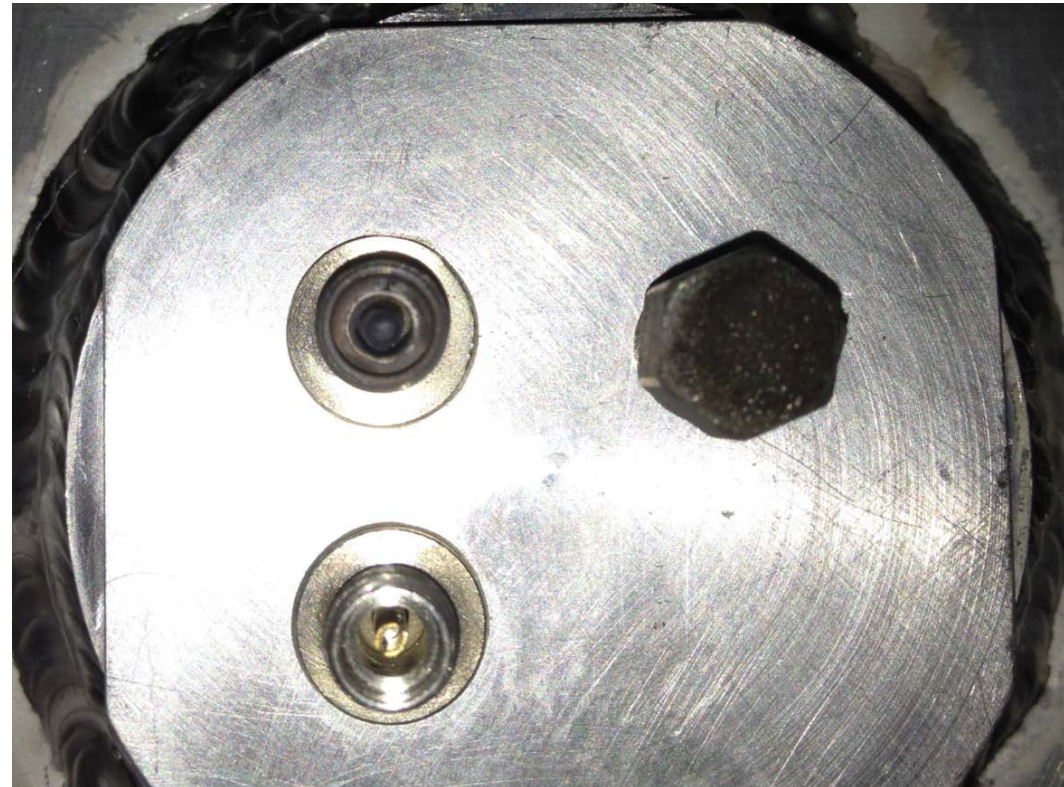
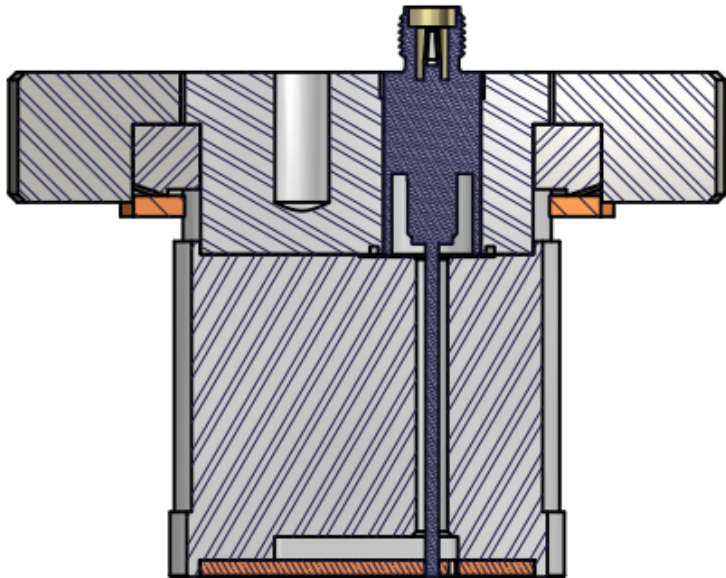
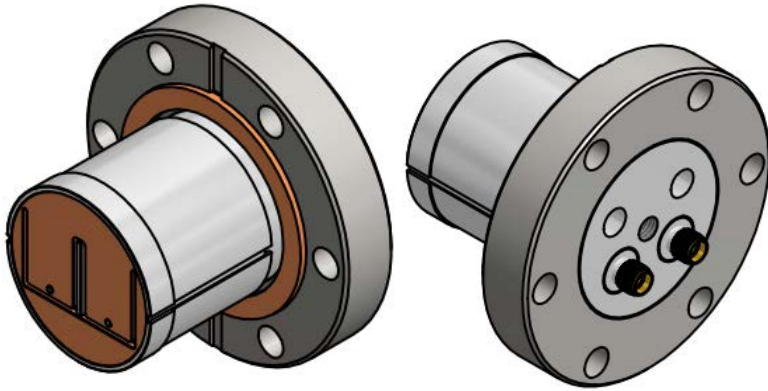


