# **Proton and Ion Linear Accelerators**

Yuri Batygin<sup>1</sup>, Sergey Kurennoy<sup>1</sup>, Sebastian Szustkowski<sup>1</sup>, Salvador Sosa Guitron<sup>1</sup>, Vyacheslav Yakovlev<sup>2</sup>

**1Los Alamos National Laboratory 2Fermi National Accelerator Laboratory**

**U.S. Particle Accelerator School**

**July 15 – July 26, 2024**







#### **Proton and Ion Linear Accelerators RF linacs: cavities, structures, EM design**

Sergey Kurennoy, LANL

USPAS, July 19, 2024

Lecture 10

LA-UR-17-24573



#### **Content**

- Why linacs & RF together?
- Reminder: basics of linacs
- RF cavities
- Accelerating structures: RFQ, DTL, CCL, etc.
- Electromagnetic (EM) design of accelerating structures. Tools.

Sources:

T.P. Wangler. *RF linear accelerators*, Wiley-VCH, 2nd Ed., 2008. *Handbook of Accelerator Physics and Engineering*. 3rd Ed., Eds. A. Chao *et al*. World Scientific, 2023.



#### **Linacs**

**Linear accelerator (linac)** – a device that accelerates charged particles in a straight line.

#### **Linac types:**

- **Electrostatic** electric field is produced by a fixed voltage (e.g., old TV tubes)
- **Induction** electric field is produced by changing magnetic flux
- **Radio-Frequency (RF)**  fields are produced by external sources of RF power





#### **Why linacs & RF together?**



**LHC RF section = 2 short linacs!**

**SLAC** – electron linac (1968): 3 km, & RF acceleration "section" ~3 km.

240 2856-MHz klystrons (design - 960), each with 50-MW peak power (x2 with pulse compression), provide total voltage up to ~50 GV (SLC, 1989).

**LHC** – circular p-p collider (2008): 27 km, but RF acceleration section <100 m. 8 SC 400.8-MHz RF cavities per ring; 8-16 MV; each cavity is only  $\sim$ 2 m long and powered by one klystron (16 klystrons total).





#### **Why linacs & RF together?**





**SLAC linac (30' below) 960 traveling-wave structures (x3m)**

#### **LHC 4 RF cavities in cryo-module**





#### **Why linacs & RF together?**

#### **LANSCE (LAMPF) linac (1972)**



**800 m, 800 MeV**  Protons (p) and hydrogen ions (H- )

#### **Drift-tube linac (DTL)**

62 m, 0.75-100 MeV  $β = v/c = 0.04 - 0.43$ 4 201.25-MHz tubes (≤3 MW) **Coupled-cavity linac (CCL)**  731 m, 100-800 MeV  $β = v/c = 0.43 - 0.84$ 44 805-MHz klystrons (1 MW)

### **Induction Accelerator**



Fig. 1. Induction accelerator principle:  $I - \text{laminated iron core; } 2 - \text{switch; } 3 - \text{pulse forming network; } 4 - \text{primary loop; } 5 - \text{secondary (case).}$ 





 $\oint \vec{E} \cdot d\vec{l} = -\frac{1}{c} \int_{s} \overrightarrow{d\vec{B}} \cdot d\vec{s},$ 



Overhead view of the Astron accelerator as it appeared when first put into operation.





#### **DARHT at LANL – two linear induction accelerators**



Dual-Axis Radiographic Hydrodynamic Test (DARHT) facility:

- Axis 1 (1999): 60-ns pulse, 2 kA, 20 MeV e-beam  $\rightarrow$  high-Z target  $\rightarrow$  X-rays (64 cells)
- Axis 2 (2008): 1.6-μs long flat-top pulse (4 short pieces cut), 2 kA, 17 MeV (74 cells)



#### **Resonance acceleration principle**



Alvarez accelerating structure



- Synchronism between the accelerating field and particles is due to the linac spatial structure: particles arrive at the gaps when the electric field is in the accelerating phase, and are hidden from the field inside drift tubes during the decelerating phase.
- The above example is a 0-mode accelerating structure (Alvarez DTL): the gap fields work in phase,  $\Delta \varphi = 0$ . BTW,  $t_{\text{flight}} = mT_{\text{RF}}$ , where  $m = 2,3,...$  will work too (*mβλ*-mode).
- Note: all these tricks are for ions at  $\beta$  <(<) 1; for electrons, things are much simpler.



