



## LECTURE 7

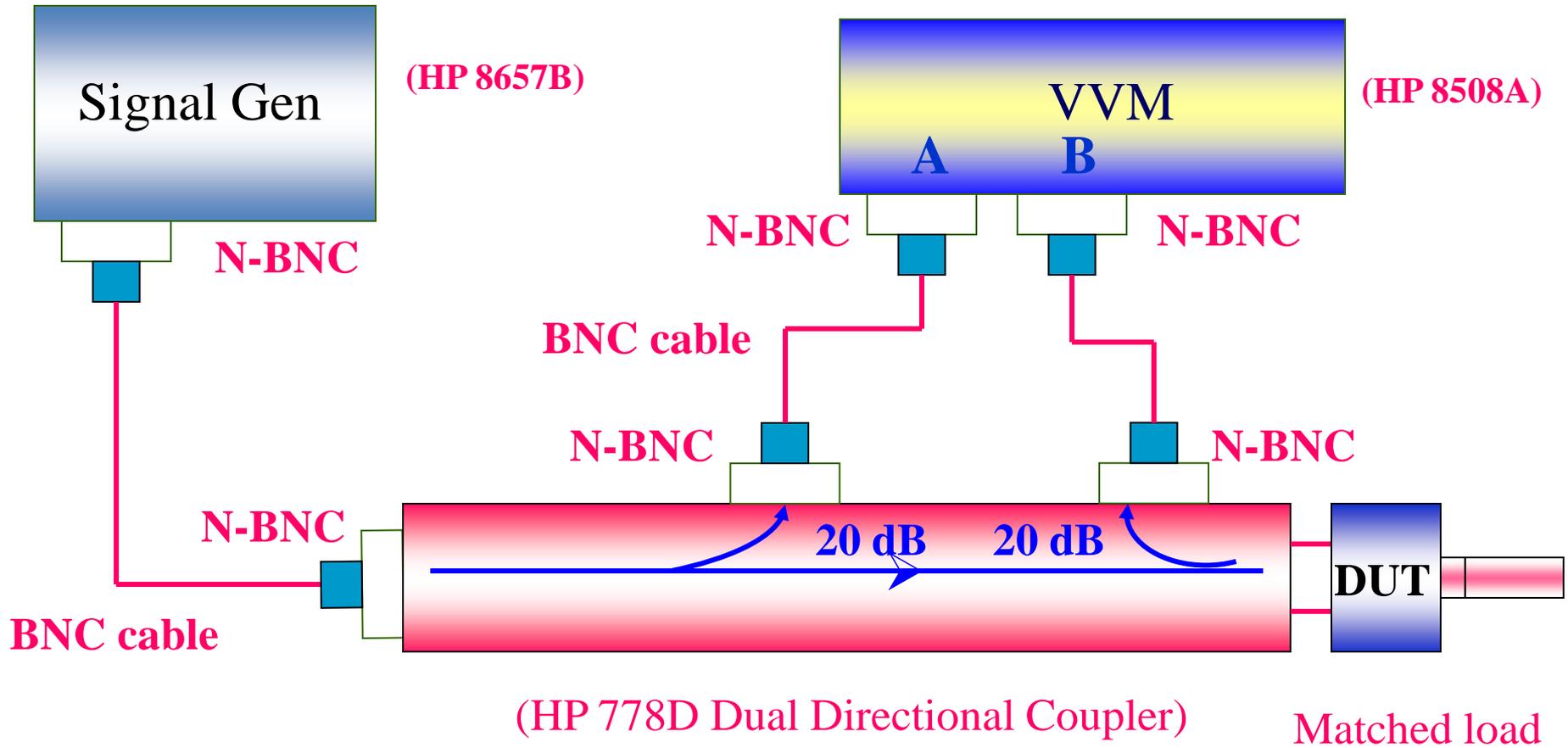
# MICROWAVE NETWORK ANALYSIS

**A. NASSIRI -ANL**



**VVM**: The vector voltmeter measures the magnitude of a reference and test voltage and the difference in phase between the voltages. Because it can measure phase, it allows us to directly measure the S-parameters of a circuit

Unfortunately, the use of the directional couplers and test cables connecting the measuring system to the vector voltmeter introduces unknown attenuation and phase shift into the measurements. These can be compensated for by making additional “calibration” measurements.





From the setup, it is seen that the voltage at channel A of the VVM ( $A^D$ ) is proportional to the amplitude of the voltage wave entering the device under test (DUT) ( $a_1^D$ ). Similarly, the voltage at channel B ( $B^D$ ) is proportional to the amplitude of the voltage wave reflected from DUT ( $b_1^D$ ). Thus we can write

$$A^D = K_A a_1^D$$

$$B^D = K_B b_1^D$$

Where  $K_A$  and  $K_B$  are constants that depend on the connecting cables. Since  $a_2^D$  is zero because of the matched load at port 2,  $S_{11}$  is given by

$$S_{11} = \frac{b_1^D}{a_1^D} = \frac{B^D / K_B}{A^D / K_A}$$



To find  $K_A$  and  $K_B$  it is necessary to make a second measurement with a known DUT. This is called a “calibration” measurement. If the DUT is removed and replaced by a short circuit, the voltage at channel A ( $A^S$ ) and channel B ( $B^S$ ) are given by

$$A^S = K_A a_1^S$$

$$B^S = K_B b_1^S$$

Where  $a_1^S$  is the amplitude of the voltage wave entering the short and  $b_1^S$  is the amplitude of the voltage wave reflected from the short. However, for a short circuit the ratio of these amplitudes is  $-1$  (reflection coefficient of a short). Thus

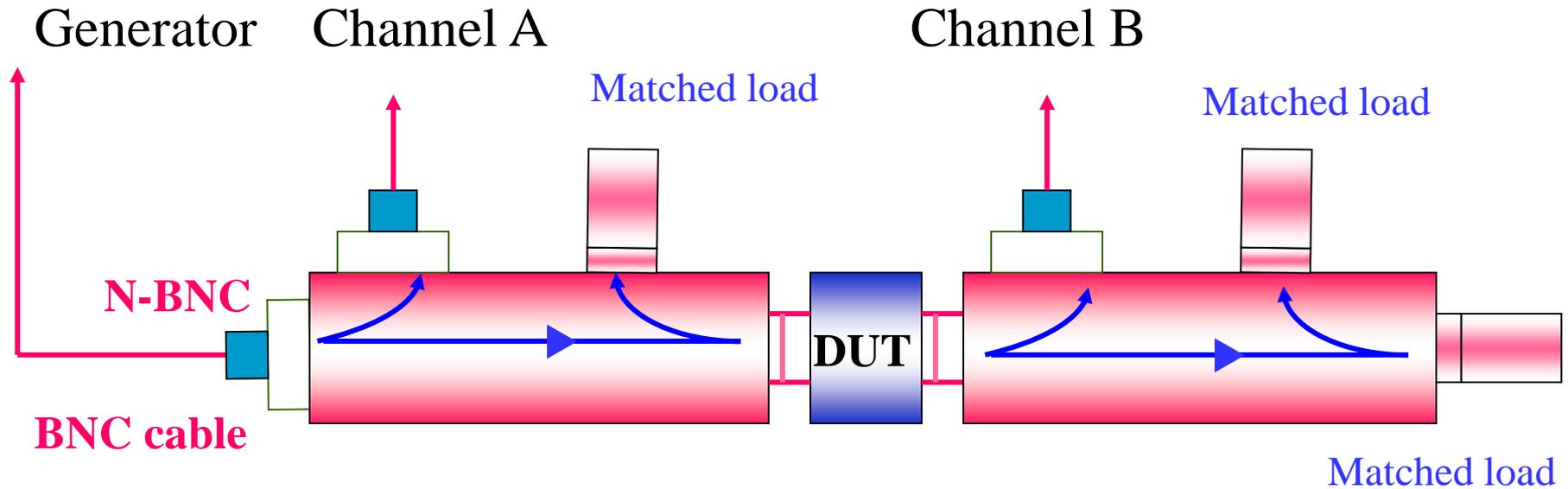
$$\frac{b_1^S}{a_1^S} = \frac{B^S / K_B}{A^S / K_A} = -1$$



$$\frac{K_B}{K_A} = -\frac{B^S}{A^S} \quad S_{11} = -\frac{\left(\frac{B^D}{A^D}\right)}{\left(\frac{B^S}{A^S}\right)}$$

**Note:** since VVM displays quantities in terms of magnitude and phase we can rewrite  $S_{11}$  as

$$S_{11} = \frac{\Gamma^D}{\Gamma^S} \angle(\phi^D - \phi^S - \pi) \quad \left(\frac{B^D}{A^D}\right) = \Gamma^D \angle\phi^D$$
$$\left(\frac{B^S}{A^S}\right) = \Gamma^S \angle\phi^S$$



The DUT is connected directly between two directional couplers. Voltage at A of the VVM is proportional to the voltage wave incident on the DUT while the voltage at B of the VVM is proportional to voltage wave transmitted through the DUT.



$$\begin{aligned} A^D &= K_A a_1^D \\ B^D &= K_B b_2^D \end{aligned} \Rightarrow S_{21} = \frac{b_2^D}{a_1^D} = \frac{B^D / K_B}{A^D / K_A}$$

To find out the constants a calibration measurement must be made. Remove the DUT and connect both directional couplers directly together. The Known DUT in this case is just a zero-length guide with a transmission coefficient of unity. The measured voltages are:

$$\begin{aligned} A^E &= K_A a_1^E \\ B^E &= K_B b_2^E \end{aligned} \quad \text{where} \quad \frac{b_2^E}{a_1^E} = \frac{B^E / K_B}{A^E / K_A} = 1$$

$$\therefore \frac{K_B}{K_A} = \frac{B^E}{A^E}$$



Transmission measurements:  $S_{12}$  or  $S_{21}$

$$S_{21} = -\frac{\left(\frac{B^D}{A^D}\right)}{\left(\frac{B^E}{A^E}\right)}$$

$$S_{21} = \frac{T^D}{T^E} \angle(\theta^D - \theta^E)$$

where

$$\left(\frac{B^D}{A^D}\right) = T^D \angle\theta^D$$

$$\left(\frac{B^E}{A^E}\right) = T^E \angle\theta^E$$



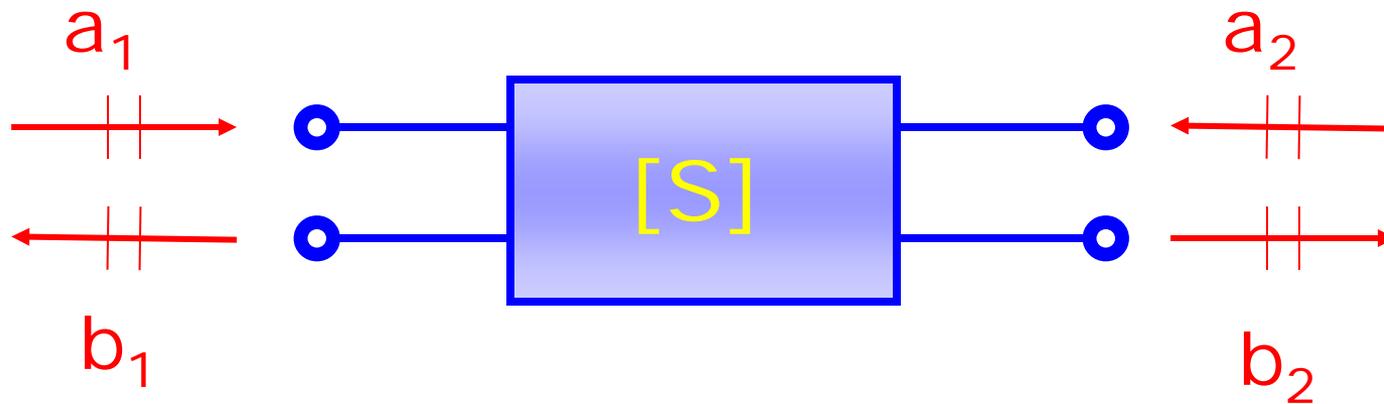
- ❑ Scattering Parameters (S-Parameters) plays a major role in network analysis
- ❑ This importance is derived from the fact that practical system characterizations can no longer be accomplished through simple open- or short-circuit measurements, as is customarily in low-frequency applications.
- ❑ In the case of a short circuit with a wire; the wire itself possesses an inductance that can be of substantial magnitude at high frequency.
- ❑ Also open circuit leads to capacitive loading at the terminal.



- ❑ In either case, the open/short-circuit conditions needed to determine Z-, Y-, h-, and ABCD-parameters can no longer be guaranteed.
- ❑ Moreover, when dealing with wave propagation phenomena, it is not desirable to introduce a reflection coefficient whose magnitude is unity.
- ❑ For instance, the terminal discontinuity will cause undesirable voltage and/or current wave reflections, leading to oscillation that can result in the destruction of the device.
- ❑ With S-parameters, one has proper tool to characterize the two-port network description of practically all RF devices without harm to DUT.



- S-parameters are power wave descriptors that permit us to define the input-output relations of a network in terms of incident and reflected power waves.



$a_n$  – normalized incident power waves

$b_n$  – normalized reflected power waves



$$a_n = \frac{1}{2\sqrt{Z_0}} (V_n + Z_0 I_n) \quad (1)$$

$$b_n = \frac{1}{2\sqrt{Z_0}} (V_n - Z_0 I_n) \quad (2)$$

□ Index  $n$  refers either to port number 1 or 2. The impedance  $Z_0$  is the characteristic impedance of the connecting lines on the input and output side of the network.



- Inverting (1) leads to the following voltage and current expressions:

$$V_n = \sqrt{Z_o} (a_n + b_n) \quad (3)$$

$$I_n = \frac{1}{\sqrt{Z_o}} (a_n - b_n) \quad (4)$$



- Recall the equations for power:

$$P_n = \frac{1}{2} \operatorname{Re} \left\{ V_n I_n^* \right\} = \frac{1}{2} \left( |a_n|^2 - |b_n|^2 \right) \quad (5)$$

- Isolating forward and backward traveling wave components in (3) and (4), we see

$$a_n = \frac{V_n^+}{\sqrt{Z_0}} = \sqrt{Z_0} I_n^+ \quad (6)$$

$$b_n = \frac{V_n^-}{\sqrt{Z_0}} = -\sqrt{Z_0} I_n^- \quad (7)$$



□ We can now define S-parameters:

$$\begin{Bmatrix} b_1 \\ b_2 \end{Bmatrix} = \begin{bmatrix} S_{11} & S_{12} \\ S_{21} & S_{22} \end{bmatrix} \begin{Bmatrix} a_1 \\ a_2 \end{Bmatrix} \quad (8)$$



$$S_{11} = \left. \frac{b_1}{a_1} \right|_{a_2=0} = \frac{\text{Reflected power wave at port 1}}{\text{Incident power wave at port 2}} \quad (9)$$

$$S_{21} = \left. \frac{b_2}{a_1} \right|_{a_2=0} = \frac{\text{Transmitted power wave at port 2}}{\text{Incident power wave at port 1}} \quad (10)$$

$$S_{22} = \left. \frac{b_2}{a_2} \right|_{a_1=0} = \frac{\text{Reflected power wave at port 2}}{\text{Incident power wave at port 2}} \quad (11)$$

$$S_{12} = \left. \frac{b_1}{a_2} \right|_{a_1=0} = \frac{\text{Transmitted power wave at port 1}}{\text{Incident power wave at port 2}} \quad (12)$$



- $a_2=0$ , and  $a_1=0 \Rightarrow$  no power waves are returned to the network at either port 2 or port 1.
- However, these conditions can only be ensured when the connecting transmission line are terminated into their characteristic impedances.
- Since the S-parameters are closely related to power relations, we can express the normalized input and output waves in terms of time averaged power.
- The average power at port 1 is given by

$$P_1 = \frac{1}{2} \frac{|V_1^+|^2}{Z_o} \left(1 - |\Gamma_{in}|^2\right) = \frac{1}{2} \frac{|V_1^+|^2}{Z_o} \left(1 - |S_{11}|^2\right) \quad (13)$$



- The reflection coefficient at the input side is expressed in terms of  $S_{11}$  under matched output according:

$$\Gamma_{in} = \frac{V_1^-}{V_1^+} = \frac{b_1}{a_1} \Big|_{a_2=0} = S_{11} \quad (14)$$

- This also allow us to redefine the VSWR at port 1 in terms of  $S_{11}$  as

$$VSWR = \frac{1 + |S_{11}|}{1 - |S_{11}|} \quad (15)$$



- We can identify the incident power in (13) and express it in terms of  $a_1$ :

$$\frac{1}{2} \frac{|V_1^+|^2}{Z_o} = P_{inc} = \frac{|a_1|^2}{2} \quad (16)$$

Maximal available power from the generator

- The total power at port 1 (under matched output condition) expressed as a combination of incident and reflected powers:

$$P_1 = P_{inc} + P_{refl} = \frac{1}{2} (|a_1|^2 - |b_1|^2) = \frac{|a_1|^2}{2} (1 - |\Gamma_{in}|^2) \quad (17)$$

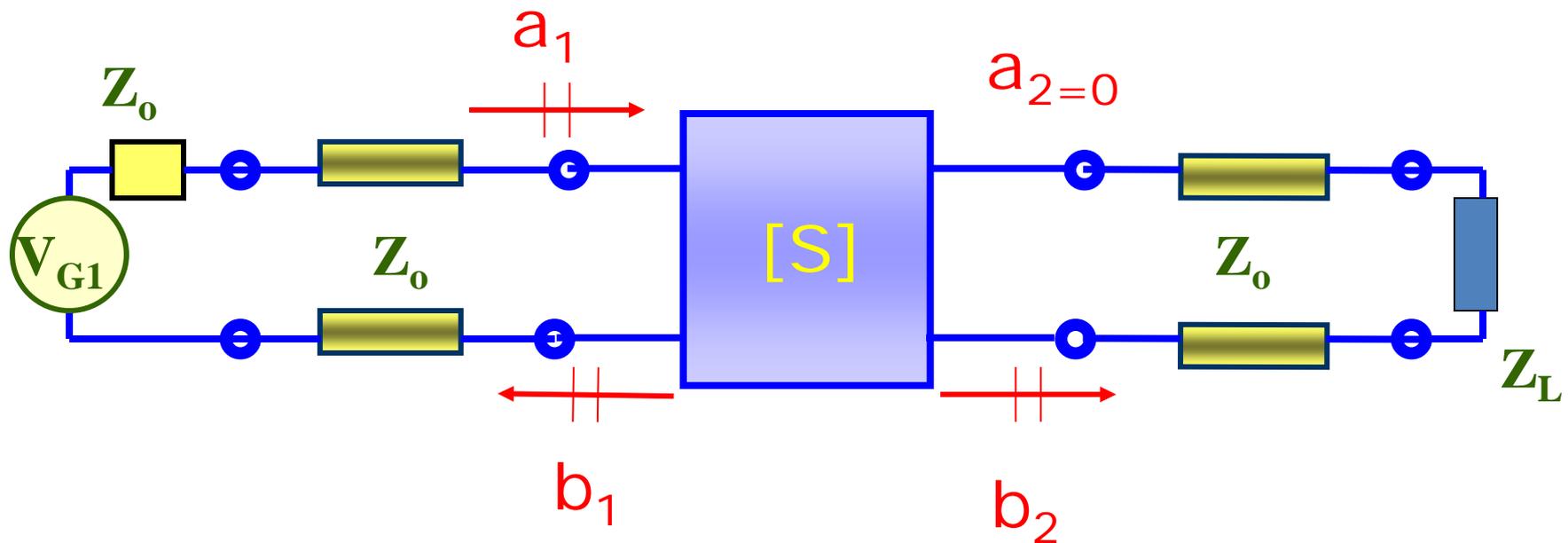


□ If the reflected coefficient, or  $S_{11}$ , is zero, all available power from the source is delivered to port 1 of the network. An identical analysis at port 2 gives

$$P_2 = \frac{1}{2} \left( |a_2|^2 - |b_2|^2 \right) = \frac{|a_2|^2}{2} \left( 1 - |\Gamma_{out}|^2 \right) \quad (18)$$



- S-parameters can only be determined under conditions of perfect matching on the input or the output side.