High resistive stainless coil springs were replaced by BeCu finger contact in an improved design

Bad Thing Happens w/ Bad RF Termination



*Damaged SMA, resulting
from a shorting SMA cap*

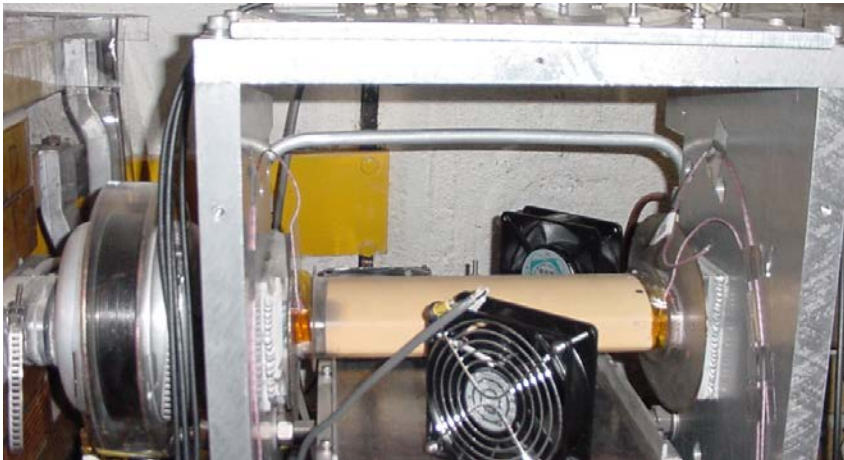


A Stripline BPM on 5-mm Undulator at CESR

Ceramic Beampipes

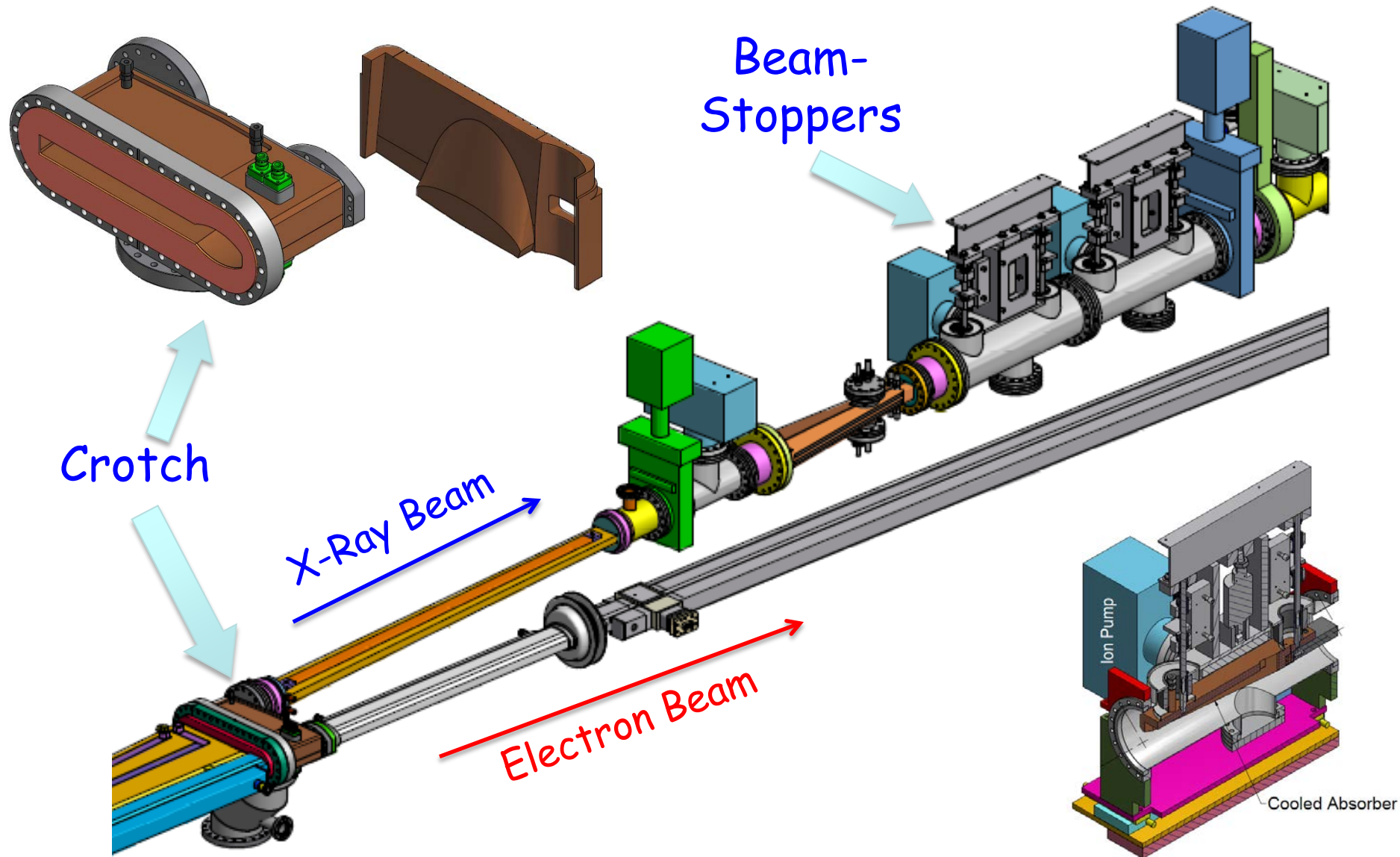


- ❑ *Almost all storage rings have ceramic beampipes, as parts of fast magnets for beam injection and feedback control systems.*
- ❑ *The ceramic body usually made of alumina, and jointed to metal flanges via vacuum braze. A strong-back structure is normally used to support the ceramics.*
- ❑ *Thin metallic coating is deposited on the inner surface of the ceramics, to provide conductive pass for image current. The coating is usually slightly thicker than the corresponding skin-depth, but thin enough to allow external field penetrate through.*



A CESR ceramic pipe mounted on strong-back frame, with flexible ends

A Typical X-Ray Beamline Front-End





- 1. Crotch - Provide safe separation of X-ray beam from the accelerator vacuum system. For high beam current storage rings, part of the crotch experience high density of SR power.*
- 2. Beam stoppers (or shutters) - Provide safe isolation between the X-ray beamline from the accelerator vacuum system. Multiple stoppers for redundancy.*
- 3. X-ray windows (Be windows) and low-E filters*
- 4. Fast-closing gate valves with vacuum triggering system*
- 5. For windowless X-ray beamlines, adequate vacuum delay lines with differential pumping.*