#### **Resonance acceleration:** *π***-mode**



Accelerating structure with  $\pi$  - type standing wave.

- This is a *π*-mode accelerating structure (e.g., Wideroe DTL): the fields in the adjacent gaps are in opposite phases, Δ*φ* = *π*.
- Particles accelerated in a gap should arrive to the next gap in one half of the RF period (strictly speaking,  $(n+1/2)T_{RF}$ ) so that its electric field changes to the accelerating phase.
- Still there is a "synchronism" between the RF field and the linac spatial structure.
- In principle, one can accelerate simultaneously a beam of opposite charge (with the same particle mass) with its bunches shifted by *π* in phase.



#### **Example: Inter-digital H-mode (IH) structure**



IH-PMQ structure for deuterons from *β*=*v*/c=0.04 to 0.055:  *f*=201.25 MHz, *I*=50 mA  *L*=73.5 cm, *a*=0.5-0.55 cm. CST Studio simulations: RF fields (MWS), PM quadrupole fields (EMS), and beam dynamics (Particle Studio).





#### **Inter-digital H-mode (IH) structure**



10 bunches of 10K particles (*d*) are accelerated in the cavity



#### **Buncher cavities**



Two buncher cavities: (a) re-entrant and (b) coaxial quarter-wave (λ/4) types. Right – on the same scale.







#### **Linac electromagnetic quadrupoles – LANSCE DTL**





DTL tank 1 EM quadrupoles are installed inside drift tubes: (a) yoke and pole pieces (iron); (b) current coil (copper, hollow); (c) coil assembled with iron; (d) quadrupole fully assembled.

EM quadrupole gradients are adjusted by changing current: gradient *G*=73.5 T/m at ~562 A. *GL* = 2.59 T in Q1.



#### **LANSCE DTL EM quadrupoles – material replacement**



#### **Permanent-magnet quadrupoles**



Magnetic field in the cross section of *M*=16 PMQ calculated with CST EM Studio. For  $r_{\text{in}} = 5.5$  mm,  $r_{\text{out}} = 11$  mm, G= 170 T/m; length *L*=19 mm.

Permanent-magnet quadrupoles are installed in the DTL of the Spallation Neutron Source (SNS).

Permanent-magnet quadrupoles are assembled from segments of PM materials, usually SmCo or NdFeB, with properly oriented magnetization vectors in segments. The gradient of such a quadrupole with *M =*  16 segments (typically *M* = 12, 16), the remnant field  $B_r$  (~1 T), and radii  $r_{\text{in}}$  and  $r_{\text{out}}$ , is

$$
G = 2B_r \left( \frac{1}{r_{in}} - \frac{1}{r_{out}} \right) K_2; \quad K_2 = \cos^2 \frac{\pi}{M} \frac{\sin(2\pi / M)}{2\pi / M} \approx 0.937.
$$



focusing for IH-PMQ cavity. Notice field overlaps.



#### **Permanent-magnet quadrupoles in SNS**



Cut of the SNS DTL drift tube with PMQ. The bore aperture diameter is 2.5 cm.

SNS DTL tank 3 with PMQs inside drift tubes (DTs). Some DTs contain beam position monitors (BPM). FFODDO focusing structure.

Permanent-magnet quadrupoles (PMQ) are installed in the DTL of the Spallation Neutron Source (SNS, Oak Ridge). Now PMQ are also installed in Linac 4 at CERN.





#### **Example: Inter-digital H-mode (IH) structure with PMQ**



IH-PMQ structure for deuterons from *β*=*v*/c=0.04 to 0.055. Focusing structure FOFODODO. CST Particle Studio simulations.



7/19/24 18

#### **Summary 1**

- Linacs and RF are closely related.
- In ion linacs synchronism between accelerated particles and RF is achieved by designing a spatial structure with  $L_c \sim \beta \lambda$ . Fixed velocity profile! Independent-cavity structures can also used, e.g., in heavy-ion linacs, for more flexibility.
- Longitudinal and transverse beam focusing cannot be achieved simultaneously in RF fields. External transverse beam focusing is usually added.



#### **Linac parts**

Linac scheme: particle source + accelerating structure(s)



Electron linacs: electron gun + linac (TW or SW *β*=1 structure); with some tricks.