Measurement of  $S_{11}$  and  $S_{21}$  by matching the line impedance  $Z_0$  at port 2 through a corresponding load impedance  $Z_L = Z_0$ .



□ This configuration allows us to compute  $S_{11}$  by finding the input reflection coefficient:

$$S_{11} = \Gamma_{in} = \frac{Z_{in} - Z_o}{Z_{in} + Z_o} \quad (19)$$

□ Taking the logarithm of the magnitude of  $S_{11}$  gives us the return loss in dB

$$RL = -20 \log |S_{11}| \quad (20)$$



□ With port 2 properly terminated, we find

$$S_{21} = \left. \frac{b_2}{a_1} \right|_{a_2=0} = \frac{V_2^- / \sqrt{Z_o}}{(V_1 + Z_o I_1) / (2\sqrt{Z_o})} \Big|_{I_2^+ = V_2^+ = 0} \quad (21)$$

□ Since  $a_2=0$ , we can set to zero the positive traveling voltage and current waves at port 2.

□ Replacing  $V_1$  by the generator voltage  $V_{G1}$  minus the voltage drop over the source impedance  $Z_o$ ,  $V_{G1} - Z_o I_1$  gives

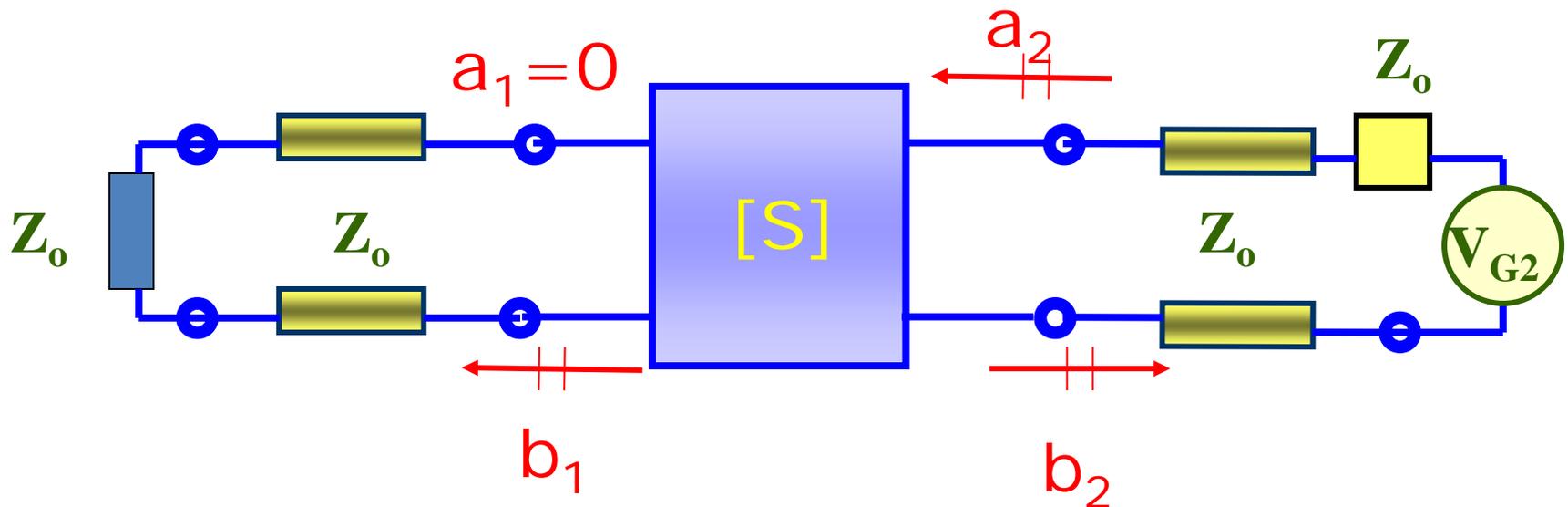
$$S_{21} = \frac{2V_2^-}{V_{G1}} = \frac{2V_2}{V_{G1}} \quad (22)$$



□ The forward power gain is

$$G_o = |S_{21}|^2 = \left| \frac{V_2}{V_{G1}/2} \right|^2 \quad (23)$$

□ If we reverse the measurement procedure and attach a generator voltage  $V_{G2}$  to port 2 and properly terminate port 1, we can determine the remaining two S-parameters,  $S_{22}$  and  $S_{12}$ .





□ To compute  $S_{22}$  we need to find the output reflection coefficient  $\Gamma_{out}$  in a similar way for  $S_{11}$ :

$$S_{22} = \Gamma_{out} = \frac{Z_{out} - Z_o}{Z_{out} + Z_o} \quad (24)$$

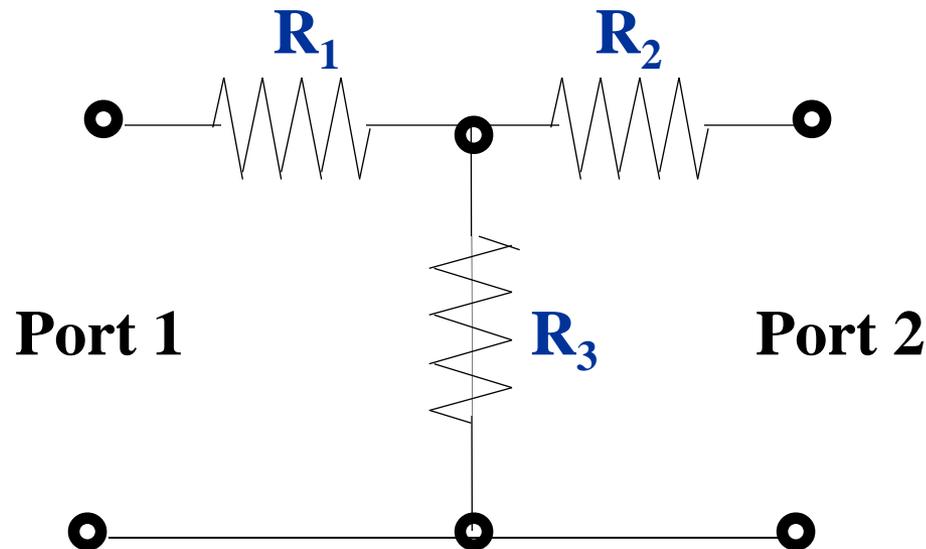
$$S_{12} = \left. \frac{b_1}{a_2} \right|_{a_1=0} = \left. \frac{V_1^- / \sqrt{Z_o}}{(V_2 + Z_o I_2) / (2\sqrt{Z_o})} \right|_{I_1^+ = V_1^+ = 0} \quad (25)$$

$$S_{12} = \frac{2V_1^-}{V_{G2}} = \frac{2V_1}{V_{G2}} \quad (26) \quad G_{or} = |S_{12}|^2 = \left| \frac{V_1}{V_{G2}/2} \right|^2 \quad (27)$$

Reverse power gain

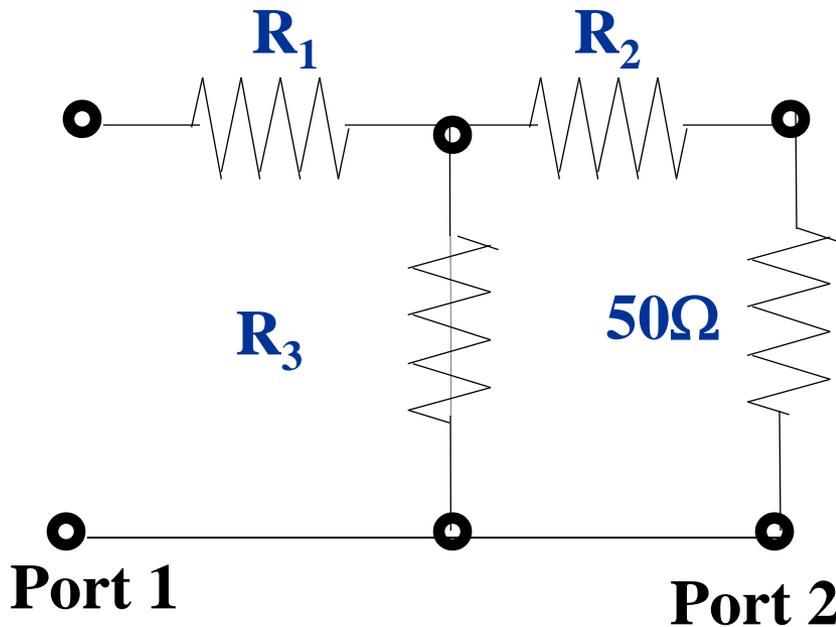


Find the S-parameters and resistive elements for the 3-dB attenuator network. Assume that the network is placed into a transmission line section with a characteristic line impedance of  $Z_0=50 \Omega$





An attenuator should be matched to the line impedance and must meet the requirement  $S_{11} = S_{22} = 0$ .

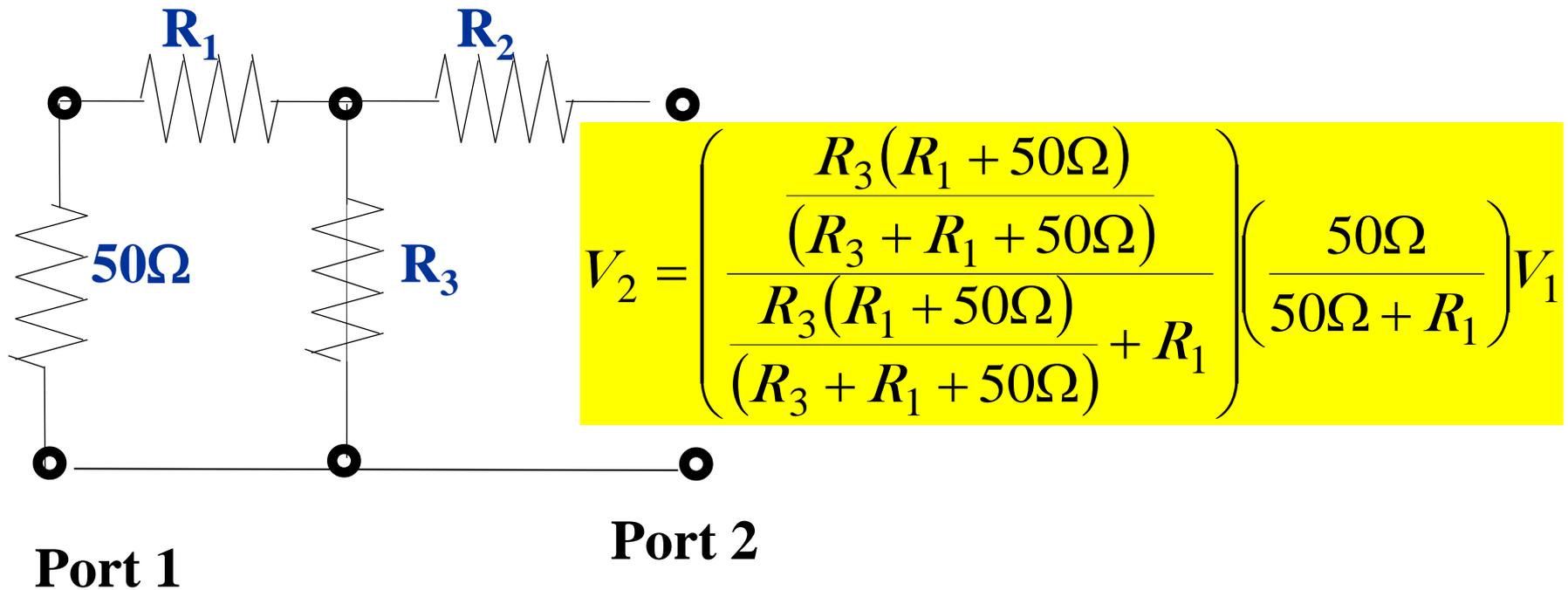


Circuit for  $S_{11}$  and  $S_{21}$

$$Z_{in} = R_1 + \frac{R_3(R_2 + 50\Omega)}{(R_3 + R_2 + 50\Omega)} = 50\Omega$$

Because of symmetry, it is clear that  $R_1 = R_2$ .

We now investigate the voltage  $V_2 = V^-_2$  at port 2 in terms of  $V_1 = V^+_1$ .





**For a 3 dB attenuation, we require**

$$S_{21} = \frac{2V_2}{V_{G1}} = \frac{V_2}{V_1} = \frac{1}{\sqrt{2}} = 0.707 = S_{12}$$

**Setting the ratio of  $V_2/V_1$  to 0.707 and using the input impedance expression, we can determine  $R_1$  and  $R_3$**

$$R_1 = R_2 = \frac{\sqrt{2}-1}{\sqrt{2}+1} Z_o = 8.58\Omega$$

$$R_3 = 2\sqrt{2}Z_o = 141.4\Omega$$



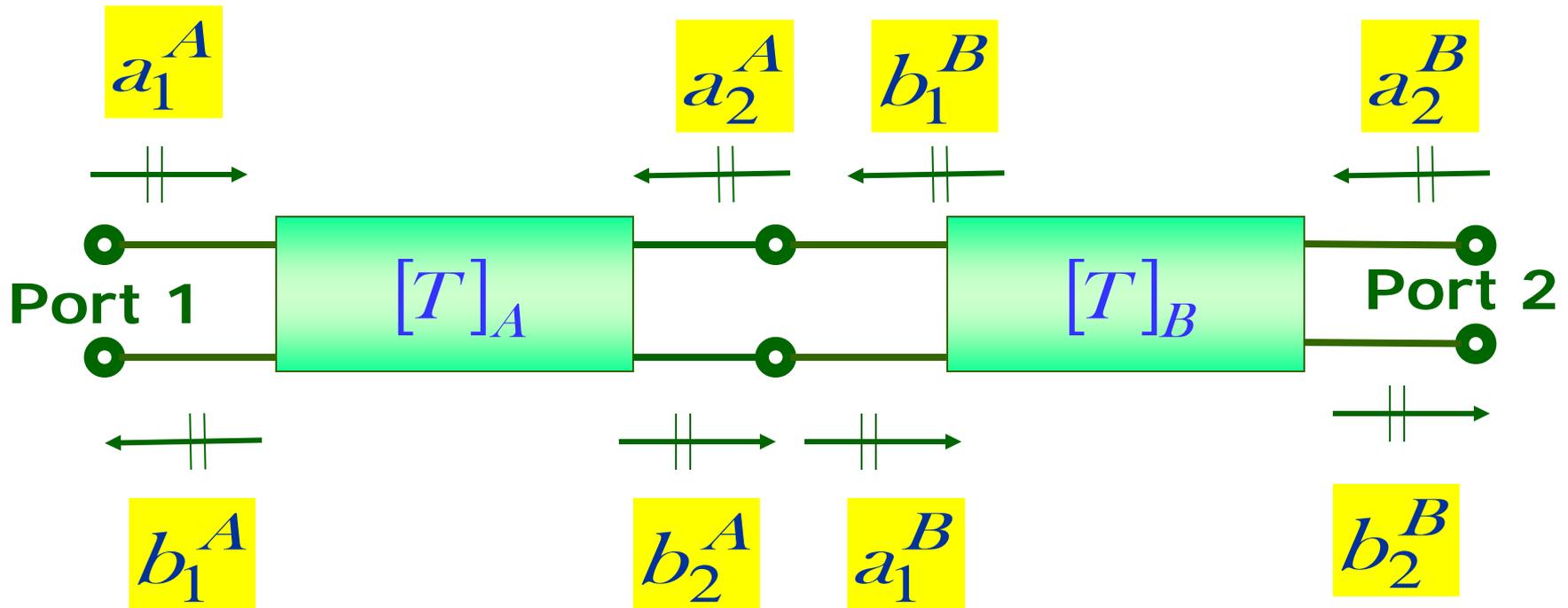
**Note:** *the choice of the resistor network ensures that at the input and output ports an impedance of  $50 \Omega$  is maintained. This implies that this network can be inserted into a  $50 \Omega$  transmission line section without causing undesired reflections, resulting in an insertion loss.*



□ To extend the concept of the S-parameter presentation to cascaded network, it is more efficient to rewrite the power wave expressions arranged in terms of input and output ports. This results in the chain scattering matrix notation. That is,

$$\begin{Bmatrix} a_1 \\ b_1 \end{Bmatrix} = \begin{bmatrix} T_{11} & T_{12} \\ T_{21} & T_{22} \end{bmatrix} \begin{Bmatrix} b_2 \\ a_2 \end{Bmatrix} \quad (28)$$

□ It is immediately seen that cascading of two dual-port networks becomes a simple multiplication.