Ion linacs: ion source (injector) + various structures for different values of *β.*





# **Typical RF linac structures**





#### **RF Linac Types**



**LEDA RFQ SARAF RFQ**

\*Low-energy, several MeV/u Heavy-ions

**INFN SARAF SPIRAL-2 FRIB** Project X EURISOL ADS projects **Injectors (FNAL,KEK, CERN, IHEP….) MMF (Moscow) SNS**

CERN SPL ESS

From P. Ostroumov (2012)



# **Drift-Tube Linac (DTL)**

Alvarez DTL structure (1946):

- TM<sub>010</sub>-like mode (*E<sub>z</sub>, E<sub>r</sub>, B<sub>θ</sub>)*
- DTs hide the beam bunches during the decelerating phase of electric field
- cell length *L*<sub>c</sub>=βλ
- long cavities (tanks) are more efficient
- field stabilization by post-couplers in long tanks





7/19/24 23 tric field lines (Superfish, left) and CST model of cell 98 (1<sup>st</sup> in T3) of the LANSCE DTL.

#### **LANSCE DTL (1968)**



CST model of Tank 1

Usually, the average longitudinal field  $E_0$ is constant (flat) along the tank length but in T1 it is ramped (increasing). Tilt tuners.



Table 4.1 DTL parameters for the LANSCE proton accelerator.

Total length including intertank spaces  $= 61.7$  m

The best efficiency (higher effective shunt impedance) for DTL is achieved in the beam velocity range  $β = 0.1$ -0.3. At LANSCE it is used for wider range,  $β = 0.04$ -0.43.



#### **LANSCE DTL tank models**



CST model of the LANSCE DTL tank 2: 66 cells, 19.68-m long, *β* = 0.107-0.287



#### **Fields in DTL tanks**

Electric field arrows (MWS norm.) in *x* & *y*-planes near the entrance (right) and exit (bottom) of DTL tank 2.





Magnetic fields of quadrupoles near the entrance of DTL tank 1 (imported in PS).





#### **DTL – PS simulations in LANSCE DTL tanks**



Particle Studio simulations of 10 RF periods (10x10K) of 18-mA proton beam injected into DTL tank 1. Transmission 85% (80.6% in bunches, 4.4% in the tail).



#### **DTL – PS simulations in LANSCE DTL tanks**



Particle Studio simulations of 10 RF periods (10x10K) of 18-mA proton beam injected into DTL tank 1 – end-tank view. Transmission 85% (bunches 80.6%, tail 4.4%).



#### **DTL cavities: tuning**



Frequency and field profile slug tuners in the DTL tank 4 model



#### **H-mode DTL – another type of DTL**



TE-mode DTL cavities: interdigital  $H_{110}$  (IH) and cross-bar  $H_{210}$  (CH)



# **Coupled-Cavity Linac (CCL)**

The coupling cells are not excited when the structure is tuned.

Various types of CCL (see below) are used at relatively high velocities, typically for *β*≥0.4.







Energy range 100-800 MeV High shunt impedance: up to 50 MΩ/m

Los Alamos Side Coupled Structure (1968)



#### **LANSCE CCL – Module 5 Tank 1 (M5T1)**

**M5T1**: 36 accelerating cells with 35 coupling cells (18 periods); length 2.89 m + 72-cm drift.

- Effective shunt impedance  $ZT^2 = 31.5 M\Omega/m$ .
- Energy in 100 MeV ( $β = 0.43$ ), out 103.4 MeV.



Electric (left) and magnetic (middle) fields and surface-current magnitude (right) in one period of M5T1



#### **LANSCE CCL – Module 5 Tank 1**



M5T1 cavity (top); electric field of the operating π-mode (middle); on-axis longitudinal electric fields of the two lowest modes: π-mode (red) and mode 35/36 π per AC (blue dashed)

# **Coupling RF power to cavities**



5 cm

"Dog-bone" coupling iris for high-power FEL photoinjector. Up to 0.5 MW at 100% duty.

Methods of coupling to RF cavities:

- (a) magnetic current loop;
- (b) electric antenna;
- (c) magnetic iris WG-cavity





## **Summary 2**

• RF cavities and some common accelerating structures (DTL, CCL) are reviewed.

#### **Figures of merit for accelerating structures**

Quality factor (stored energy *U*, averaged power loss *P*)

Shunt impedance (total cavity voltage  $V_0$ )

Effective shunt impedance (effective voltage  $V_0T$ )  $R_{\text{eff}} = R_{\text{sh}}T^2$ 

Shunt impedance per unit length (voltage  $V_0 = E_0 L$ )

Effective shunt impedance per unit length ( $Z_{\text{eff}}$ )  $ZT^{2} = \frac{\left(E_{0}T\right)^{2}}{E+T}$ 

Ratio  $R_{\text{eff}}/Q$  is independent of surface losses and depends only on the cavity (structure) geometry

Ratios  $E_{\rm max}/E_{\rm acc}$  ( $E_{\rm acc}$ = $E_{\rm 0}$ T) and  $B_{\rm max}/E_{\rm acc}$  – lower is better. The latter is very important for SC cavities.



*ZT*



#### **RF cavities: cylindrical resonator (pillbox)**





Longitudinally integer number of half-variations can be excited

Transverse boundary condition:

Frequency of oscillation mode is

Longitudinal component

$$
k_z = \frac{\pi p}{L}
$$
  
\n
$$
E_z(a) = 0 \qquad J_n(k,a) = 0 \qquad k_r = \frac{v_{nm}}{a}
$$
  
\n
$$
\frac{\omega_o^2}{c^2} - k_z^2 = \frac{v_{nm}^2}{a^2}
$$

$$
\omega_o = c \sqrt{\frac{v_{nm}^2}{a^2} + (\frac{\pi p}{L})^2}
$$

$$
E_z = E_o J_n (v_{nm} \frac{r}{a}) \cos n\theta \cos \frac{\pi p z}{L}
$$

mode  $TM_{nmp}$ 



#### **Example: TM<sub>010</sub> mode**

 $J_1(2.405) = 0.5191$  $E_z = E_o J_o (v_{01} \frac{r}{a}) \cos \omega_o t$  $B_{\theta} = -\frac{E_o}{c} J_1(v_{01} \frac{r}{a}) \sin \omega_o t$  $E_z(a) = 0$  $v_{01} = 2.405$  $k_z = 0$  $\omega_o = 2\pi f = \frac{c v_{01}}{a}$ <br> $f = \frac{2.405 c}{2}$ 

**Boundary condition** 

Field components

Frequency of resonator



TM010 mode in a pill-box cavity.

 $J'_1(x) = 0$   $x_1 = 1.841$   $J_1(x_1) = 0.5819$ 

Example: radius of resonator for  $f = 201.25$  MHz:

$$
a = \frac{2.405 c}{2\pi f} = 0.57 m
$$

Note:

$$
B = \mu_0 H; \quad [B] = T; [H] = A/m; Z_0 = \sqrt{\mu_0 / \varepsilon_0} = 376.7 \,\Omega; \quad [E] = [Z_0 H] = V/m;
$$
  

$$
c = 1 / \sqrt{\mu_0 \varepsilon_0}; \quad \mu_0 c = Z_0.
$$

#### **Energy dissipation in resonator and Q factor**

Dissipated power is a combination of power losses inside cavity and outside cavity

Energy stored in cavity

**Quality factor** 

Q-factor is a combination of unloaded quality factor of cavity and external quality (loaded Q factor)

**External quality factor** 

Losses in metal with surface resistance  $R_{s}$  [Ohm]

Unloaded quality factor  $\frac{1}{\sigma} = \sqrt{\frac{\mu_0 \omega}{2}}$ , where  $\sigma$  is the surface conductivity,  $R_s = \frac{1}{\sigma \delta} = \sqrt{\frac{\mu_0 \omega}{2\sigma}},$  $=\frac{1}{\sigma\delta}=\sqrt{\frac{\mu_0\omega}{2\sigma}}$ and  $\delta$  is the skin depth  $\delta = \sqrt{2 / (\mu_0 \sigma \omega)}$ .