## Cascading of two networks A and B



If network A is described by

$$\begin{Bmatrix} a_1^A \\ b_1^A \end{Bmatrix} = \begin{bmatrix} T_{11}^A & T_{12}^A \\ T_{21}^A & T_{22}^A \end{bmatrix} \begin{Bmatrix} b_2^A \\ a_2^A \end{Bmatrix} \quad (29)$$

And network B by

$$\begin{Bmatrix} a_1^B \\ b_1^B \end{Bmatrix} = \begin{bmatrix} T_{11}^B & T_{12}^B \\ T_{21}^B & T_{22}^B \end{bmatrix} \begin{Bmatrix} b_2^B \\ a_2^B \end{Bmatrix} \quad (30)$$



$$\begin{Bmatrix} b_2^A \\ a_2^A \end{Bmatrix} = \begin{Bmatrix} a_1^B \\ b_1^B \end{Bmatrix} \quad (31)$$

Thus, for the combined system, we conclude

$$\begin{Bmatrix} a_1^A \\ b_1^A \end{Bmatrix} = \begin{bmatrix} T_{11}^A & T_{12}^A \\ T_{21}^A & T_{22}^A \end{bmatrix} \begin{bmatrix} T_{11}^B & T_{12}^B \\ T_{21}^B & T_{22}^B \end{bmatrix} \begin{Bmatrix} b_2^B \\ a_2^B \end{Bmatrix} \quad (31)$$



The conversion from S-matrix to the chain matrix notation is similar as described before.

$$T_{11} = \left. \frac{a_1}{b_2} \right|_{a_2=0} = \frac{a_1}{S_{21}a_1} = \frac{1}{S_{21}} \quad (32)$$

$$T_{12} = -\frac{S_{22}}{S_{21}} \quad (33)$$

$$T_{21} = \frac{S_{11}}{S_{21}} \quad (34)$$

$$T_{22} = \frac{-(S_{11}S_{22} - S_{12}S_{21})}{S_{21}} = \frac{-\Delta S}{S_{21}} \quad (35)$$



Conversely, when the chain scattering parameters are given and we need to convert to S-parameters, we find the following relations:

$$S_{11} = \left. \frac{b_1}{a_2} \right|_{a_2=0} = \frac{T_{21}b_2}{T_{11}b_2} = \frac{T_{21}}{T_{11}} \quad (36)$$

$$S_{12} = \frac{(T_{11}T_{22} - T_{12}T_{21})}{T_{11}} = \frac{\Delta T}{T_{11}} \quad (37)$$

$$S_{21} = \frac{1}{T_{11}} \quad (38)$$

$$S_{22} = -\frac{T_{12}}{T_{11}} \quad (39)$$



To find the conversion between the S-parameters and the Z-parameters, let us begin with defining S-parameters relation in matrix notation

$$\{b\} = [S]\{a\} \quad (40)$$

Multiplying by  $\sqrt{Z_0}$  gives

$$\sqrt{Z_0}\{b\} = \{V^-\} = \sqrt{Z_0}[S]\{a\} = [S]\{V^+\} \quad (41)$$

Adding  $\{V^+\} = \sqrt{Z_0}\{a\}$  to both sides results in

$$\{V\} = [S]\{V^+\} + \{V^+\} = ([S] + [E])\{V^+\} \quad (42)$$



To compare this form with the impedance expression

$$\{V\} = [Z]\{I\}$$

We have to express  $\{V^+\}$  in term of  $\{I\}$ . Subtract  $[S]\{V^+\}$  from both sides of

$$\{V^+\} = \sqrt{Z_0} \{a\}$$

$$\{V^+\} - [S]\{V^+\} = \sqrt{Z_0} (\{a\} - \{b\}) = Z_0 \{I\} \quad (43)$$

$$\{V^+\} = Z_0 ([E] - [S])^{-1} \{I\} \quad (44)$$



Substituting (44) into (42) yields

$$\{V\} = ([S] + [E])\{V^+\} = Z_o ([S] + [E])([E] - [S])^{-1}\{I\} \quad (45)$$

or

$$[Z] = Z_o ([S] + [E])([E] - [S])^{-1} \quad (46)$$

Explicitly

$$\begin{aligned} \begin{bmatrix} Z_{11} & Z_{12} \\ Z_{21} & Z_{22} \end{bmatrix} &= Z_o \begin{bmatrix} 1 + S_{11} & S_{12} \\ S_{21} & 1 + S_{22} \end{bmatrix} \begin{bmatrix} 1 - S_{11} & -S_{12} \\ -S_{21} & 1 - S_{22} \end{bmatrix}^{-1} \\ &= \frac{Z_o \begin{bmatrix} 1 + S_{11} & S_{12} \\ S_{21} & 1 + S_{22} \end{bmatrix}}{(1 - S_{11})(1 - S_{22}) - S_{21}S_{12}} \begin{bmatrix} 1 - S_{22} & S_{12} \\ S_{21} & 1 - S_{11} \end{bmatrix} \quad (47) \end{aligned}$$

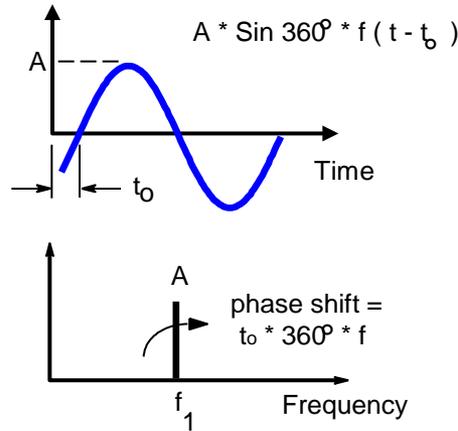
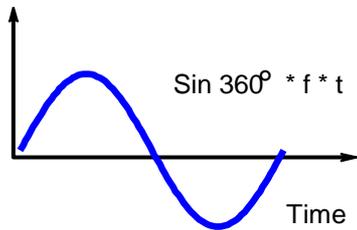


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# Practical Network Analysis



# Linear Versus Nonlinear Behavior



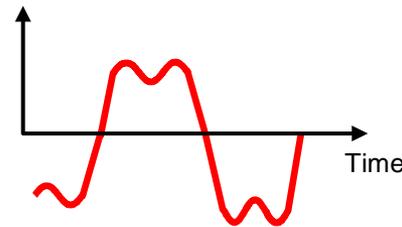
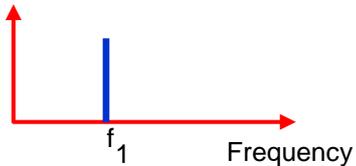
## **Linear behavior:**

- input and output frequencies are the same (no additional frequencies created)
- output frequency only undergoes magnitude and phase change

Input

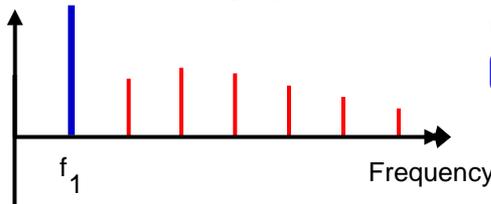


Output



## **Nonlinear behavior:**

- output frequency may undergo frequency shift (e.g. with mixers)
- additional frequencies created (harmonics, inter-modulation)

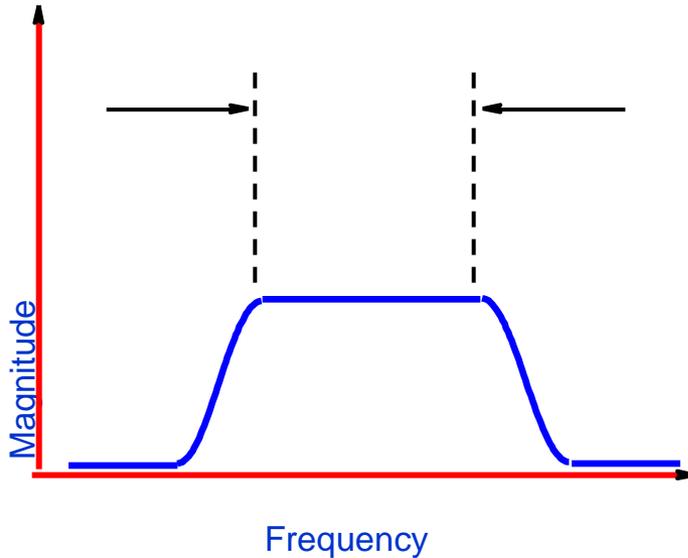




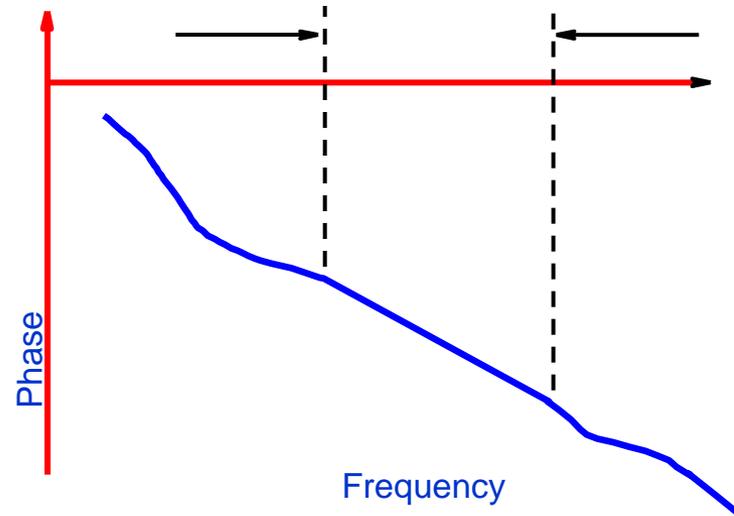
# Criteria for Distortionless Transmission

## *Linear Networks*

*Constant amplitude over bandwidth of interest*



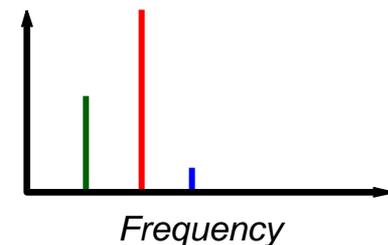
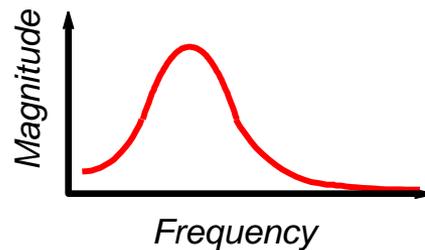
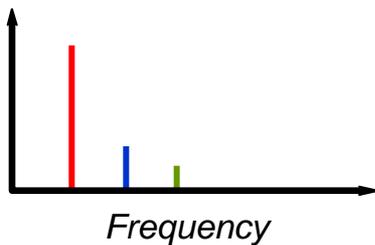
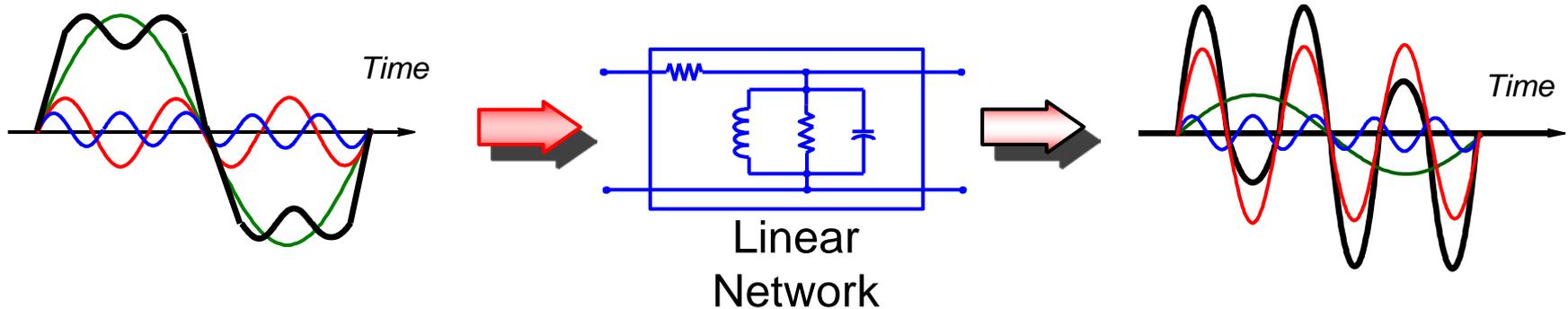
*Linear phase over bandwidth of interest*





# Magnitude Variation with Frequency

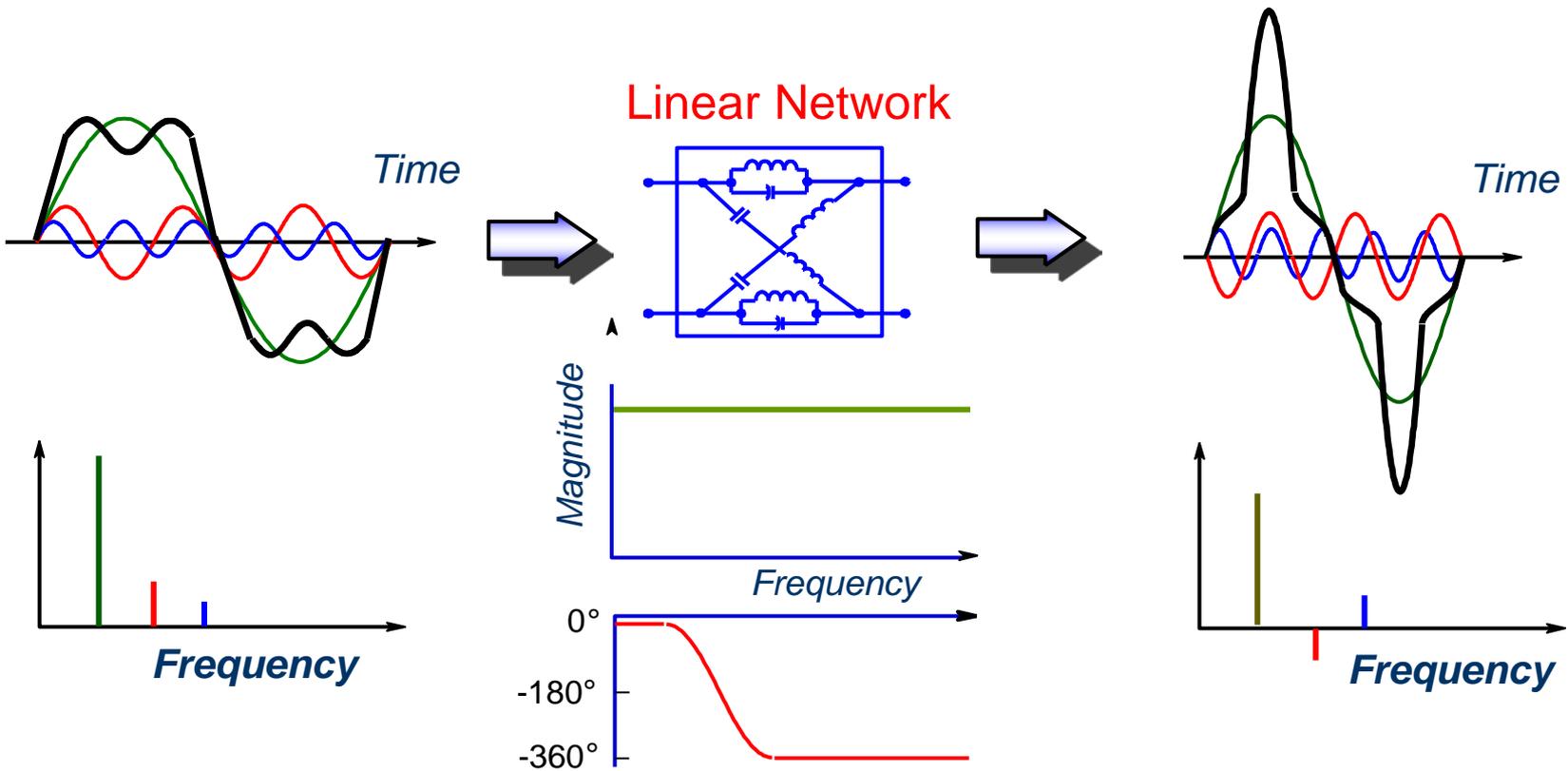
$$f(t) = \sin \omega t + \frac{1}{3} \sin 3\omega t + \frac{1}{5} \sin 5\omega t$$





# Phase Variation with Frequency

$$f(t) = \sin \omega t + \frac{1}{3} \sin 3\omega t + \frac{1}{5} \sin 5\omega t$$

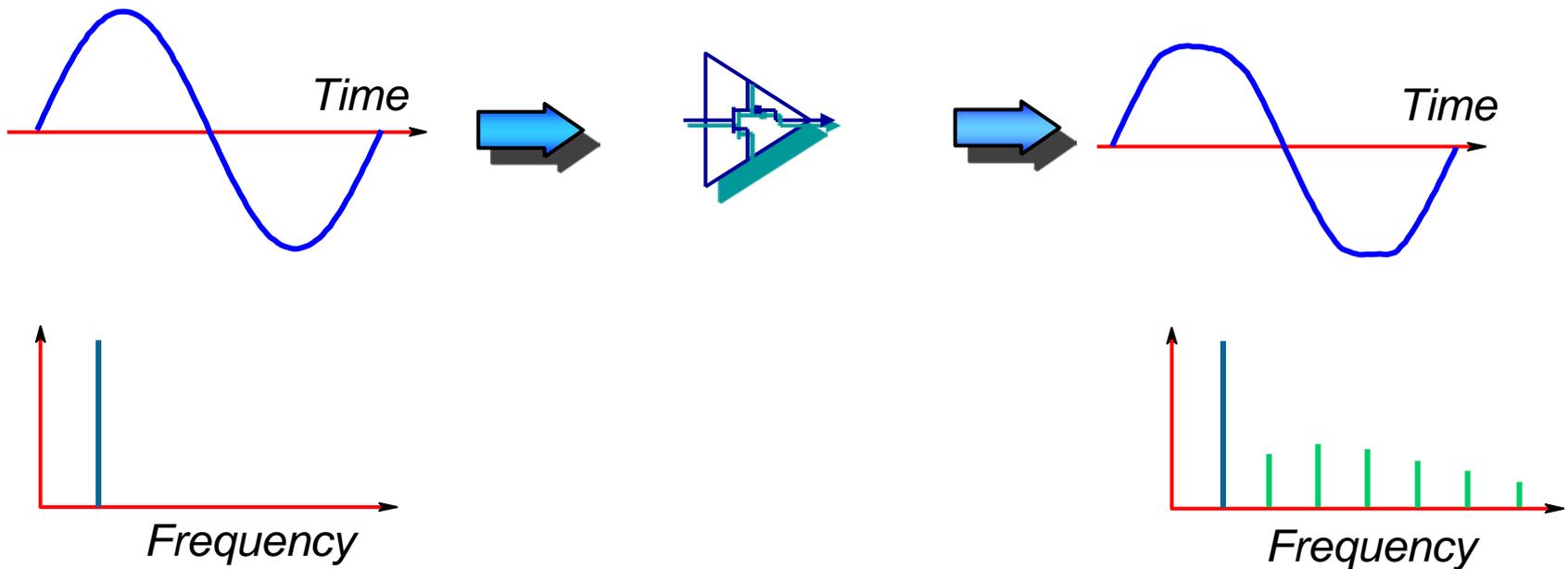




# Criteria for Distortionless Transmission

## ***Nonlinear Networks***

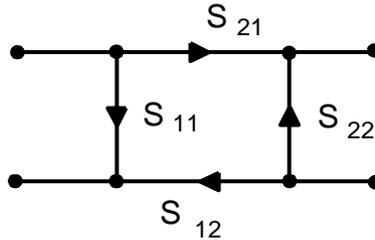
Saturation, crossover, inter-modulation, and other nonlinear effects can cause signal distortion





# The Need for Both Magnitude and Phase

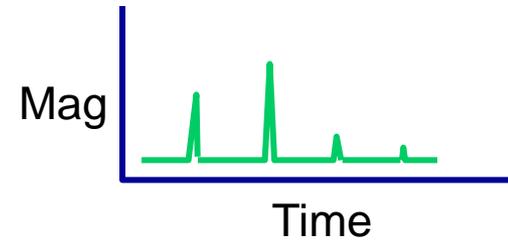
1. Complete characterization of linear networks



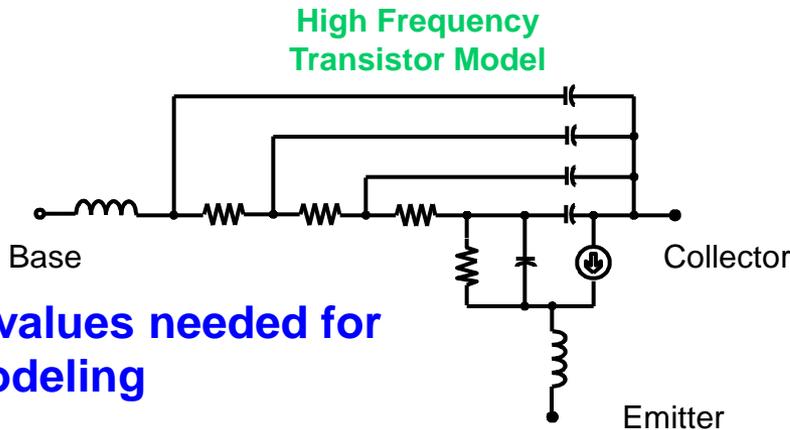
2. Complex impedance needed to design matching circuits