Physical meaning:  $Q = G \frac{V}{S}$ 

 $W_o = \frac{1}{2} \int_{V_o} \mu H_m^2 dV = \frac{1}{2} \int_{V_o} \varepsilon E_m^2 dV$  $Q = \frac{\omega_o W_o}{P}$  $\frac{1}{\omega} = \frac{1}{\omega} + \frac{1}{\omega}$  $Q_{ext} = \frac{\omega_o W_o}{P}$ 

 $P = P_+ + P_{-}$ 







# **Quality factor of TM<sub>010</sub> cavity**

 $H_{m\theta} = -E_o \sqrt{\frac{\varepsilon_o}{\mu_o}} J_1(\nu_{01} \frac{r}{a})$ Amplitude

$$
W_o = \frac{1}{2} \int_{V_o} \mu_o H_{m\theta}^2 dV = \frac{\pi \varepsilon_o E_o^2 L a^2 J_1^2(\nu_{01})}{2} = 0.135 \pi \varepsilon_o L a^2 E_o^2
$$

$$
P_o = \frac{R_s}{2} \int_S H_{m\theta}^2 dS = \pi a R_s E_o^2 \frac{\varepsilon_o}{\mu_o} J_1^2(\nu_{01})(L + a)
$$

Loss power in cavity

Energy stored in cavity

Magnetic field

$$
Q_o = \frac{\omega_o W_o}{P} = \frac{\omega_{01}}{2R_s} \sqrt{\frac{\mu_o}{\varepsilon_o}} \frac{1}{(1 + \frac{a}{L})} = 1.2025 \frac{376.7[Ohm]}{R_s} \frac{1}{(1 + \frac{a}{L})}
$$

For <u>ideal copper surface</u>  $\sigma$  = 5.8⋅10<sup>7</sup> Sm/m, so that  $R_s$  = 2.6⋅10<sup>-4</sup> √ $f(MHz)$  Ω. At 201.25 MHz, *R<sub>s</sub>* = 3.7 mΩ, and  $Q_0$  = 66500 for *a*/*L* = 1. In practice, typically 10%-20% less.



#### **Surface conductivity in superconducting RF cavities**

For RF cavities the power loss depends on the surface resistance: for normal-conducting

$$
R_s = \frac{1}{\sigma \delta} = \sqrt{\frac{\mu_0 \omega}{2\sigma}}
$$
 scales with RF frequency as  $\sqrt{f}$ .

In superconducting (SC) RF cavities the surface resistance is much lower; e.g., for Nb

$$
R_{s}(\Omega) = 9.10^{-5} \frac{f^{2}(GHz)}{T(\degree K)} \exp\left(-\alpha \frac{T_{c}}{T}\right) + R_{res},
$$

where  $R_{res}$  is the residual resistance (~1-10 nΩ),  $\alpha$  = 1.83, and  $T_c$  = 9.2 K is the critical temperature.

SC R<sub>s</sub> is ~10<sup>-5</sup> of that in copper, and so are the cavity surface losses!



#### **RF cavity design**

Cavity design goals depend on many factors including the cavity type and its application: maximize accelerating gradient, minimize losses (NC), minimize max surface fields, etc.

Frequency dependence of cavity parameters:  $a \sim 1/f$ ,

$$
P \propto \begin{Bmatrix} f^{-1/2}, & NC \\ f, & SC \end{Bmatrix} \qquad Q \propto \begin{Bmatrix} f^{-1/2}, & NC \\ f^{-2}, & SC \end{Bmatrix} \qquad ZT^2 \propto \begin{Bmatrix} f^{1/2}, & NC \\ f^{-1}, & SC \end{Bmatrix}
$$

Frequency choice also depends on available RF sources and beam parameters.

Changing cavity shape is the common way of achieving the design goals. Examples:



4-cell elliptical cavity (SC)



#### **RF cavity design codes**

- Calculation of EM fields in the cavity: frequencies, modes, secondary parameters (losses, *Q*, shunt impedance, surface fields, ...)
- Calculation methods:
	- Analytical (simple cavity shapes) + perturbation theory
	- 2D codes (axisymmetric or flat structures): Superfish, URMEL, …
	- 3D codes: CST, HFSS, Analyst, ACE-3P (Omega-3P), etc.



# **Los Alamos Accelerator Code Group (LAACG)**

#### Available at laacg.lanl.gov/ laacg/services/services.phtml

#### Poisson / Superfish

- *collection of programs for calculating static magnetic and electric fields and radio-frequency electromagnetic fields in either 2-D Cartesian coordinates or axially symmetric cylindrical coordinates.*
- *triangular mesh*
- *includes plotting and post-processing*
- \* Poisson / Pandira
- *static electric and magnetic fields*

#### \* Superfish

*- radio-frequency electromagnetic fields*

Windows  $PC - C \cdot U$  ANL contains *programs & utilities; \Docs; \Examples; etc.*



**Los Alamos National** Laboratory

Operated by the University of California for the National Nuclear Security Administr of the US Department of Energy. Copyright © 2003 UC | Disclaimer/Privacy



# **Superfish (SF)**

Steps for running SF (from command window or with right click):

- create geo file (test.am);  $x \rightarrow z$ ,  $y \rightarrow r$  (cm); define BC and materials
- run Automesh on test.am > test.T35 with geo and mesh
- run Fish on test.T35 > test.T35 with fields
- double-click test.T35 to see field lines
- run post-processing of test.T35 > test.sfo to get cavity parameters

Alternative: run Autofish on test.am



# **Superfish input file**

SF input (\*.am or \*.af):

- First line is the problem title (< 80 char) followed by 3 namelists: REG, PO, MT (actually parsing). Delimiters: & or \$; comment: ; or !
- \$reg: kprob problem type  $(1 SF, 0 Poisson) in$  the 1<sup>st</sup> \$reg, symmetry: e.g., icylin=1 – cylindrical; BCs; approximate frequency (MHz); mat #.
- \$po: defines geometry; separate \$po list for each material. Note \$po … \$.
- \$mt: mt=2, 3, … material table defines mat properties (epsilon, mu).





#### **Superfish problem 1. Pillbox cavity.**

#### Design  $TM_{010}$  cavity for frequency 201.25 MHz

- Estimate radius *R*, choose length *L* (default units cm); define BCs or use default BCs (SF: left – symmetry: Dirichlet BC).
- Create cavity geometry file, e.g., pb.am
- run Automesh on pb.am > pb.T35 with geo and mesh
- run Fish on pb.T35 > pb.T35 with fields
- double-click pb.T35 to see field lines
- run SFO post-processing of pb.T35 > pb.sfo

For TM<sub>nmp</sub> modes in a cylindrical cavity of radius  $R$  and length  $L$ , the frequency

$$
f_{nmp}=\frac{c}{2\pi}\sqrt{\left(\frac{j_{nm}}{R}\right)^2+\left(\frac{\pi p}{L}\right)^2},
$$

where  $j_{\text{nm}}$  are the roots of  $J_n(j_{nm}) = 0$ . The value of  $j_{01}$  = 2.4048.



#### **SF problems 1a & 1b. Pillbox cavity with beam pipe.**

SF 1a: Design  $TM_{010}$  cavity for frequency 201.25 MHz with beam pipe.

- Add beam pipe to the pillbox cavity you already designed. Use pipe radius *a << R*, choose pipe length *p* > 2*a*.
- Will the cavity frequency increase or decrease when you add the pipe?

SF 1b:  $TM_{010}$  cavity with rounded edge of cavity-pipe connection: blend the sharp edge by introducing an arc:

Use \$po nt=2, x0=11.0, y0=3.5, r=1, theta=270 \$ to make an arc.

Slater perturbation theorem relates the cavity frequency change with energy changes due to small deformations of cavity walls:

$$
\frac{\Delta f}{f_0} = \frac{\Delta W_m - \Delta W_e}{2W_0}.
$$

Sometimes it is useful to use *L-C* circuit analogy for the cavity frequency:

$$
f = \frac{1}{2\pi\sqrt{LC}}.
$$



#### **SF problem 2. Pillbox cavity with drift tube**

Design  $TM_{010}$  cavity for frequency 201.25 MHz with a drift tube.

- Recommended *g*/*L*=0.3, DT outer radius 10 cm. How large is the frequency shift from 201.25 MHz when DT is inserted?
- Adjust cavity radius to get back to 201.25 MHz.





#### **DTL design using DTLfish**

Tuning code DTLfish can design and tune a sequence of cells with some required parameters, e.g. frequency, in a given velocity range, e.g.  $β = 0.1$ -0.3.



**ENDFILE** 

**Contract Contract** 



2

3

#### **SF problem 3. DTL design using DTLfish.**

Design DTL cells for frequency 201.25 MHz for  $β = 0.135$ .

- Recommended g/L=0.3, DT outer radius 10 cm. Note: \*.dtl
- DTLfish can tune the cavity parameters, e.g. cavity radius or gap, to get the required frequency, 201.25 MHz.