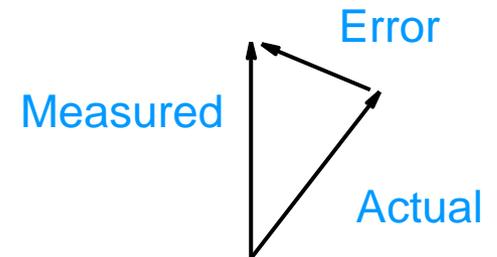
4. Time Domain Characterization



3. Complex values needed for device modeling



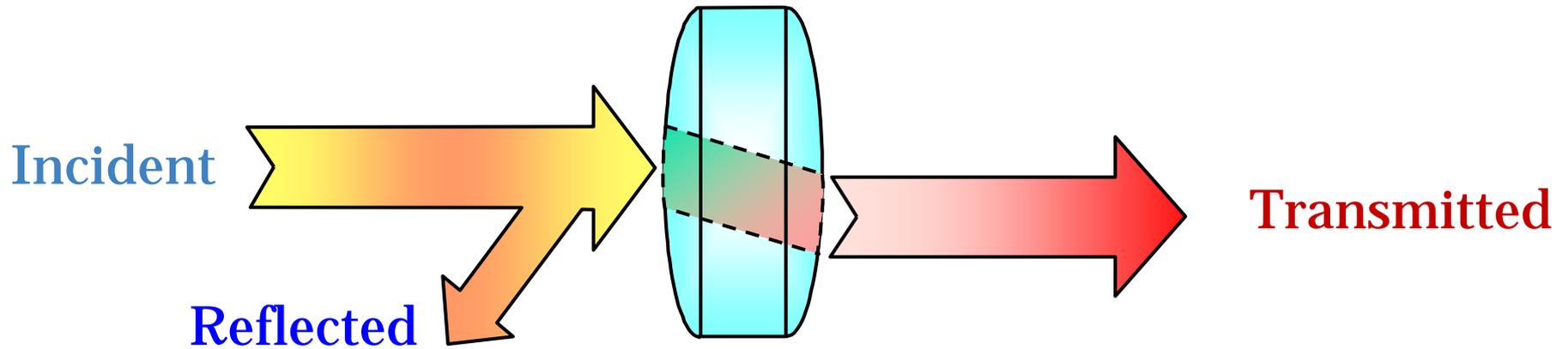
5. Vector Accuracy Enhancement





# High-Frequency Device Characterization

## *Lightwave Analogy*



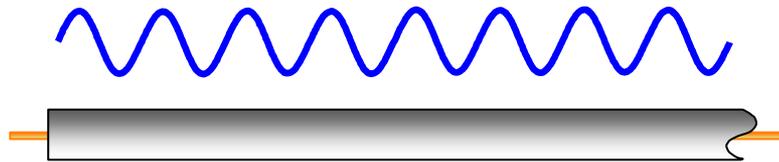


# Transmission Line Review

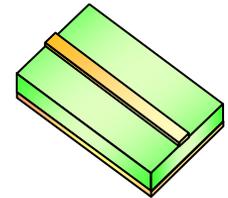
## Low Frequencies



- Wavelength  $\gg$  wire length
- Current (I) travels down wires easily for efficient power transmission
- Voltage and current not dependent on position



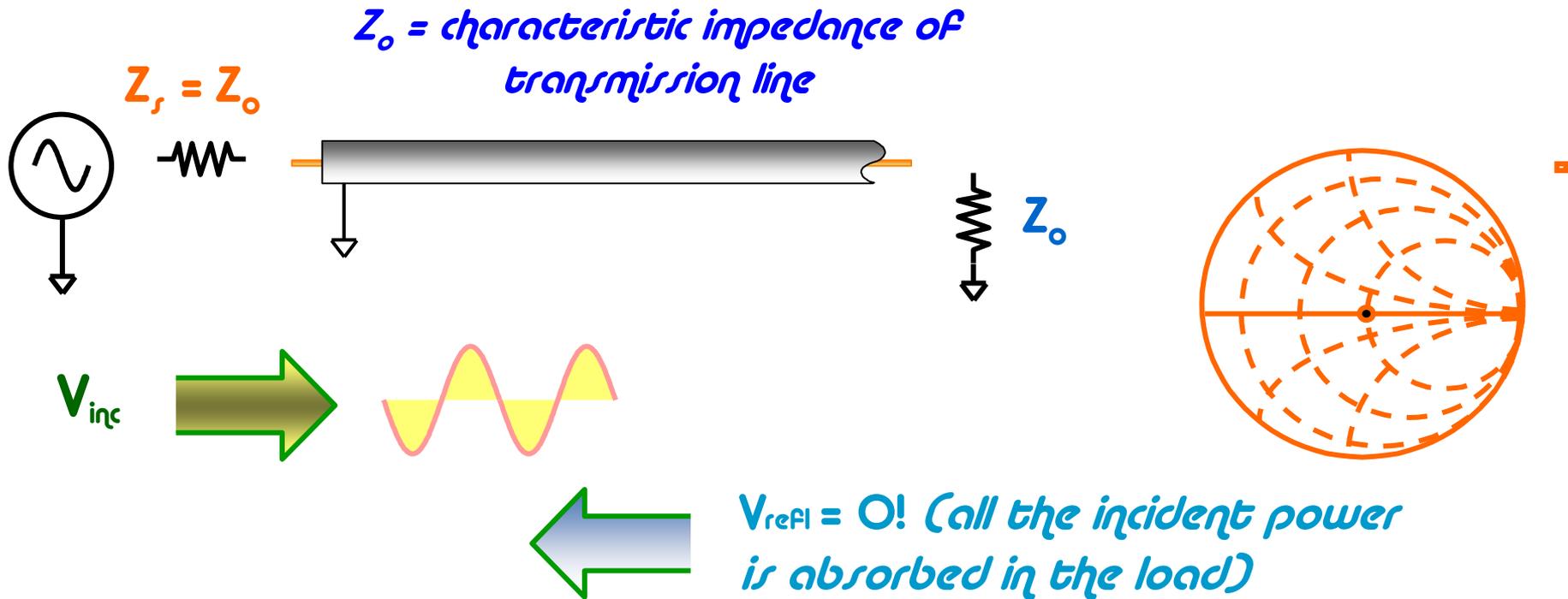
## High Frequencies



- Wavelength  $\approx$  or  $\ll$  wire (transmission line) length
- Need transmission-line structures for efficient power transmission
- Matching to characteristic impedance ( $Z_0$ ) is very important for low reflection
- Voltage dependent on position along line



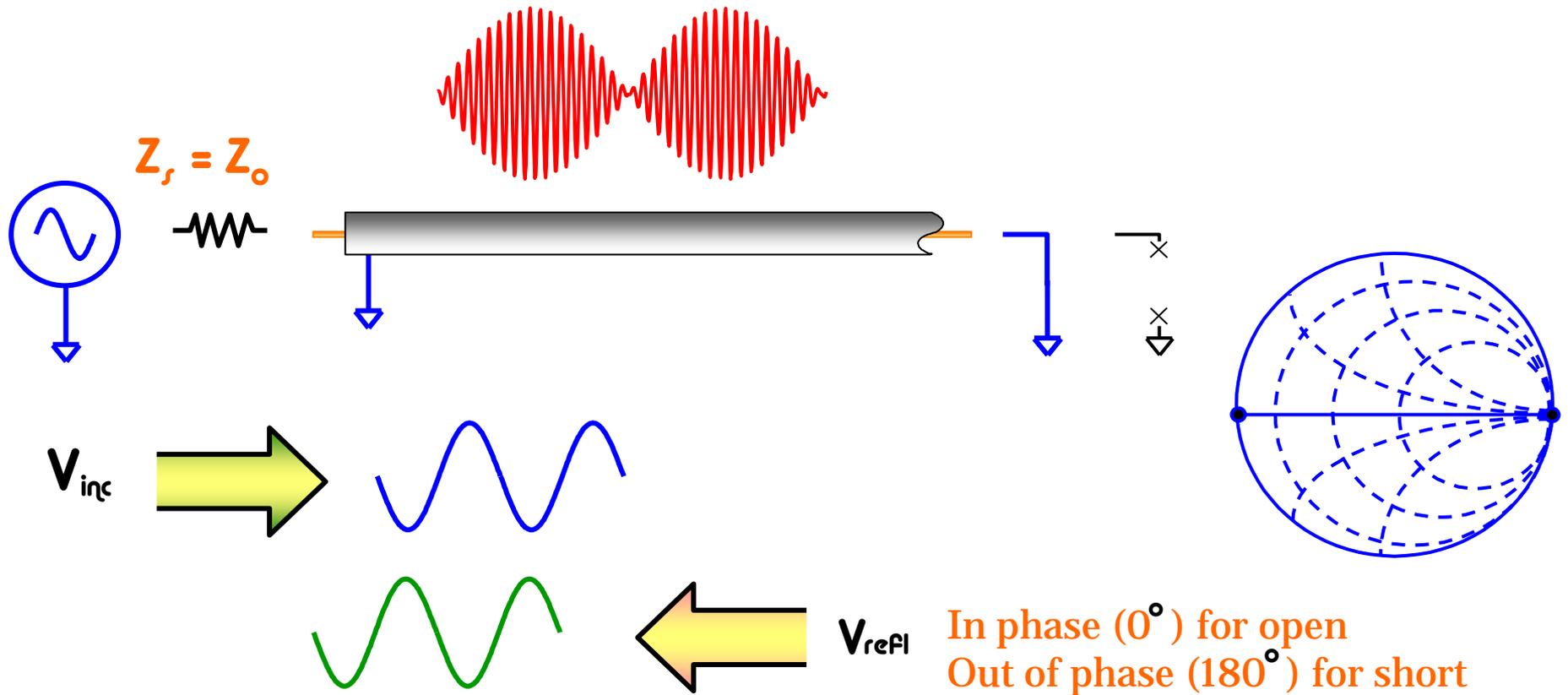
# Transmission Line Terminated with $Z_0$



For reflection, a transmission line terminated in  $Z_0$  behaves like an infinitely long transmission line



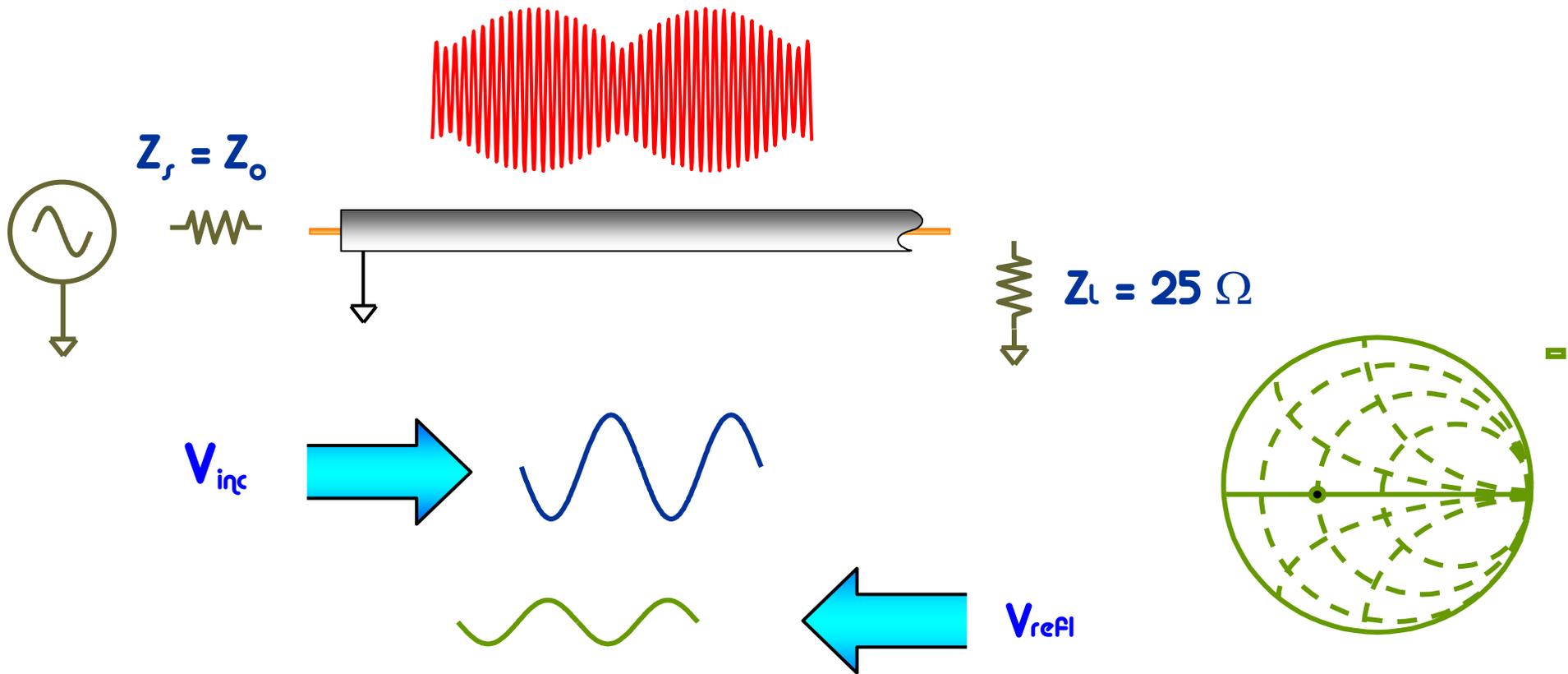
# Transmission Line Terminated with Short, Open



For reflection, a transmission line terminated in a short or open reflects all power back to source



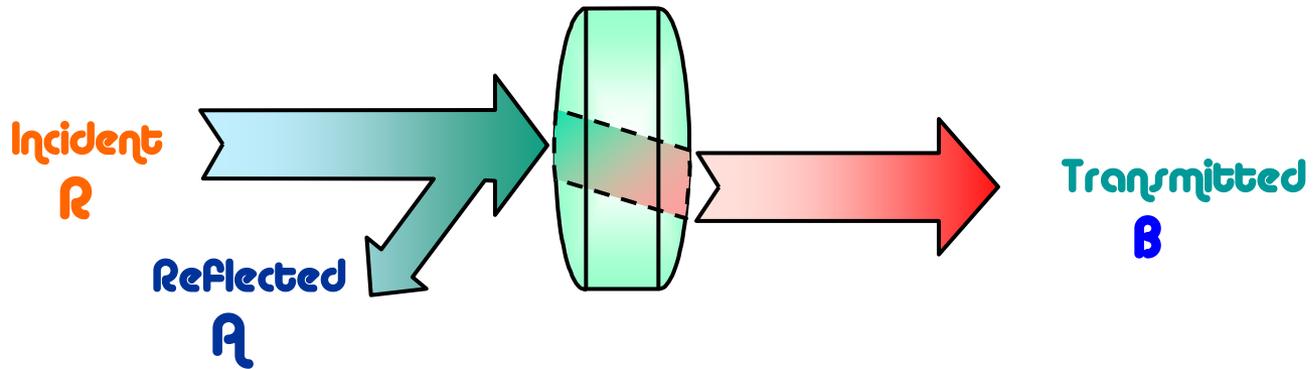
# Transmission Line Terminated with $25\Omega$



Standing wave pattern does not go to zero as with short or open



# High-Frequency Device Characterization



## REFLECTION

$$\frac{\text{Reflected}}{\text{Incident}} = \frac{A}{R}$$

- SWR
- S-Parameters  $S_{11}, S_{22}$
- Reflection Coefficient  $\Gamma, \rho$
- Impedance, Admittance  $R+jX, G+jB$
- Return Loss

## TRANSMISSION

$$\frac{\text{Transmitted}}{\text{Incident}} = \frac{B}{R}$$

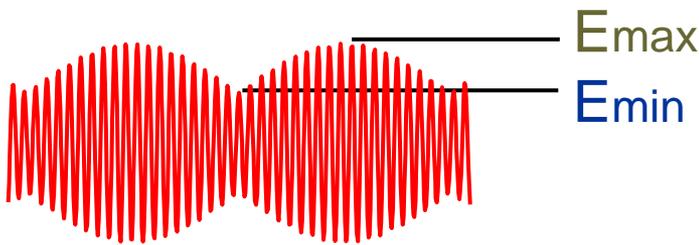
- Gain / Loss
- S-Parameters  $S_{21}, S_{12}$
- Transmission Coefficient  $T, \tau$
- Insertion Phase
- Group Delay



# Reflection Parameters

**Reflection Coefficient**  $\Gamma = \frac{V_{\text{reflected}}}{V_{\text{incident}}} = \rho \angle \Phi = \frac{Z_L - Z_0}{Z_L + Z_0}$

**Return loss** =  $-20 \log(\rho)$ ,  $\rho = |\Gamma|$



*Voltage Standing Wave Ratio*

**VSWR** =  $\frac{E_{\text{max}}}{E_{\text{min}}} = \frac{1 + \rho}{1 - \rho}$

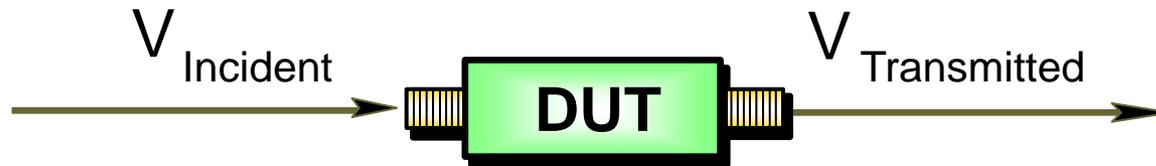
**No reflection**  
( $Z_L = Z_0$ )

**Full reflection**  
( $Z_L = \text{open, short}$ )

0	$\rho$	1
$\infty$ dB	RL	0 dB
1	VSWR	$\infty$



# Transmission Parameters



$$\text{Transmission Coefficient } \mathbb{T} = \frac{V_{\text{Transmitted}}}{V_{\text{Incident}}} = \tau \angle \phi$$

$$\text{Insertion Loss (dB)} = -20 \text{ Log} \left| \frac{V_{\text{Trans}}}{V_{\text{Inc}}} \right| = -20 \log \tau$$

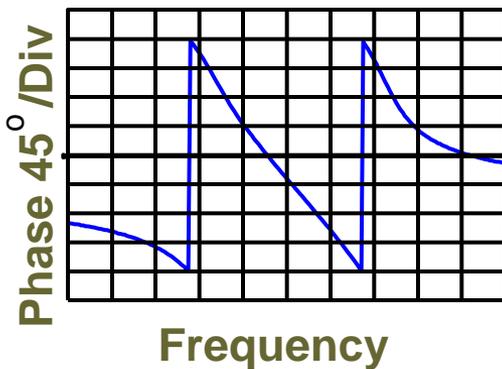
$$\text{Gain (dB)} = 20 \text{ Log} \left| \frac{V_{\text{Trans}}}{V_{\text{Inc}}} \right| = 20 \log \tau$$



# Deviation from Linear Phase

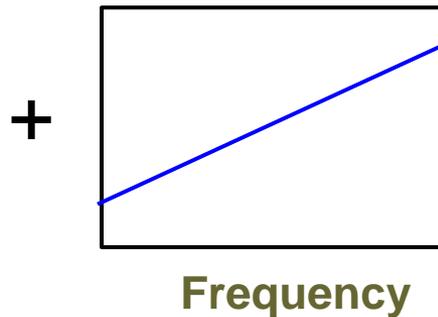
*Use electrical delay to remove linear portion of phase response*

RF filter response



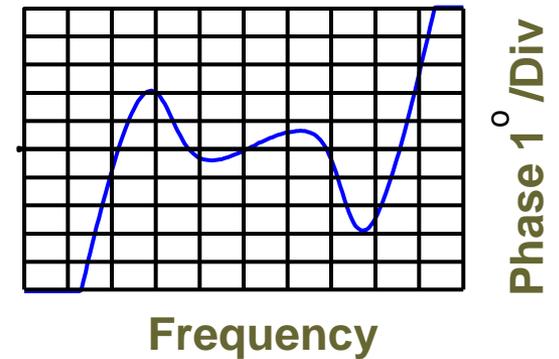
**Low resolution**

Linear electrical length added  
(Electrical delay function)



yields

Deviation from linear phase



**High resolution**



# Low-Frequency Network Characterization

## H-parameters

$$V_1 = h_{11}I_1 + h_{12}V_2$$

$$V_2 = h_{21}I_1 + h_{22}V_2$$

## Y-parameters

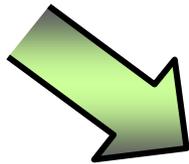
$$I_1 = y_{11}V_1 + y_{12}V_2$$

$$I_2 = y_{21}V_1 + y_{22}V_2$$

## Z-parameters

$$V_1 = Z_{11}I_1 + Z_{12}I_2$$

$$V_2 = Z_{21}I_1 + Z_{22}I_2$$



$$h_{11} = \left. \frac{V_1}{I_1} \right|_{V_2=0}$$

**(requires short circuit)**

$$h_{12} = \left. \frac{V_1}{V_2} \right|_{I_1=0}$$

**(requires open circuit)**

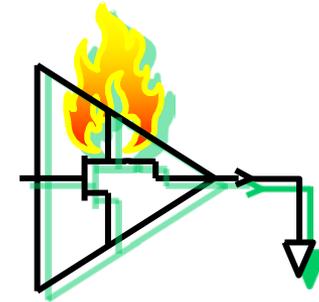
***All of these parameters require measuring voltage and current (as a function of frequency)***



# Limitations of H, Y, Z Parameters (Why use S-parameters?)

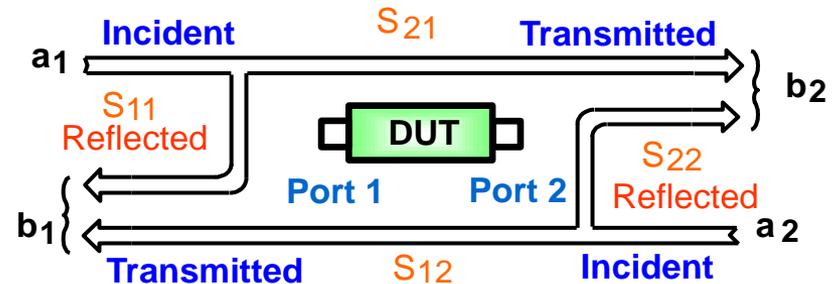
## H, Y, Z parameters

- Hard to measure total voltage and current at device ports at high frequencies
- Active devices may oscillate or self-destruct with shorts or opens



## S-parameters

- Relate to familiar measurements (gain, loss, reflection coefficient ...)
- Relatively easy to measure
- Can cascade S-parameters of multiple devices to predict system performance
- Analytically convenient
  - CAD programs
  - Flow-graph analysis
- Can compute H, Y, or Z parameters from S-parameters if desired



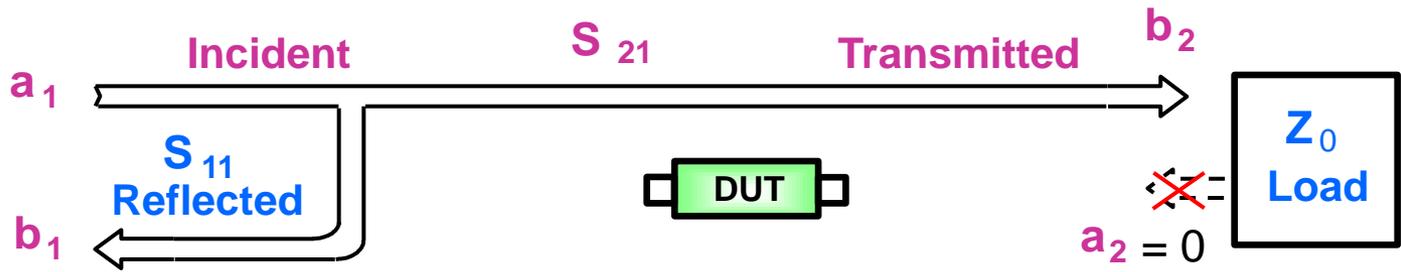
$$b_1 = S_{11} a_1 + S_{12} a_2$$

$$b_2 = S_{21} a_1 + S_{22} a_2$$



# Measuring S-Parameters

**Forward**

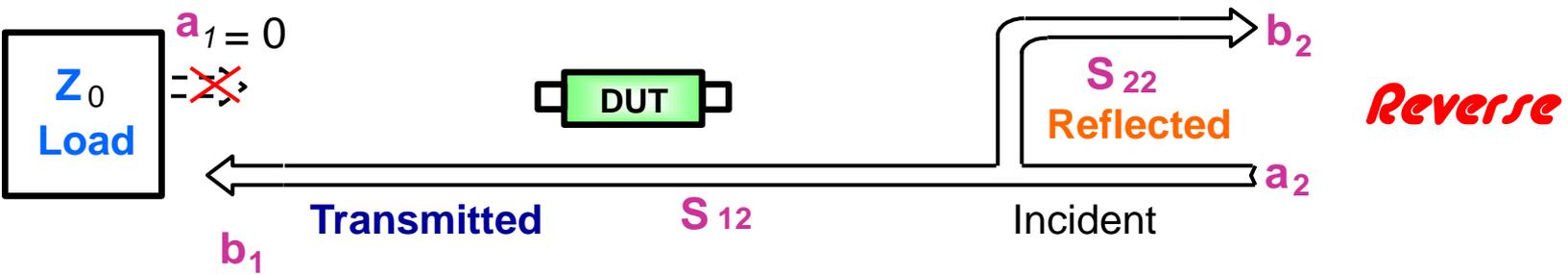


$$S_{11} = \frac{\text{Reflected}}{\text{Incident}} = \frac{b_1}{a_1} \Big|_{a_2 = 0}$$

$$S_{21} = \frac{\text{Transmitted}}{\text{Incident}} = \frac{b_2}{a_1} \Big|_{a_2 = 0}$$

$$S_{22} = \frac{\text{Reflected}}{\text{Incident}} = \frac{b_2}{a_2} \Big|_{a_1 = 0}$$

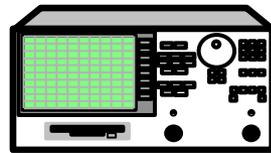
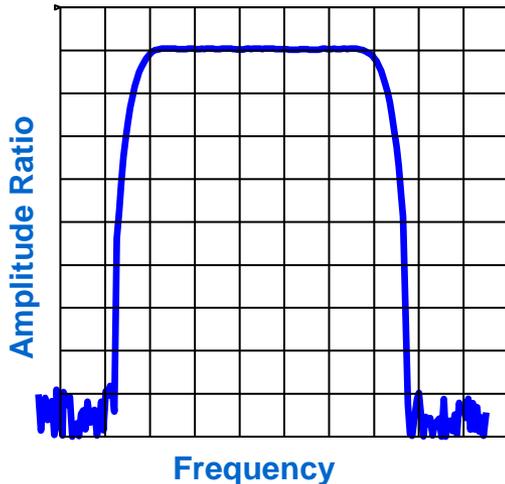
$$S_{12} = \frac{\text{Transmitted}}{\text{Incident}} = \frac{b_1}{a_2} \Big|_{a_1 = 0}$$





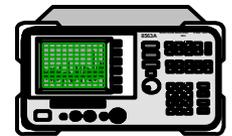
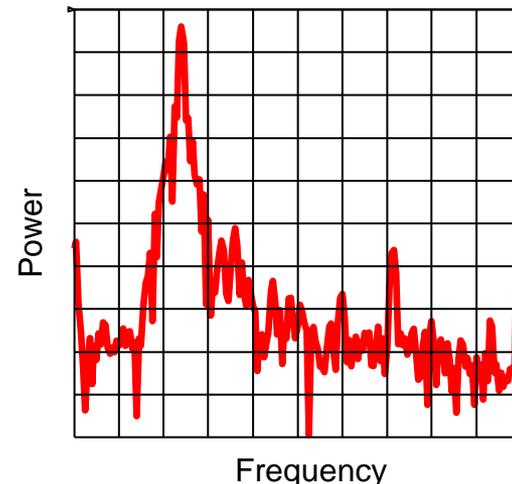
# What is the difference between *network* and *spectrum* analyzers?

*Hard: getting (accurate) trace*  
*Easy: interpreting results*



Measures  
known signal

*Easy: getting trace*  
*Hard: interpreting results*



Measures  
unknown  
signals

## Network analyzers:

- measure components, devices, circuits, sub-assemblies
- contain source and receiver
- display ratioed amplitude and phase (frequency or power sweeps)

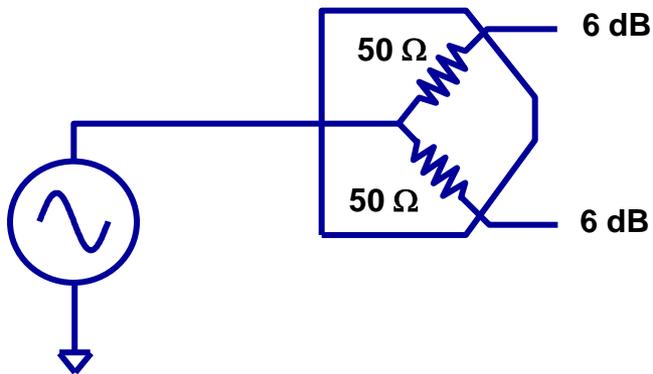
## Spectrum analyzers:

- measure signal amplitude characteristics (carrier level, sidebands, harmonics...)
- are receivers only (single channel)
- can be used for scalar component test (*no phase*) with tracking gen. or ext. source(s)



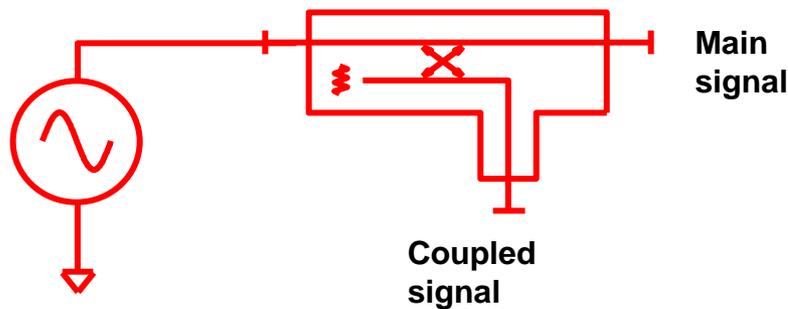
# Signal Separation

## *Measuring incident signals for ratioing*



### ◆ *Splitter*

- usually resistive
- non-directional
- broadband

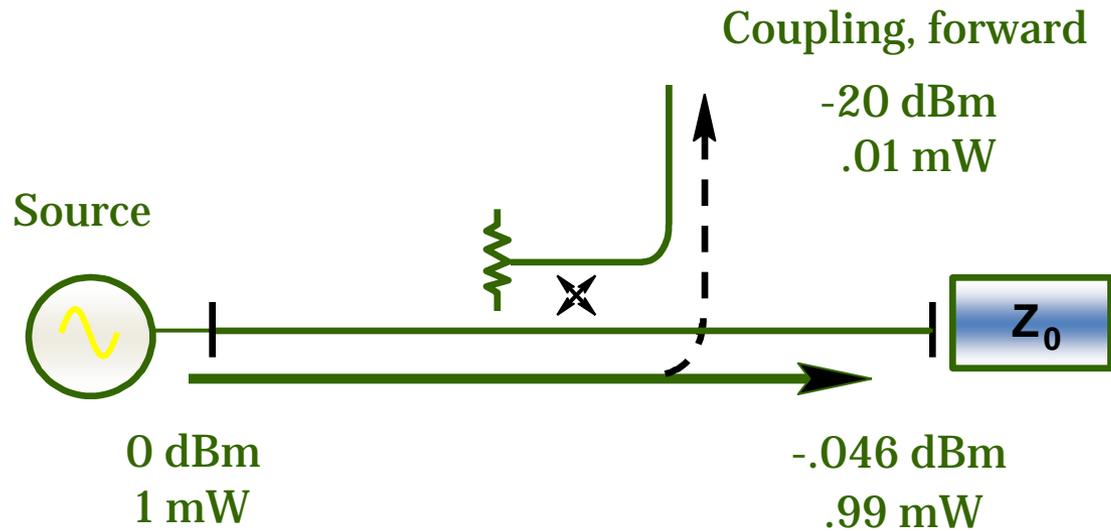


### ◆ *Coupler*

- directional
- low loss
- good isolation, directivity
- hard to get low freq performance



# Forward Coupling Factor

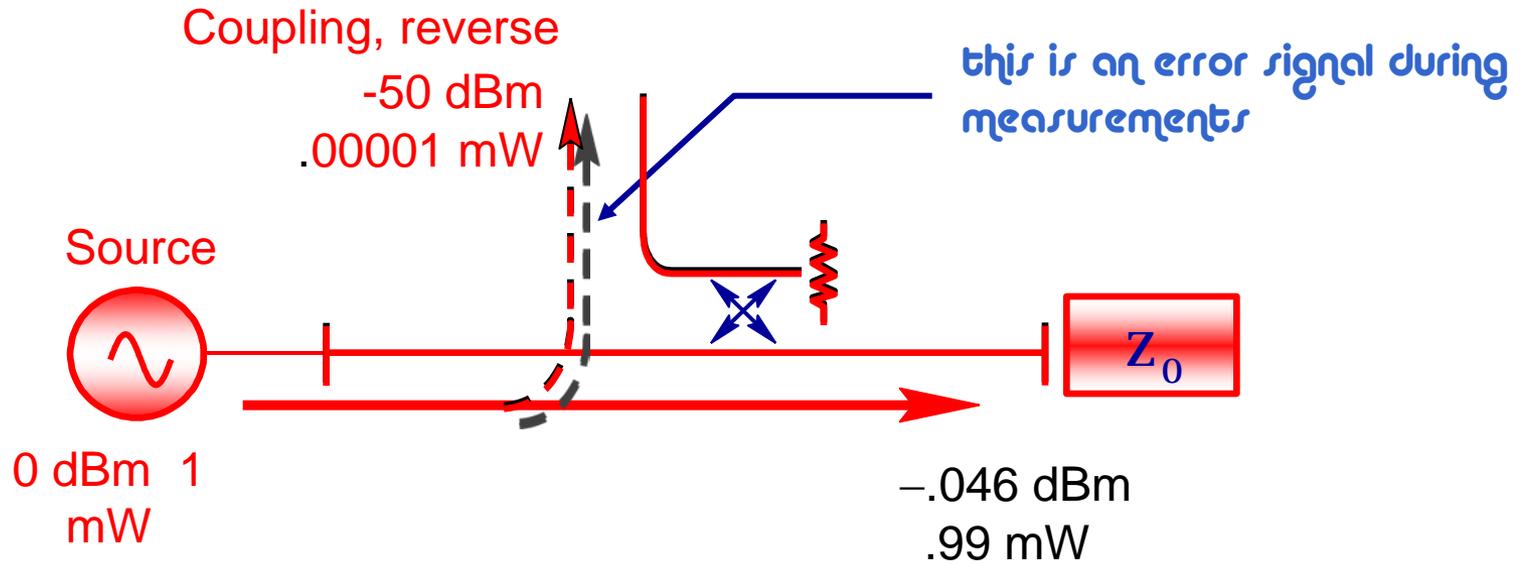


*Example of 20 dB Coupler*

$$\text{Coupling Factor (dB)} = -10 \log \frac{P_{\text{coupling forward}}}{P_{\text{incident}}}$$



# Directional Coupler Isolation (Reverse Coupling Factor)



*Example of 20 dB Coupler "turned around"*

$$\text{Isolation Factor (dB)} = -10 \log \frac{P_{\text{coupled reverse}}}{P_{\text{incident}}}$$



# Directional Coupler Directivity

$$\text{Directivity (dB)} = 10 \log \frac{P_{\text{coupled forward}}}{P_{\text{coupled reverse}}}$$

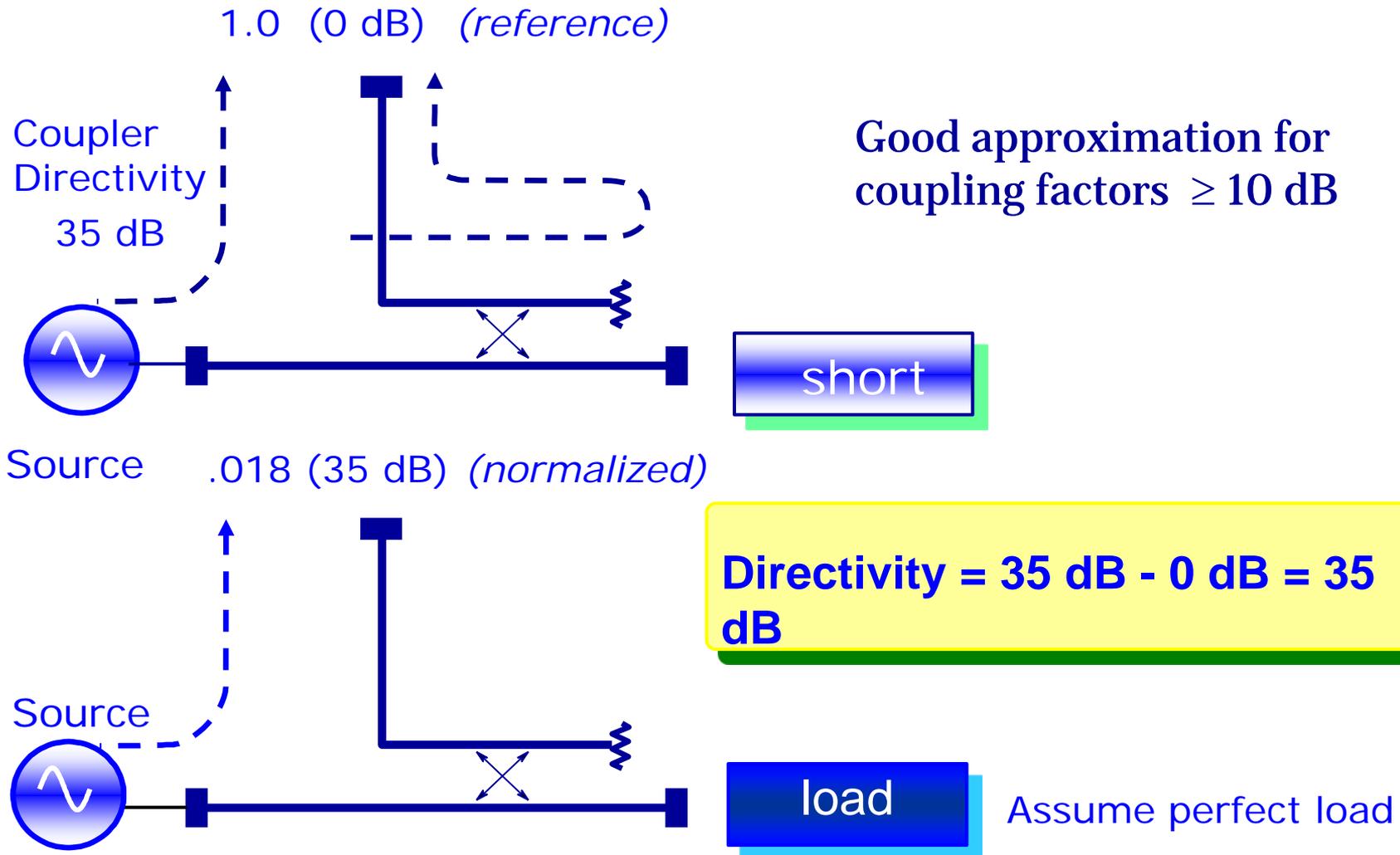
$$\text{Directivity} = \frac{\text{Coupling Factor}}{\text{Isolation}}$$

$$\text{Directivity (dB)} = \text{Isolation (dB)} - \text{Coupling Factor (dB)}$$

***Example of 20 dB Coupler with 50 dB isolation:  
Directivity = 50 dB - 20 dB = 30 dB***

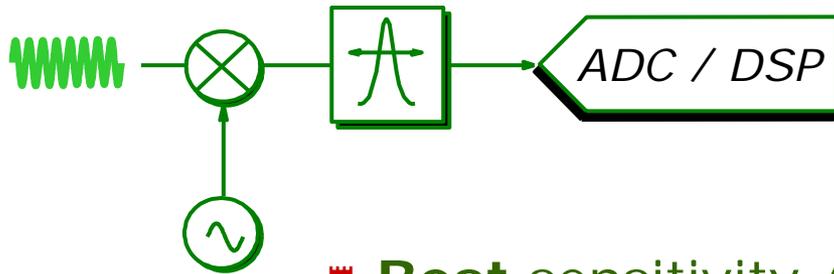


# Measuring Coupler Directivity the Easy Way

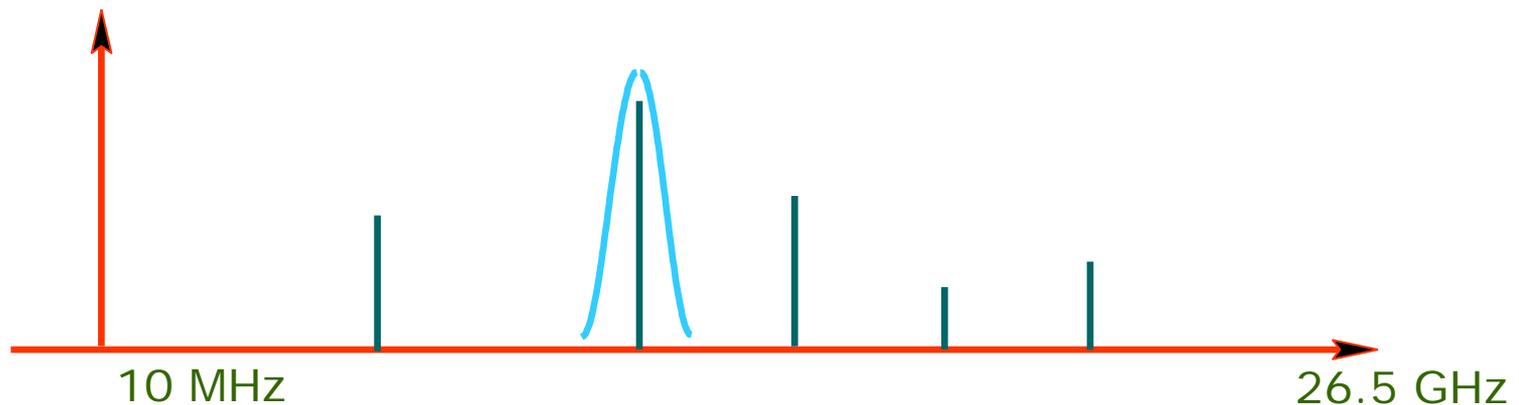




# Narrowband Detection - Tuned Receiver



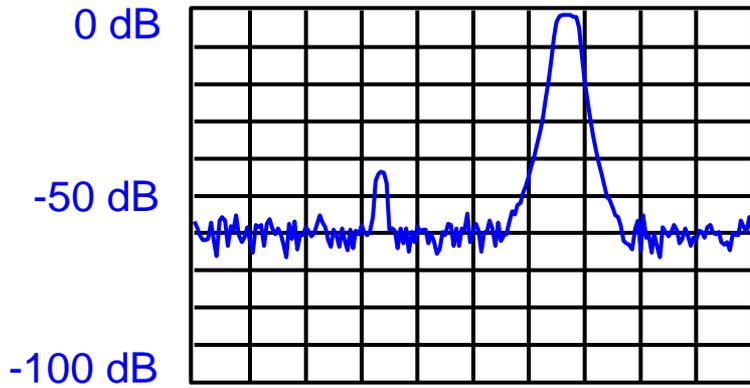
- **Best** sensitivity / dynamic range
- Provides harmonic / spurious signal **rejection**
- Improve dynamic range by increasing **power**, decreasing IF **bandwidth**, or **averaging**
- Trade off noise floor and measurement speed





# Comparison of Receiver Techniques

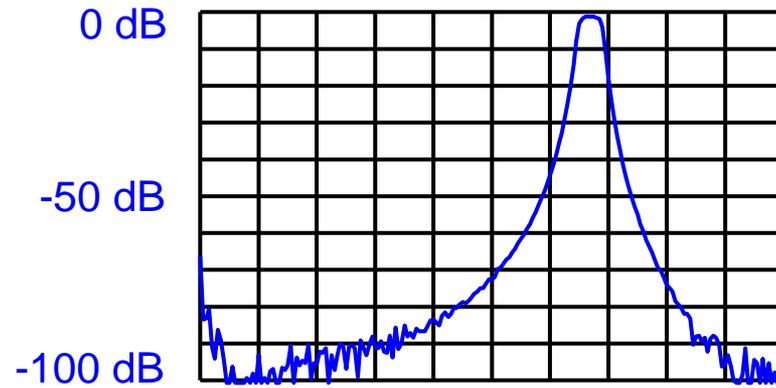
## Broadband (diode) detection



-60 dBm Sensitivity

- higher noise floor
- false responses

## Narrowband (tuned-receiver) detection



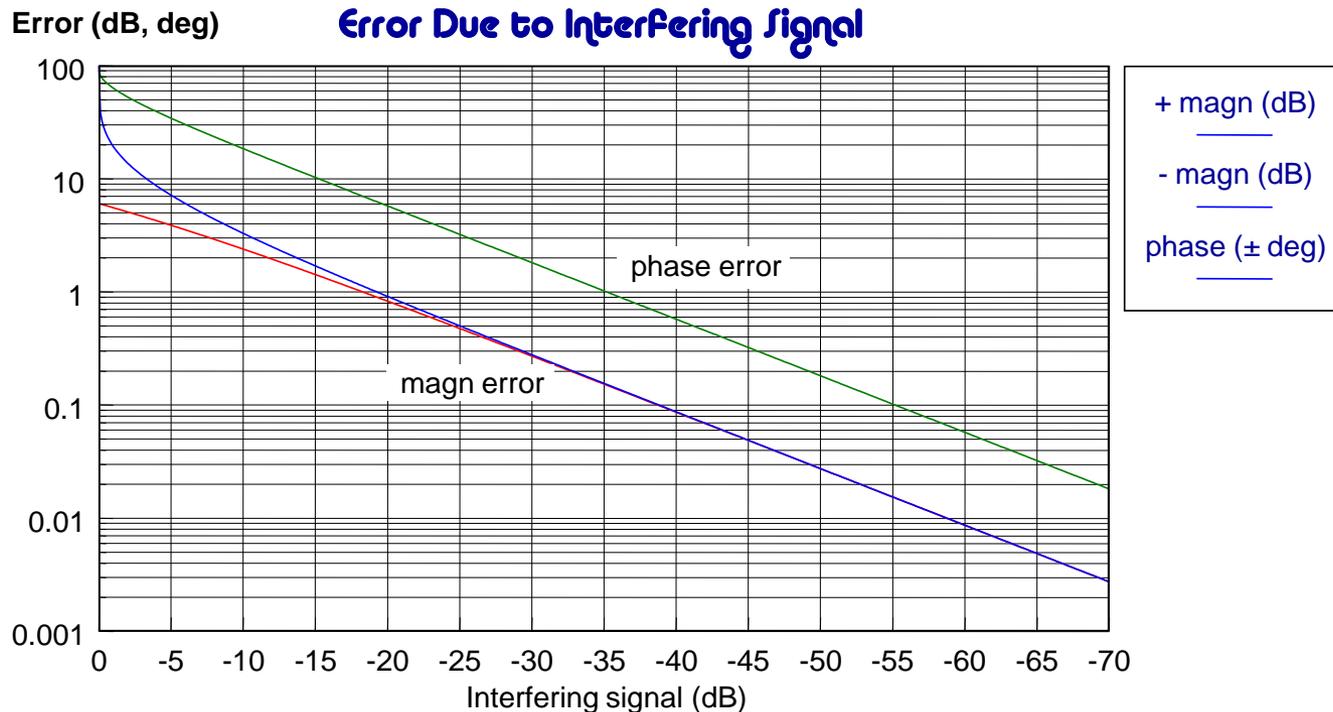
< -100 dBm Sensitivity

- high dynamic range
- harmonic immunity

*Dynamic range = maximum receiver power - receiver noise floor*

# Dynamic Range and Accuracy

*Dynamic range is very important  
for measurement accuracy !*





# Measurement Error Modeling

## Systematic errors

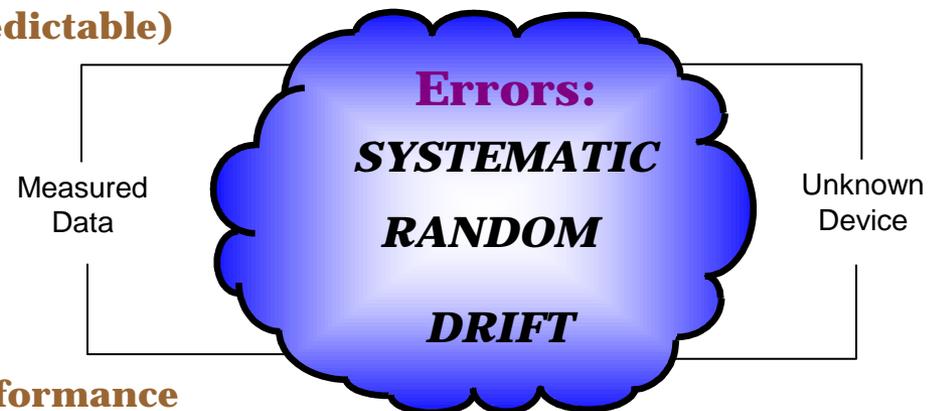
- **due to imperfections in the analyzer and test setup**
- **are assumed to be time invariant (predictable)**
- **can be characterized (during calibration process) and mathematically removed during measurements**

## Random errors

- **vary with time in random fashion (unpredictable)**
- **cannot be removed by calibration**
- **main contributors:**
  - × **instrument noise (source**
  - × **phase noise, IF noise floor, etc.)**
  - × **switch repeatability**
  - × **connector repeatability**

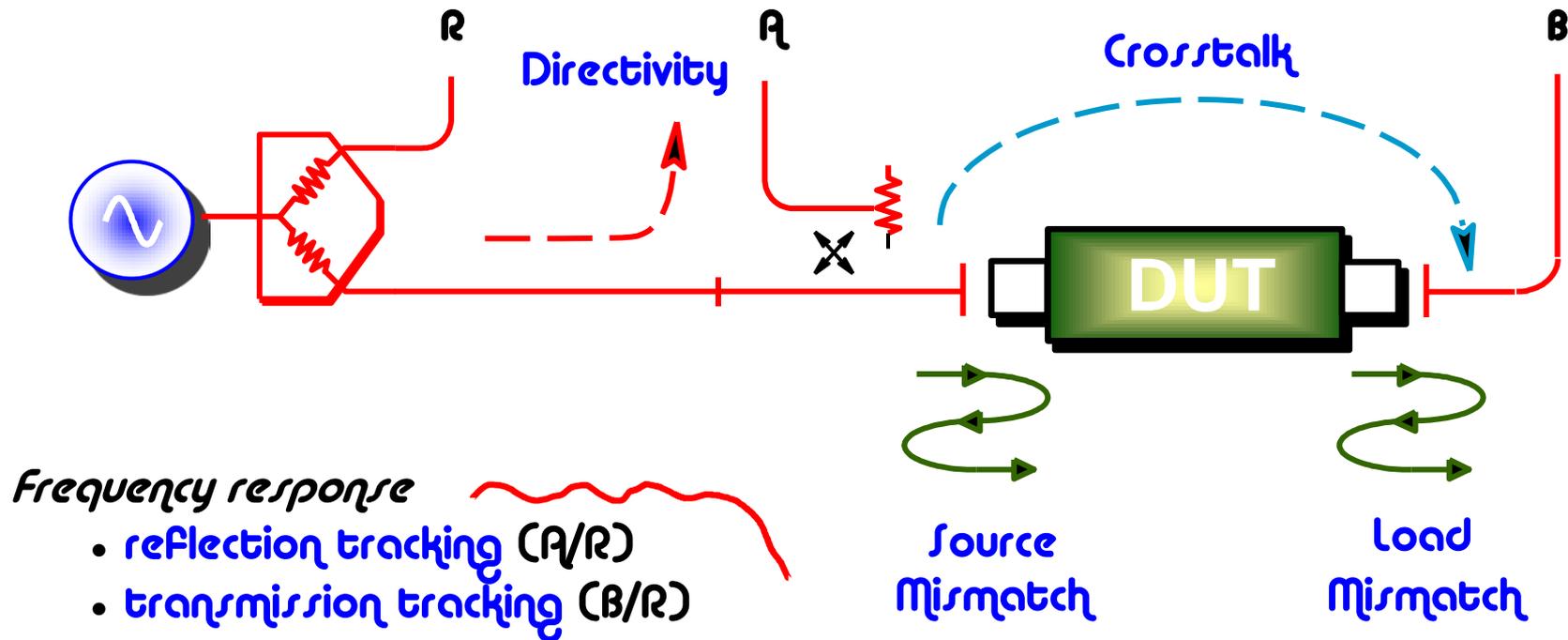
## Drift errors

- ❖ **are due to instrument or test-system performance changing *after* a calibration has been done**
- ❖ **are primarily caused by temperature variation**
- ❖ **can be removed by further calibration(s)**





# Systematic Measurement Errors



Six forward and six reverse error terms yields 12 error terms for two-port devices



# Types of Error Correction

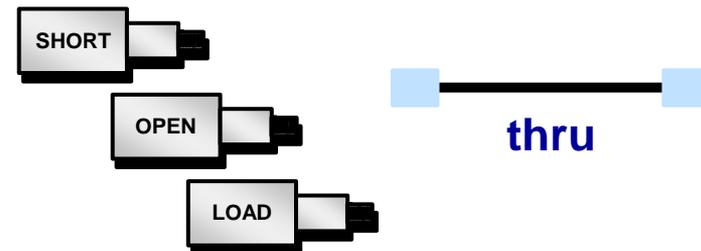
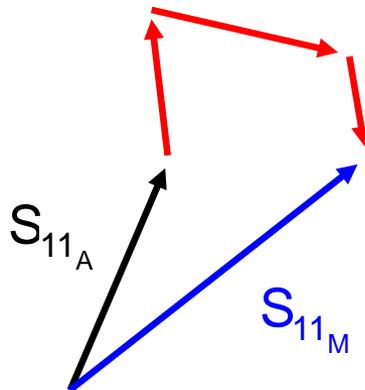
## Two main types of error correction:

### ⊕ response (normalization)

- simple to perform
- only corrects for tracking errors
- stores reference trace in memory, then does data divided by memory

### ⊕ vector

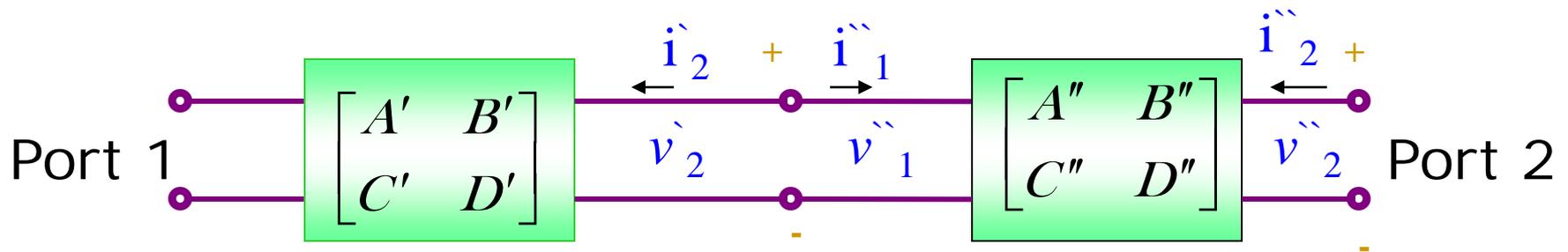
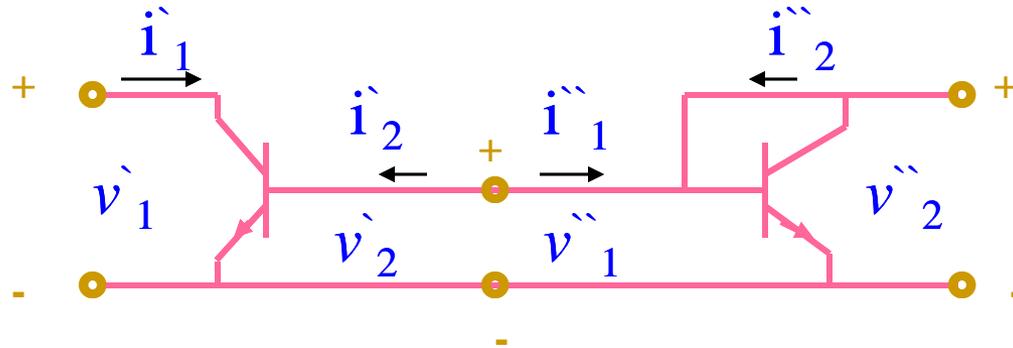
- requires more standards
- requires an analyzer that can measure phase
- accounts for all major sources of systematic error





# ABCD parameter representation

► Very useful when cascading networks

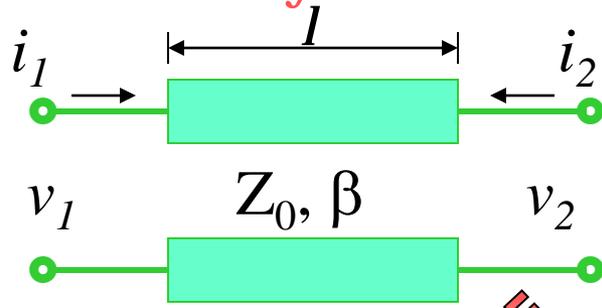


$$\begin{Bmatrix} v_1 \\ i_1 \end{Bmatrix} = \begin{bmatrix} A' & B' \\ C' & D' \end{bmatrix} \begin{bmatrix} A'' & B'' \\ C'' & D'' \end{bmatrix} \begin{Bmatrix} v_2'' \\ -i_2'' \end{Bmatrix}$$



# ABCD parameter representation

➡ ABCD very useful for T.L.

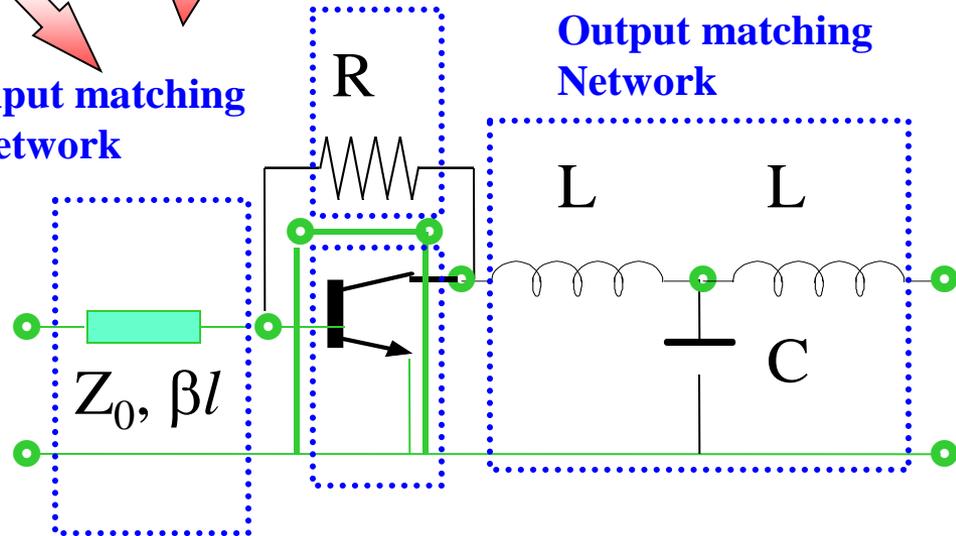
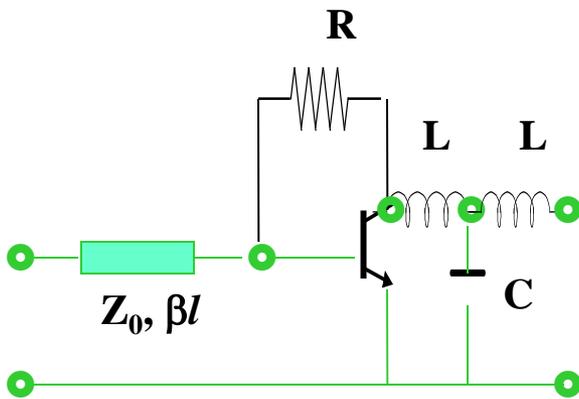


$$\begin{bmatrix} A & B \\ C & D \end{bmatrix} = \begin{bmatrix} \cos(\beta l) & jZ_0 \sin(\beta l) \\ j \frac{\sin(\beta l)}{Z_0} & \cos(\beta l) \end{bmatrix}$$

Feedback loop

Input matching Network

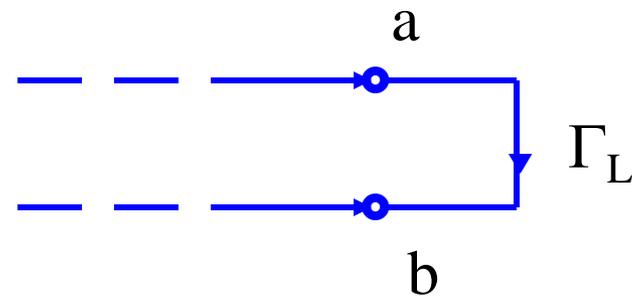
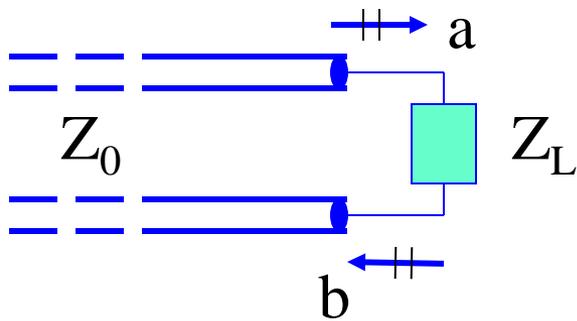
Output matching Network



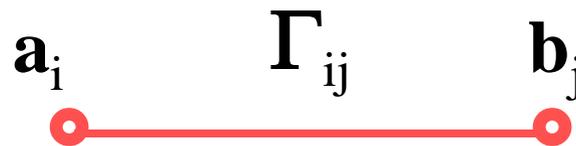


# Signal Flow Computations

Complicated networks can be efficiently analyzed in a manner identical to signals and systems and control.



in general





## Basic Rules:

We'll follow certain rules when we build up a network flow graph.

1. Each variable,  $a_1$ ,  $a_2$ ,  $b_1$ , and  $b_2$  will be designated as a node.
2. Each of the S-parameters will be a branch.
3. Branches enter dependent variable nodes, and emanate from the independent variable nodes.
4. In our S-parameter equations, the reflected waves  $b_1$  and  $b_2$  are the dependent variables and the incident waves  $a_1$  and  $a_2$  are the independent variables.
5. Each node is equal to the sum of the branches entering it.

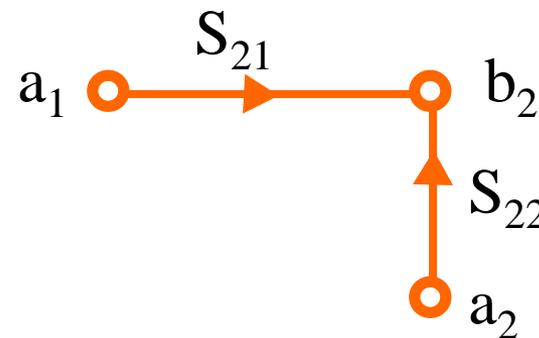
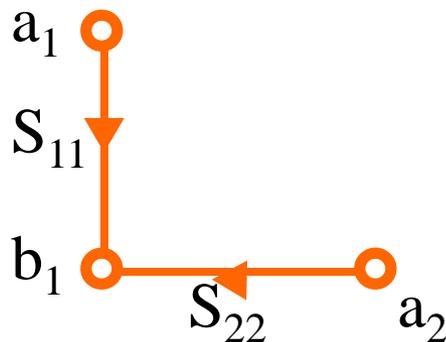


Let's apply these rules to the two S-parameters equations

$$b_1 = S_{11}a_1 + S_{12}a_2$$

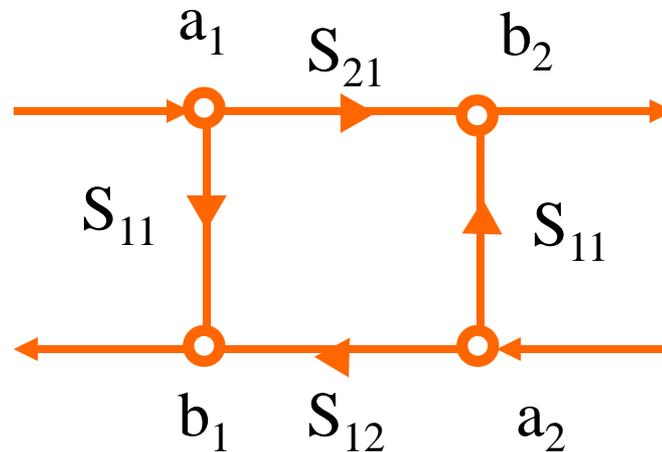
$$b_2 = S_{21}a_1 + S_{22}a_2$$

First equation has three nodes:  $b_1$ ,  $a_1$ , and  $a_2$ .  $b_1$  is a dependent node and is connected to  $a_1$  through the branch  $S_{11}$  and to node  $a_2$  through the branch  $S_{12}$ . The second equation is similar.





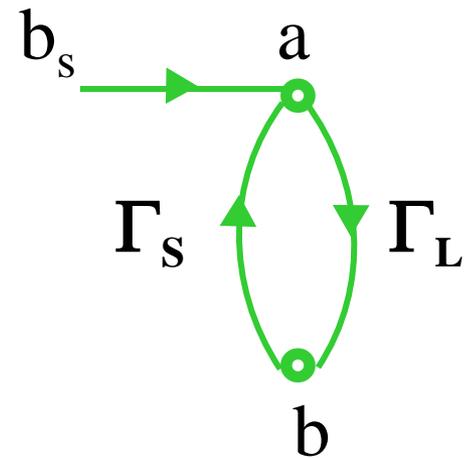
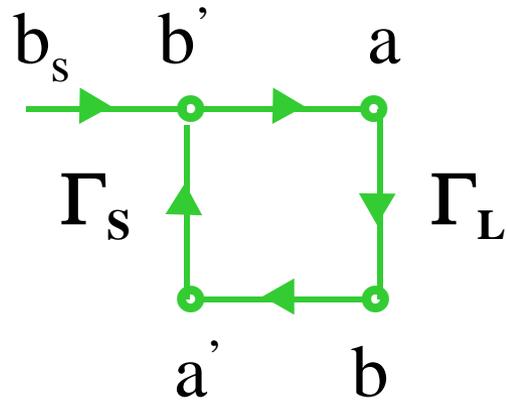
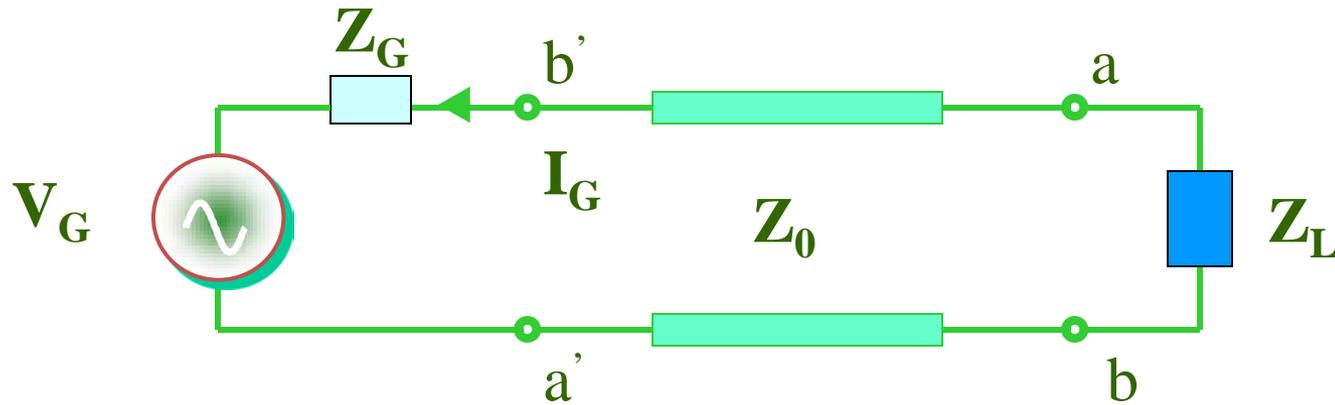
## Complete Flow Graph for 2-Port



The relationship between the traveling waves is now easily seen. We have  $a_1$  incident on the network. Part of it transmits through the network to become part of  $b_2$ . Part of it is reflected to become part of  $b_1$ . Meanwhile, the  $a_2$  wave entering port two is transmitted through the network to become part of  $b_1$  as well as being reflected from port two as part of  $b_2$ . By merely following the arrows, we can tell what's going on in the network. This technique will be all the more useful as we cascade networks or add feedback paths.



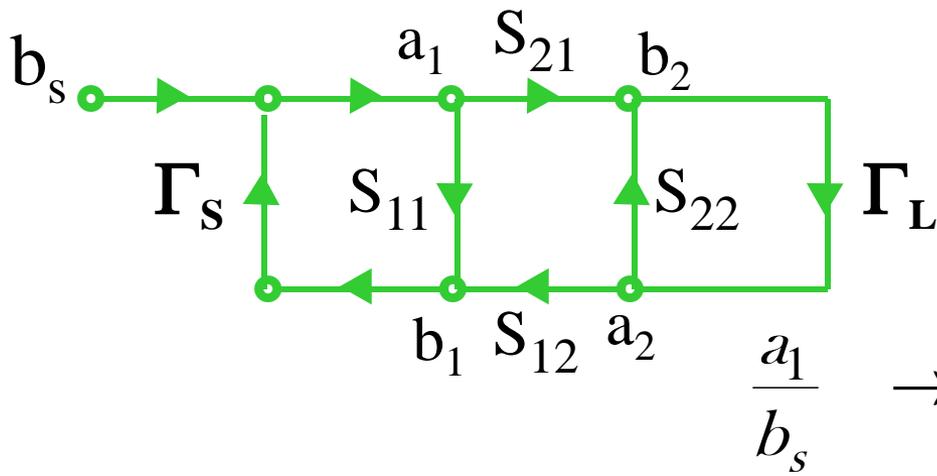
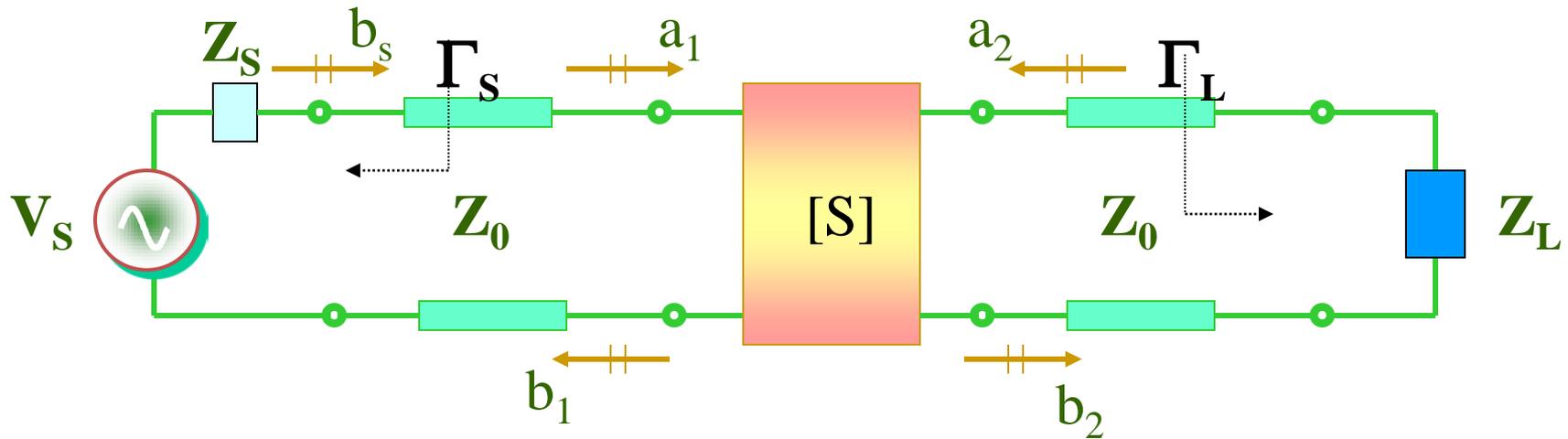
# Arrangement for Signal Flow Analysis



$$b_s = \frac{\sqrt{Z_0}}{Z_G + Z_0} V_G$$

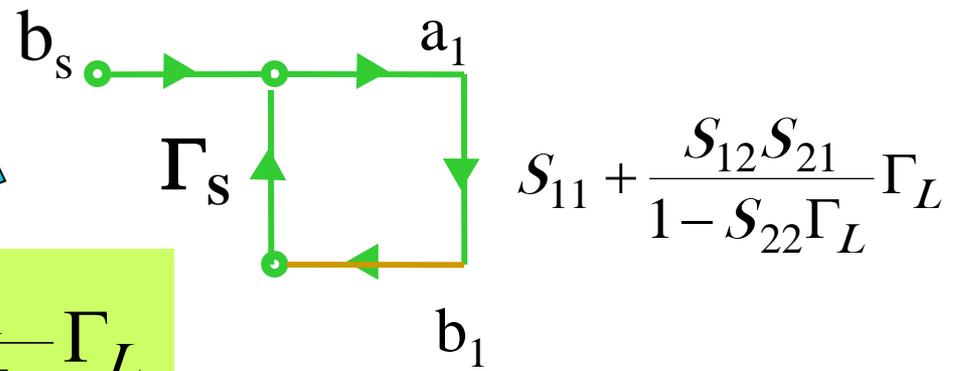
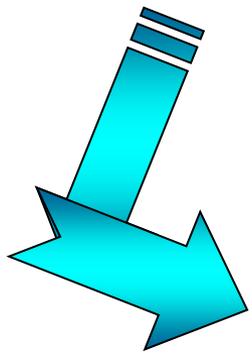
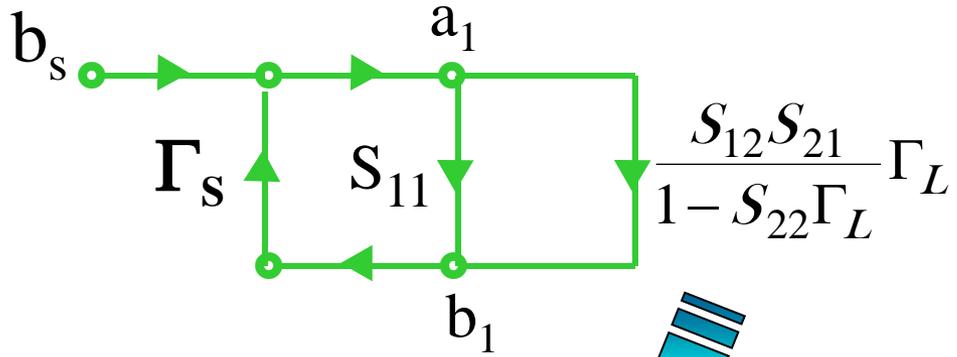


# Analysis of Most Common Circuit



The diagram shows the transmission coefficient from the source to the input port of the network. The incident wave is  $b_s$  and the transmitted wave is  $a_1$ .

$$\frac{a_1}{b_s} \rightarrow \frac{1}{1 - \left( S_{11} + \frac{S_{12} S_{21}}{1 - S_{22} \Gamma_L} \Gamma_s \right)}$$



$$\Gamma_{in} = \frac{b_1}{a_1} = S_{11} + \frac{S_{12}S_{21}}{1 - S_{22}\Gamma_L} \Gamma_L$$

Note: Only  $\Gamma_L = 0$  ensures that  $S_{11}$  can be measured.

The scattered-wave amplitudes are linearly related to the incident wave amplitudes. Consider the N port junction

If the only incident wave is  $V_1^+$  then

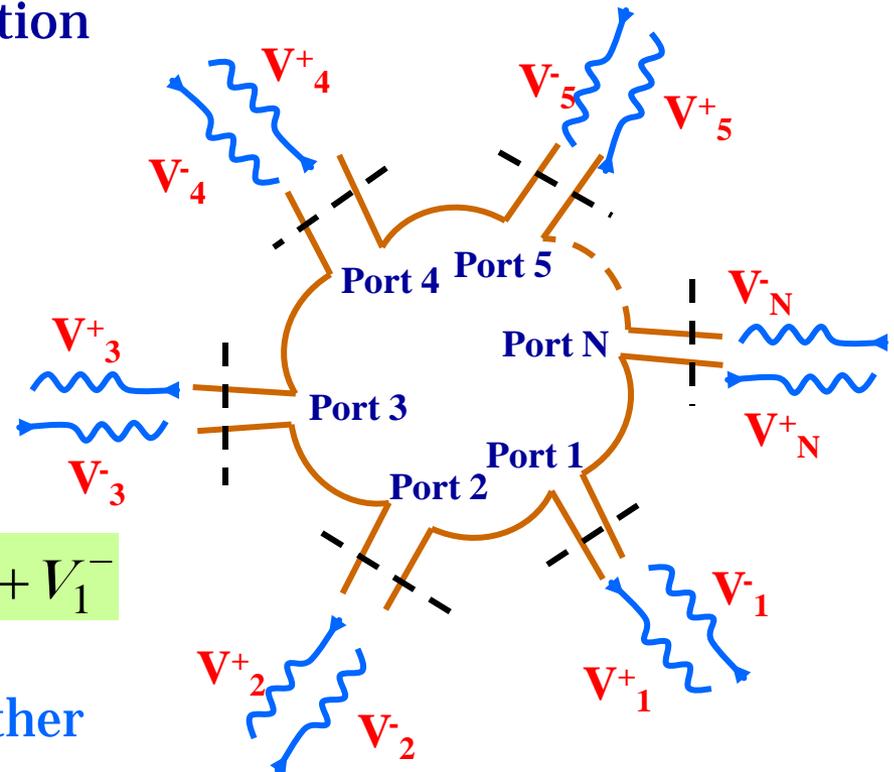
$$V_1^- = S_{11}V_1^+$$

$S_{11}$  is the reflection coefficient

The total voltage is port 1 is  $V_1 = V_1^+ + V_1^-$

Waves will also be scattered out of other ports. We will have

$$V_n^- = S_{n1}V_1^+ \quad n = 2, 3, 4, \dots, N$$





If all ports have incident wave then

$$\begin{bmatrix} V_1^- \\ V_2^- \\ \dots \\ V_N^- \end{bmatrix} = \begin{bmatrix} S_{11} & S_{12} & S_{13} & \dots & S_{1N} \\ S_{21} & S_{22} & S_{23} & \dots & S_{2N} \\ \dots & \dots & \dots & \dots & \dots \\ S_{N1} & S_{N2} & S_{N3} & \dots & S_{NN} \end{bmatrix} \begin{bmatrix} V_1^+ \\ V_2^+ \\ \dots \\ V_N^+ \end{bmatrix}$$

or

$$[V^-] = [S][V^+]$$

$[S]$  is called the scattering matrix  $S_{ij} = \frac{V_i^-}{V_j^+}$  for  $V_k^+ = 0 (k \neq j)$



If we choose the equivalent  $Z_0$  equal to 1 then the incident power is given by

$$\frac{1}{2} |V_n^+|^2$$

and the scattering will be symmetrical. With this choice

$$V = V^+ + V^-, I = I^+ + I^-$$

*and*

$$V^+ = \frac{1}{2}(V + I)$$

$$V^- = \frac{1}{2}(V - I)$$



$V^+$  and  $V^-$  are the variables in the scattering matrix formulation; but they are linear combination of  $V$  and  $I$ .

Other normalization are

$$v = \frac{V}{\sqrt{Z_0}} \quad i = \frac{I}{\sqrt{Z_0}}$$

Just as in the impedance matrix there are several properties of the scattering matrix we want to consider.

1. A shift of the reference planes
2. S matrix for reciprocal devices
3. S matrix for the lossless devices

## Shift in the reference planes

Consider the following network, where  $t_n$  is the original location of the reference plane, and  $t'_n$  in the new location of the reference plane.

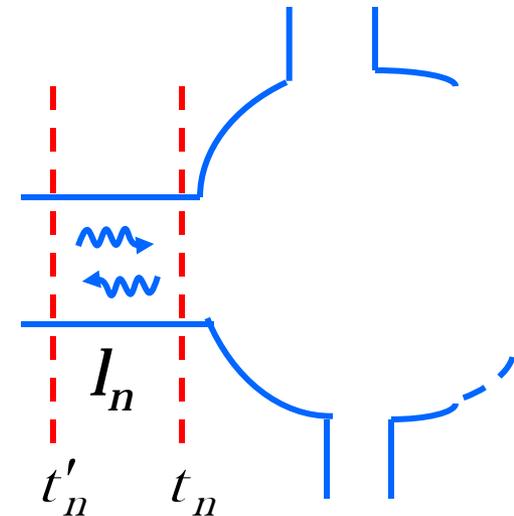
The electrical length between  $t_n$  and  $t'_n$  is

$$\theta = \beta_n \ell_n.$$

$S_{mn}$   $m \neq n$  must be multiplied by  $e^{-j\theta_n}$

$S_{nn}$  must be multiplied by  $e^{-j2\theta_n}$

Why is this a factor of 2?





$$V_n'^+ = V_n^+ e^{j\theta_n}$$

$$V_n'^- = V_n^- e^{-j\theta_n}$$

$$[S] = \begin{bmatrix} e^{-j\theta_1} & & & & \\ & e^{-j\theta_2} & & & \\ & & \ddots & & \\ & & & \ddots & \\ & & & & e^{-j\theta_N} \end{bmatrix} \begin{bmatrix} S_{11} & S_{12} & \dots & S_{1N} \\ S_{21} & S_{22} & \dots & S_{2N} \\ \dots & \dots & \dots & \dots \\ S_{N1} & S_{N2} & \dots & S_{nn} \end{bmatrix} \begin{bmatrix} e^{-j\theta_1} & & & & \\ & e^{-j\theta_2} & & & \\ & & \ddots & & \\ & & & \ddots & \\ & & & & e^{-j\theta_N} \end{bmatrix}$$



Consider a  $2 \times 2$  scattering matrix where two reference planes are shifted.

$$[S'] = \begin{bmatrix} e^{-\theta_1} & 0 \\ 0 & e^{-\theta_2} \end{bmatrix} \begin{bmatrix} S_{11} & S_{12} \\ S_{21} & S_{22} \end{bmatrix} \begin{bmatrix} e^{-\theta_1} & 0 \\ 0 & e^{-\theta_2} \end{bmatrix}$$

$$[S'] = \begin{bmatrix} S_{11}e^{-\theta_1} & S_{12}e^{-\theta_1}e^{-\theta_2} \\ S_{21}e^{-\theta_1}e^{-\theta_2} & S_{22}e^{-\theta_2} \end{bmatrix}$$

$$[S'] = \begin{bmatrix} S_{11}e^{-j2\theta_1} & S_{21}e^{-\theta_1}e^{-\theta_2} \\ S_{12}e^{-\theta_1}e^{-\theta_2} & S_{22}e^{-j2\theta_2} \end{bmatrix}$$



## Proof of Symmetry of Scattering Matrix

For a reciprocal junction  $S_{mn} = S_{nm}$   $m \neq n$  provided that  $Z_0 = 1$

$$P = \frac{1}{2} |V_n^+|^2 \quad \text{for all modes.}$$

$$V_n = V_n^+ + V_n^- \quad \text{and} \quad I_n = I_n^+ - I_n^-$$

$$\therefore I_n = V_n^+ - V_n^- \quad (Z_0 = 1)$$

$$\begin{aligned} [V] &= [V^+] + [V^-] \\ &= [Z][I] \\ &= [Z][V^+] - [Z][V^-] \end{aligned}$$



## Defining the unit matrix

$$[u] = \begin{bmatrix} 1 & 0 \\ & 1 \\ & & \cdot \\ 0 & & & 1 \end{bmatrix}$$

$$[V^+] + [V^-] = [Z][V^+] - [Z][V^-]$$

## Rearrange and factor

$$([Z] + [U])[V^-] = ([Z] - [U])[V^+]$$

or

$$[V^-] = ([Z] + [U])^{-1} ([Z] - [U])[V^+]$$

$$\text{but } [V^-] = [S][V^+] \quad \therefore [S] = ([Z] + [U])^{-1} ([Z] - [U])$$



## Loss-less Junction

The total power leaving a junction must be equal to the total power entering the junction power.

$$\sum_{n=1}^N |V_n^-|^2 = \sum_{n=1}^N |V_n^+|^2$$

but

$$V_n^- = \sum_{i=1}^N S_{ni} V_i^+$$

so that

$$\sum_{n=1}^N \left| \sum_{i=1}^N S_{ni} V_i^+ \right|^2 = \sum_{n=1}^N |V_n^+|^2$$



## Loss-less Junction

$V_n^+$  are all independent incident voltages, so we choose  $V_n^+ = 0$  except for  $n=i$

$$\sum_{n=1}^N \left| \sum_{i=1}^N S_{ni} V_i^+ \right|^2 = \sum_{n=1}^N |V_n^+|^2$$

$$\sum_{n=1}^N |S_{ni} V_i^+|^2 = |V_n^+|^2$$

$$\sum_{n=1}^N |S_{ni}|^2 = \sum_{n=1}^N S_{ni} S_{ni}^* = 1 \quad \forall i.$$

$$[S_{1i} \quad S_{2i} \quad \dots \quad S_{Ni}] \begin{bmatrix} S_{1i}^* \\ S_{2i}^* \\ \dots \\ S_{Ni}^* \end{bmatrix} = 1$$



## Loss-less 2 Port Junction

For this case [S] is unitary

$$\therefore \sum_{n=1}^N S_{nm} S_{np}^* = \delta_{mp}$$

or

$$\left. \begin{aligned} S_{11} S_{11}^* + S_{12} S_{12}^* &= 1 \\ S_{22} S_{22}^* + S_{12} S_{12}^* &= 1 \end{aligned} \right\} \Rightarrow |S_{11}| = |S_{22}|$$
$$S_{11} S_{12}^* + S_{12} S_{22}^* = 0$$

The magnitude of the input and output ports are equal in magnitude. Also

$$|S_{12}| = \sqrt{1 - |S_{11}|^2}$$



If we know  $|S_{11}|$  then we can obtain  $|S_{12}|$  and  $|S_{22}|$ .

Note: The fraction of power reflected at terminal  $t$ , is

$$\frac{P_{refl}}{P_{inc}} = |S_{11}|^2$$

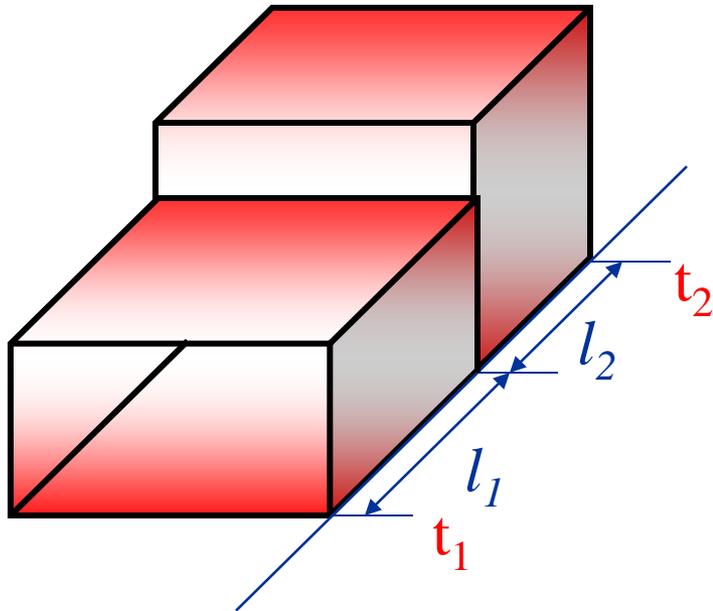
So that the insertion loss due to reflection is

$$IL = 10 \log(1 - |S_{11}|^2)$$

$$IL = 20 \log |S_{12}|$$

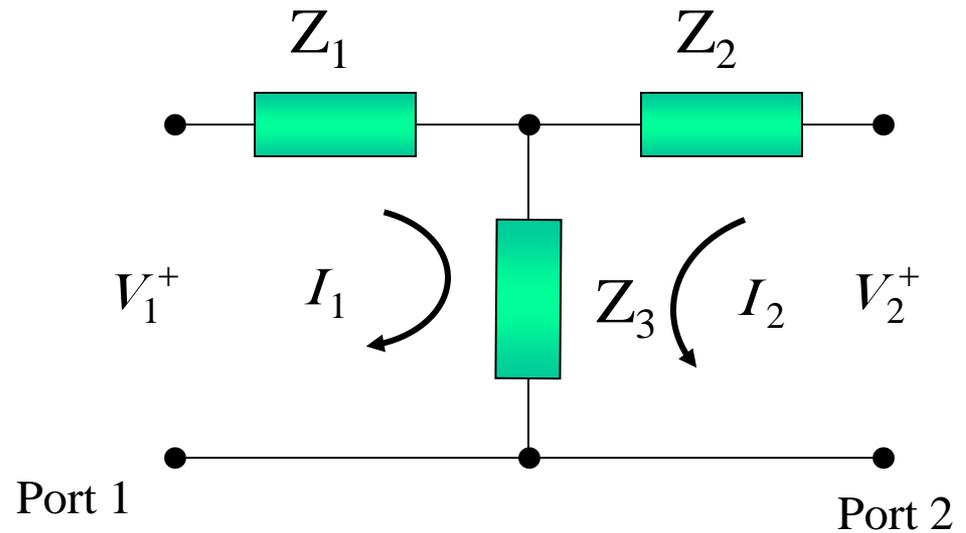


## Example: two-port network



Assume  $TE_{10}$  modes at  $t_1$  and  $t_2$

## Equivalent Circuit



Apply KVL:

$$V_1 = Z_1 I_1 + Z_3 I_1 + Z_3 I_2$$

$$V_2 = Z_2 I_2 + Z_3 I_2 + Z_3 I_1$$



If

$$Z_3 = Z_{12} = \left. \frac{V_1}{I_2} \right|_{I_1=0}$$

$$Z_1 = Z_{11} - Z_{12}$$

$$Z_2 = Z_{22} - Z_{12}$$

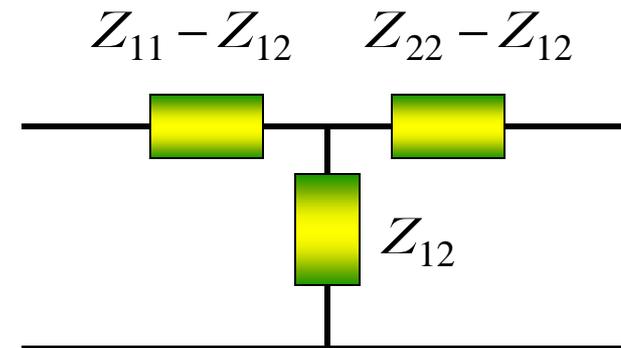
Then we have

$$V_1 = Z_{11}I_1 + Z_{12}I_2$$

$$V_2 = Z_{22}I_2 + Z_{12}I_2$$

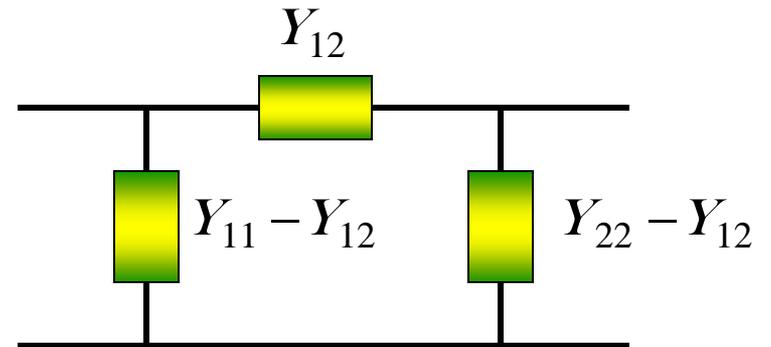
and

$$[V] = [Z][I]$$



This can be transformed into an admittance matrix

$$\begin{bmatrix} I_1 \\ I_2 \end{bmatrix} = \begin{bmatrix} Y_{11} & Y_{12} \\ Y_{12} & Y_{22} \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \end{bmatrix}$$





### Traveling Wave:

$$V^+ = Ae^{-\delta x}, V^- = Ae^{\delta x}$$

$$V(x) = V^+(x) + V^-(x)$$

Similarly for current:

$$I(x) = I^+(x) - I^-(x) = \frac{V^+(x)}{Z_0} - \frac{V^-(x)}{Z_0}$$

Reflection Coefficient:

$$\Gamma(x) = \frac{V^-(x)}{V^+(x)}$$



Introduce “normalized” variables:

$$v(x) = V(x)/\sqrt{Z_0}, i(x) = \sqrt{Z_0}I(x)$$

So that

$$v(x) = a(x) + b(x) \quad i(x) = a(x) - b(x) \quad \text{and} \quad b(x) = \Gamma(x)a(x)$$

This defines a single port network. What about 2-port?

2-port

$$b_1 = S_{11}a_1 + S_{12}a_2$$

$$b_2 = S_{21}a_1 + S_{22}a_2$$



Each reflected wave ( $b_1, b_2$ ) has two contributions: **one from the incident wave at the same port** and another **from the incident wave at the other port**.

How to calculate S-parameters?

$$S_{11} = \left. \frac{b_1}{a_1} \right|_{a_2=0}$$

Input reflected coefficient with output matched.

$$S_{12} = \left. \frac{b_1}{a_2} \right|_{a_1=0}$$

Reverse transmission coefficient with input matched.

$$S_{21} = \left. \frac{b_2}{a_1} \right|_{a_2=0}$$

Transmission coefficient with output matched.

$$S_{22} = \left. \frac{b_2}{a_2} \right|_{a_1=0}$$

Output reflected coefficient with input matched.



## Generalized Scattering Matrix:

We define it via  $[b]=[S][a]$ . S-matrix depends on the choice of normalized impedance. Usually  $50 \Omega$ , but can be anything and can even be complex!

### Calculating $S_{ij}$ :

$$S_{ij} = \left. \frac{b_i}{a_i} \right|_{a_k=0, k \neq i, k=1, \dots, n} = \frac{V_i - Z_{\circ,i}^* I_i}{V_i + Z_{\circ,i}^* I_i} = \frac{Z_i - Z_{\circ,i}^*}{Z_i + Z_{\circ,i}}$$

Which is input reflected coefficient with all other ports matched.

$$S_{ki} = \left. \frac{b_k}{a_i} \right|_{a_k=0, k \neq i, k=1, \dots, n}$$

is equal to transducer power gain from i to k with ports other than i matched.